



Benjamin R. Edwards Indiana University

# Finsler Geometry and Lorentz-Violating Field Theories

IUCSS

## Overview

Open questions

#### Associated Finsler spaces

Constructing point-particle lagrangians

Scalar field theory

Introduction to Lorentz violation and the SME Introduction to Lorentz violation and the SME

- What is Lorentz symmetry? What is Lorentz violation?
- How do we test Lorentz symmetry?
- Point-particle lagrangians from field theory
- Connection to Finsler geometry



Michelson, Morley 1887

# Lorentz symmetry







Coordinate transformation Particle transformation



Coordinate transformation

Particle transformation

#### Lorentz violation



 $U = -\mu \cdot \mathbf{B}$ 

 $U' = -\mu \cdot \mathbf{B}$ 

### Lorentz violation



#### Lorentz violation



 $U = -\mu \cdot \mathbf{B} \qquad \qquad > \qquad \qquad U' = -\mu \cdot \mathbf{B}$ 



Meanwhile in the lab...

$$\mathcal{L}_{SME} \supset \frac{1}{2} i \bar{\psi} \gamma^{\mu} \overleftrightarrow{\partial_{\mu}} \psi - m \bar{\psi} \psi - \mathbf{a}_{\mu} \bar{\psi} \gamma^{\mu} \psi - \mathbf{b}_{\mu} \bar{\psi} \gamma_{5} \gamma^{\mu} \psi$$

- Coefficients for Lorentz violation act like background fields
- $\mathcal{L}_{SME}$  constructed from known fields
- Has implications for experiments at currently attainable energy levels

# The Standard-Model Extension

Colladay, Kostelecký PRD 1997, 1998, Kostelecký PRD 2004

## Effective field theory



### From field theories to point particles



Why study point-particle lagrangians? Little is known of kinematics in Lorentz-violating backgrounds

Many experiments involve signals from macroscopic bodies

Exact momentum-velocity relationship unknown

# Connection to Finsler geometry

# Lagrangians and Finsler norms



Goldstien <u>Classical Mechanics</u> 1950, Bao, Chern, Shen <u>An Introduction to Riemann-Finsler Geometry</u> 2000

# Finsler geometry



Constructed by adding background field couplings



Constructed by adding covector field couplings

# Finsler geometry



Lorentz-Finsler Spacetime

Pseudo-Riemann Spacetime Finsler Geometry

Riemann Geometry



SME

General

Relativity

Lorentz-Finsler Spacetime

Pseudo-Riemann Spacetime Finsler Geometry

Riemann Geometry

precise definition still open Beem Canad. J. Math. 1970, Asanov <u>Finsler Geometry, Relativity, and Gauge Theories</u> 1985 Miron, Anastasiei <u>The theory of Lagrange Spaces: Theory and Applications</u> 1994



precise definition still open

Benjacu, Farran <u>Geometry of Pseudo-Finsler Submanifolds</u> 2000, Pfeifer, Wohlfarth PRD 2011, Kostelecký PLB 2011, Lämmerzahl, Perlick, Hasse PRD 2012, Javaloyes, Sánchez arXiv: 1805.06978

Why study point-particle lagrangians? Little is known of kinematics in Lorentz-violating backgrounds

Many experiments involve signals from macroscopic bodies

Exact momentum-velocity relationship unknown

Why study point-particle lagrangians? Provide us with more physical examples of possible Lorentz-Finsler spacetimes

Little is known of kinematics in Lorentz-violating backgrounds

Many experiments involve signals from macroscopic bodies

Exact momentum-velocity relationship unknown

# Finsler geometry

SME

General Relativity Lorentz-Finsler Spacetime

Pseudo-Riemann Spacetime Finsler Geometry

Riemann Geometry

# Finsler geometry



Spontaneous vs. explicit symmetry breaking

- Spontaneous
  - underlying theory has Lorentz symmetry
  - dynamic fields acquire backgrounds

#### • Explicit

- nondynamic background
- in GR this has implications for geometry

Kostelecký, Samuel PRD 1989, Kostelecký PRD 2004

# Explicit breaking and gravity

• Einstein tensor and Bianchi identity

 $D_{\mu}G^{\mu\nu}=0$ 

- Einstein equation
  - $G^{\mu\nu} = \kappa T^{\mu\nu}$
- Together these imply

 $D_{\mu}T^{\mu\nu}=0$ 

# Explicit breaking and gravity

• Equations of motion in the presence of background fields imply

$$D_{\mu}T^{\mu\nu} = J_{x}D^{\nu}k^{x}$$

• To be consistent, right hand side must vanish!

- Need extra degrees of freedom to reconcile these requirements
  - these may come from the direction dependence in Finsler geometry!

Kostelecký PRD 2004

# Finsler geometry

Geodesics are controlled by a metric with extra degrees of freedom



Conjecture: SME background fields may give rise to these modifications

Finsler (thesis) 1918, Kostelecký PRD 2004

## Overview

Open questions

#### Associated Finsler spaces

Constructing point-particle lagrangians

Scalar field theory

Introduction to Lorentz violation and the SME

#### Scalar field theory

## Why scalars?

The most general Lorentzviolating scalar field theory has not been studied

All particles in nature exhibit a property called spin

• scalar, spinor, vector,...

A quantum scalar field theory describes spin 0 particles

## Why scalars?

In certain cases, spin can complicate the trajectory

A large subset of Lorentzviolating effects are spin independent

Free particles can be handled as if they have 0 spin in this case

General scalar field theory  

$$\mathcal{L}(\phi, \phi^{\dagger}) = \partial^{\mu} \phi^{\dagger} \partial_{\mu} \phi - m^{2} \phi^{\dagger} \phi + \partial_{\mu} \phi^{\dagger}(\widehat{k}_{c})^{\mu\nu} \partial_{\nu} \phi - \frac{1}{2} [i \phi^{\dagger}(\widehat{k}_{a})^{\mu} \partial_{\mu} \phi + \text{h.c.}]$$
even number of derivatives  

$$(\widehat{k}_{c})^{\mu\nu} = \sum_{d=n} (i)^{d-n} (k_{c}^{(d)})^{\mu\nu\alpha_{1}\alpha_{2}\cdots\alpha_{d-n}} \partial_{\alpha_{1}} \partial_{\alpha_{2}} \cdots \partial_{\alpha_{d-n}}$$
odd number of derivatives  

$$(\widehat{k}_{a})^{\mu} = \sum_{d=n-1} (i)^{d-n+1} (k_{a}^{(d)})^{\mu\alpha_{1}\alpha_{2}\cdots\alpha_{d-n+1}} \partial_{\alpha_{1}} \partial_{\alpha_{2}} \cdots \partial_{\alpha_{d-n+1}}$$
*n*: number of spacetime dimension

*k*'s have constant cartesian components

าร

d: mass dimension of the operator

Edwards, Kostelecký PLB 2018
# Existing work in scalar field theory

#### Much work done in minimal sector

Borges, Ferrari, Farone arXiv:1809.08883 Xiao PRD 2018 de Paula Netto PRD 2018 Silva, Carvalho IJGMMP 2018 Scarpelli, Brito, Felipe, Nascimento, Petrov EPJC 2017 Cruz, Bezerra de Mello, Petrov PRD 2017, MPLA 2018 Kamand, Altschul, Schindler PRD 2017 Casana, da Silva MPLA 2015 Carvalho PLB 2013, PLB 2014 Altschul PRD 2013 Ferrero, Altschul PRD 2011 Bazeia, Barreto, Menezes PRD 2006 Altschul, PLB 2006 Anderson, Sher, Turan PRD 2004 Berger, Kostelecký PRD 2002 Colladay, Kostelecký PRD 1997, 1998

# Existing work in scalar field theory

• Previous work all n = 4, d = 3, 4

• Recent work on n = 4, d = 6

• No results for  $n \neq 4$ 

• Nonminimal sector largely ignored

Nascimento, Petrov, Reyes EPJC 2018

# General scalar field theory

 $\mathcal{L}(\phi,\phi^{\dagger}) = \partial^{\mu}\phi^{\dagger}\partial_{\mu}\phi - m^{2}\phi^{\dagger}\phi + \partial_{\mu}\phi^{\dagger}(\widehat{k}_{c})^{\mu\nu}\partial_{\nu}\phi - \frac{1}{2}[i\phi^{\dagger}(\widehat{k}_{a})^{\mu}\partial_{\mu}\phi + \text{h.c.}]$ 

- d = n absorbed into metric, d = n 1 is a local phase
  - only *d* > *n* can be observed for single scalar field!
- Coefficients can be taken to be traceless, symmetric
- In 4 dimensions,  $k_c$  is CPT even,  $k_a$  is CPT odd
  - hermitian fields cannot violate CPT!

### **Equations of motion**

$$(\partial^{\mu}\partial_{\mu} + m^2 + i(\widehat{k}_a)^{\mu}\partial_{\mu} + (\widehat{k}_c)^{\mu\nu}\partial_{\mu}\partial_{\nu})\phi = 0$$

lead to a dispersion relation

$$p^{2} - m^{2} - (\hat{k}_{a})^{\mu} p_{\mu} + (\hat{k}_{c})^{\mu\nu} p_{\mu} p_{\nu} = 0$$

where extra terms affect propagation

# Overview

Open questions

#### Associated Finsler spaces

Constructing point-particle lagrangians

Scalar field theory

Introduction to Lorentz violation and the SME

### **Equations of motion**

$$(\partial^{\mu}\partial_{\mu} + m^2 + i(\widehat{k}_a)^{\mu}\partial_{\mu} + (\widehat{k}_c)^{\mu\nu}\partial_{\mu}\partial_{\nu})\phi = 0$$

lead to a dispersion relation

$$p^{2} - m^{2} - (\hat{k}_{a})^{\mu} p_{\mu} + (\hat{k}_{c})^{\mu\nu} p_{\mu} p_{\nu} = 0$$

where extra terms affect propagation

### Two ways to view dispersion relations

**Field theory** 

$$p^{2} - m^{2} - (\widehat{k}_{a})^{\mu} p_{\mu} + (\widehat{k}_{c})^{\mu\nu} p_{\mu} p_{\nu} = 0$$

Wave vectors constrained to a hypersurface

#### **Point particles**

Momentum constrained to a hypersurface



Can we build a point-particle lagrangian that generates this dispersion?

• Start with a dispersion relation

R(p)=0

• Enforce wave-packet group velocity = classical velocity



• Action invariant under reparameterization:  $L(\lambda u) = \lambda L(u)$ 

$$\Rightarrow L = -u^{\mu}p_{\mu}$$

Kostelecký, Russell PLB 2010

- *n* equations can eliminate *n* momentum components
- In principle,  $L = -u^{\mu}p_{\mu}$  becomes L = L(u)
- In practice, only known exactly for:
  - quadratic dispersions
  - quartic dispersions
- Calculations are difficult in general

- Formalism applied to
  - *face*, *ab*, *H* limits of SME
  - exact lagrangians found for minimal coefficients
- Ansatz method used in fermion sector of SME
  - results are for nonminimal coefficients to first order

• New method generates all orders for minimal and nonminimal terms

Kostelecký, Russell PLB 2010, Reis, Schreck PRD 2018, Edwards, Kostelecký PLB 2018

Can find exact lagrangian for d = n

$$p_{\mu}\Omega^{\mu\nu}p_{\nu} = m^{2} \qquad \Omega = \eta + k^{(n)}$$

$$(u^{0}\Omega^{j\nu} - u^{j}\Omega^{0\nu})p_{\nu} = 0$$

$$u^{\mu} = -\frac{L^{(n)}}{m^{2}}\Omega^{\mu\nu}p_{\nu}$$

Can find exact lagrangian for d = n



Kostelecký, Russell PLB 2010, Edwards, Kostelecký PLB 2018

- For d > n, extra p dependence makes obtaining exact solution difficult
- Following previous steps produces a power series for *L* after expansion

$$L^{(d)}(u, p, \boldsymbol{k}^{(d)}) = \frac{1}{4}(d - n + 2)u_{\alpha_1}p_{\alpha_2}\cdots p_{\alpha_{d-n+2}}(\boldsymbol{k}^{(d)})^{\alpha_1\cdots\alpha_{d-n+2}} + m\bar{u}\sum_{s=0}^{j}\sum_{j}[(-1)^{j}a_{js}((d - n + 2)u_{\alpha_1}p_{\alpha_2}\cdots p_{\alpha_{d-n+2}}(\boldsymbol{k}^{(d)})^{\alpha_1\cdots\alpha_{d-n+2}})^{2s} ((d - n)p_{\alpha_1}\cdots p_{\alpha_{d-n+2}}(\boldsymbol{k}^{(d)})^{\alpha_1\cdots\alpha_{d-n+2}})^{j-s}] 
$$a_{js} = \frac{(2j)!}{m^{2j}u^{2s}(2j - 1)8^{j+s}j!s!(j - s)!}$$$$

Extended method applied to scalars  

$$L^{(d)}(u, p, k^{(d)}) = \frac{1}{4}(d - n + 2)u_{\alpha_1}p_{\alpha_2} \cdots p_{\alpha_{d-n+2}}(k^{(d)})^{\alpha_1 \cdots \alpha_{d-n+2}} + m\bar{u}\sum_{s=0}^{j}\sum_{j}[(-1)^{j}a_{js}((d - n + 2)u_{\alpha_1}p_{\alpha_2} \cdots p_{\alpha_{d-n+2}}(k^{(d)})^{\alpha_1 \cdots \alpha_{d-n+2}})^{2s} \\ ((d - n)p_{\alpha_1} \cdots p_{\alpha_{d-n+2}}(k^{(d)})^{\alpha_1 \cdots \alpha_{d-n+2}})^{j-s}]$$

$$(d - n)p_{\alpha_1} \cdots p_{\alpha_{d-n+2}}(k^{(d)})^{\alpha_1 \cdots \alpha_{d-n+2}})^{j-s}]$$
Define zeroth order  

$$L_0^{(d)} \equiv L^{(d)}(u, p, 0) = -m\bar{u} \qquad \bar{u} = \sqrt{u^{\mu}\eta_{\mu\nu}u^{\nu}}$$

$$L_0^{(d)} \equiv L^{(d)}(u, p, 0) = -m\bar{u}$$



$$(p_0^{(d)})_{\mu} = -\frac{\partial L_0^{(d)}}{\partial u^{\mu}} = m\hat{u}_{\mu} \underbrace{L^{(d)}(u, p, \boldsymbol{k}^{(d)})}_{L^{(d)}(u, p, \boldsymbol{k}^{(d)})}$$
Reinsert to get next-order  $L$ 

$$L_1^{(d)} = L^{(d)}(u, p_0, \boldsymbol{k}^{(d)}) = -m\bar{u} \left[ 1 - \frac{1}{2}m^{d-n}(\hat{u}^{\alpha_1} \cdots \hat{u}^{\alpha_{d-n+2}}(\boldsymbol{k}^{(d)})_{\alpha_1 \cdots \alpha_{d-n+2}}) \right]$$

L

# **Iterative process**



$$L_{3}^{(d)} = L_{0}^{(d)} \left[ 1 - \frac{1}{2} \widetilde{k}^{(d)} - \frac{1}{8} (d - n + 1)^{2} (\widetilde{k}^{(d)})^{2} + \frac{1}{8} (d - n + 2)^{2} \widetilde{k}^{(d)}{}_{\alpha} \widetilde{k}^{(d)}{}_{\alpha} - \frac{1}{16} (d - n + 1)^{4} (\widetilde{k}^{(d)})^{3} + \frac{1}{16} (d - n + 1) (2d - 2n + 1) \widetilde{k}^{(d)} \widetilde{k}^{(d)}{}_{\alpha} \widetilde{k}^{(d)}{}_{\alpha} - \frac{1}{16} (d - n + 1) (d - n + 2)^{2} \widetilde{k}^{(d)}{}_{\alpha} \widetilde{k}^{(d)}{}_{\alpha} \widetilde{k}^{(d)}{}_{\beta} \right]$$

$$\tilde{k}^{(d)}{}_{\alpha_1\cdots\alpha_s} = (k^{(d)})_{\alpha_1\cdots\alpha_s\alpha_{s+1}\cdots\alpha_{d-n+2}} \hat{u}^{\alpha_{s+1}}\cdots\hat{u}^{\alpha_{d-n+2}}$$

Matches previous results derived from fermion limit of SME

Reis, Schreck PRD 2018, Edwards, Kostelecký PLB 2018

# Overview

Open questions

#### Associated Finsler spaces

Constructing point-particle lagrangians

Scalar field theory

Introduction to Lorentz violation and the SME

### Associated Finsler spaces

# Finsler geometry

SME

General Relativity Lorentz-Finsler Spacetime

> Pseudo-Riemann Spacetime

Finsler Geometry

Riemann Geometry

# Finsler geometry

![](_page_57_Figure_1.jpeg)

# Lagrangians and Finsler norms

![](_page_58_Picture_1.jpeg)

- L(x, u) smooth on  $TM \setminus S$
- L is 1-homogeneous in u
  - Effective metric

 $g_{\mu\nu} = \frac{1}{2} \frac{\partial^2 L^2}{\partial u^{\mu} \partial u^{\nu}}$ 

$$F: TM \to [0,\infty)$$

• F(x, y) smooth on  $TM \setminus \{0\}$ 

• F is 1-homogeneous in y

• Finsler metric (positive definite!)

$$g_{ij} = \frac{1}{2} \frac{\partial^2 F^2}{\partial y^i \partial y^j}$$

# Analytic continuation

$$ds^{2} = dt^{2} - dx^{2}$$

$$g_{\mu\nu} = diag(1, -1)$$

$$t \to t'$$

$$x \to ix'$$

$$ds^{2} = d(t')^{2} - d(ix')^{2} = d(t')^{2} + d(x')^{2}$$

$$g'_{\mu\nu} = diag(1, 1)$$

Kostelecký PLB 2011

### **SME-based** Finsler norms

$$L_{ab} \to F_{ab} = \sqrt{y^2} + \mathbf{a} \cdot y \pm \sqrt{b^2 y^2 - (b \cdot y)^2}$$

• Randers space

$$F_{ab}|_{b\to 0} = \sqrt{y^2} + a \cdot y = \sqrt{y^2} \pm ||a||y_{||}$$

• **b** space

$$F_{ab}|_{a\to 0} = \sqrt{y^2} \pm \sqrt{b^2 y^2 - (b \cdot y)^2} = \sqrt{y^2} \pm ||b|| y_{\perp}$$

![](_page_60_Picture_6.jpeg)

Randers 1941, Kostelecký PLB 2011

# SME-based Finsler norms

- Large class of bipartite norms studied
  - includes **b** space and Randers space
  - includes spaces generated from H coefficients
- *n*-dimensional spaces considered
- Spaces categorized by isomorphism

Kostelecký, Russell, Tso PLB 2012

$$p_{\mu}(u) \to (-i)^{n} p_{j}(y)$$
$$(k^{(d)})^{\alpha_{1}\cdots} \to i^{n} (k^{(d)})^{j_{1}\cdots}$$
$$L \to -F = -y \cdot p$$
$$u^{\mu} \to i^{n} y^{j}$$

# Map to Finsler space

• ensures nonnegative Finsler norm

• takes  $\eta \rightarrow \delta$ 

• allows positive-definite metric

![](_page_63_Figure_0.jpeg)

![](_page_64_Figure_0.jpeg)

# Finsler *k* spaces

- Finsler norm is reversible if F(y) = F(-y)
  - Reversible iff  $k_a = 0$

 Reversibility of *F* ⇒ CPT invariance in the corresponding effective field theory for *n* = 4

#### $F_1^{(d_1d_2)} = \bar{y}(1 - \frac{1}{2}\tilde{k}^{(d_1)} - \frac{1}{2}\tilde{k}^{(d_2)})$

 $F_1^{(d)} = \bar{y}(1 - \frac{1}{2}\tilde{k}^{(d)})$ 

 $L_3^{(d)} \to F_3^{(d)}$ 

# Finsler *k* spaces

- Generalizes Randers
  - generalized  $(\alpha, \beta)$  metric
- Infinite set of Finsler spaces:  $F_l^{(D)}$  for some subset *D* and order *l*
- Includes every perturbation of Riemann geometry that corresponds to spin-independent Lorentz violation

# Finsler *k* spaces

• The Hilbert form  $\omega = F_{y^i} dx^i$  is the Riemann-Finsler analogue of the *n*-momentum per mass

$$p_i = [1 + \frac{1}{2}(d - n + 1)\widetilde{\mathbf{k}}]\hat{y}_i - \frac{1}{2}(d - n + 2)\widetilde{\mathbf{k}}_i$$
$$\hat{y}^j = \frac{y^j}{\sqrt{y^k r_{km} y^m}}$$

- Rescaled in a direction-dependent way
- Momentum and velocity are generally not aligned

# Finsler *k* spaces

$$g_{jk}^{(d)} = r_{jk} + \frac{1}{2} \left[ (d-n)\widetilde{k}^{(d)}(r_{jk} - (d-n+2)\hat{y}_j\hat{y}_k) + (d-n+2)(d-n)(\widetilde{k}^{(d)}_j\hat{y}_k + \widetilde{k}^{(d)}_k\hat{y}_j) - (d-n+1)(d-n+2)\widetilde{k}^{(d)}_{jk} \right]$$

- First-order Finsler metric
- Sufficient condition for positive-definite g places constraint on k
- Reduces to the Riemann metric for d = n and d = n 2
- Randers metric for d = n 1

Cartan torsion vanishes

![](_page_68_Picture_2.jpeg)

#### Riemann metric

Matsumoto torsion vanishes

![](_page_68_Picture_5.jpeg)

Randers metric

Deicke 1953, Matsumoto 1974

1

Cartan torsion vanishes for d = n, d = n - 2, also for n = 1

$$\begin{split} C_{jkl} &= \frac{1}{4\bar{y}} (d-n)(d-n+2) \sum_{(jkl)} r_{jk} \widetilde{k}_{l}^{(d)} - \frac{1}{3} (d-n+1) \widetilde{k}^{(d)}{}_{jkl} \\ &- \widetilde{k}^{(d)} r_{jk} \hat{y}_{l} + (d-n+1) \widetilde{k}^{(d)}{}_{jk} \hat{y}_{l} + \frac{1}{3} (d-n+4) \widetilde{k}^{(d)} \hat{y}_{j} \hat{y}_{k} \hat{y}_{l} - (d-n+2) \widetilde{k}^{(d)}{}_{j} \hat{y}_{k} \hat{y}_{l} \\ &\text{Matsumoto torsion vanishes for } d = n-1 \end{split}$$

$$M_{jkl} = \frac{(d-n)(d-n+1)(d-n+2)}{4(n+1)\bar{y}} \sum_{(jkl)} \left[ r_{jk} (\tilde{k}^{(d)} \hat{y}_l - \tilde{k}^{(d)}{}_l) + (n+1)\tilde{k}^{(d)}{}_{jk} \hat{y}_l - \frac{1}{3}(n+1)\tilde{k}^{(d)}{}_{jkl} + \frac{1}{3}(n-2)\tilde{k}^{(d)} \hat{y}_j \hat{y}_k \hat{y}_l - n\tilde{k}^{(d)}{}_j \hat{y}_k \hat{y}_l - (r_{jk} - \hat{y}_j \hat{y}_k) (\tilde{k}^{(d)m}{}_m \hat{y}_l - \tilde{k}^{(d)m}{}_m n) \right]$$

$$F\frac{d}{d\lambda}\left(\frac{y^{j}}{F}\right) + G^{j} = 0 \qquad \qquad G^{j} = \frac{1}{2}y^{m}y^{l}g^{jk}(\partial_{m}g_{kl} + \partial_{l}g_{km} - \partial_{k}g_{ml})$$

![](_page_70_Figure_2.jpeg)

Covariant derivatives with respect to  $r_{ik}$ 

• Finsler manifolds have different covariant (coordinate) bases

![](_page_71_Figure_2.jpeg)

• Connection forms (and the related curvatures) also modified  $\Gamma^{j}{}_{ml} = \tilde{\gamma}^{j}{}_{ml} + \frac{1}{4}r^{js} \left[ (d-n)(r_{sl} - (d-n+2)\hat{y}_{s}\hat{y}_{l}) \widetilde{D}_{m} \widetilde{k}^{(d)} + (d-n+2)(d-n)(\hat{y}_{s} \widetilde{D}_{m} \widetilde{k}^{(d)}{}_{l} + (s \leftrightarrow l)) - (d-n+2)(d-n+1)\widetilde{D}_{m} \widetilde{k}^{(d)}{}_{sl} + (m \leftrightarrow l) - (m \leftrightarrow s) \right]$ 

Bao, Chern, Shen An Introduction to Riemann-Finsler Geometry 2000, Edwards, Kostelecký PLB 2018
## Characterizing the geometry

• Compatibility of Riemann geometry and explicit Lorentz violation

$$\widetilde{D}_j \boldsymbol{k^{(d)}}_{a_1 \cdots a_{d-2}} = 0$$

• Most quantities reduce to Riemann form for *r*-parallel backgrounds

$$\frac{1}{\bar{y}^2} G^{(d)j} \to \tilde{\gamma}^j \bullet \bullet \qquad \Gamma^j{}_{ml} \to \tilde{\gamma}^j{}_{ml}$$

• Geodesics are unaffected, space is Berwald

Edwards, Kostelecký PLB 2018

## Overview

Open questions

#### Associated Finsler spaces

Constructing point-particle lagrangians

Scalar field theory

Introduction to Lorentz violation and the SME





• Can other exact lagrangians be found? What are the associated Finsler spaces?



#### Classical

Curved

**555** 

- How to define Lorentz-Finsler spacetimes?
- What is the geometry of curved spacetime in theories with explicit Lorentz violation?

## Future interest



Conjectures supported but remain unproved

- Berwald  $\Leftrightarrow$  *r*-parallel
- *r*-parallel  $\Rightarrow$  usual geodesics



*r*-parallel backgrounds seem to be undetectable via geodesic motion



Can *r*-parallel components be removed from the field theory?

Kostelecký PLB 2011

## **Future interest**

# Dispersion relations

provide a connection between field theories and point particles







## Future interest: classical applications

- Classical applications of *k*-space?
  - Shen's fishpond (Randers)
  - Bead on a wire, magnetized chain (*b* space)

Shen Canad. J. Math. 2003, Foster, Lehnert PLB 2015

## **Future interest**





- The general Lorentz-violating scalar field theory
- Extended method to construct point-particle lagrangians
  - any order, any mass dimension
- Associated Finsler spaces obtained
  - all perturbations of Riemann spaces describing spin-independent effects
- Many interesting open questions for future investigation