# Complete Flat Surfaces with two Isolated Singularities in $\mathbb{H}^{3}$. 

Francisco Milán López

Joint work with Armando V. Corro and Antonio Martínez

## Classical Results

## Theorem (Volkov-Vladimirova (1971), Sasaki (1973))

The only complete examples of flat surfaces in $\mathbb{H}^{3}$ (without singularities) are horospheres and hyperbolic cilinders.

Horosphere


Hyperbolic Cylinder


## Classical Results

## Up to now

The only known examples of complete flat surfaces in $\mathbb{H}^{3}$ with isolated singularities are rotational ones.


Rotational flat surface


## Problem

Existence and characterization of new examples of complete flat surfaces in $\mathbb{H}^{3}$ with isolated singularities.

## Solution with two isolated singularities and one end



- Singularities in a vertical line.
- Coordinates strongly related.


## Main Schedule

(1) Recent Tools from Weierstrass representation
(2) Flat surfaces with n isolated singularities
(3) Rotational examples $(\mathrm{n}=1)$
(4) Solved Problem $(\mathrm{n}=2)$
(5) Unsolved Problem $(n>2)$
(6) Canonical examples $(\mathrm{n}=2)$
(7) Characterizations

## Recent Tools

- From Bryant's representation for surfaces of mean curvature one in $\mathbb{H}^{3}$ and our results about improper affine spheres, (Ferrer, Martínez, M, 1996):

Flat surfaces in $\mathbb{H}^{3}$ admit a Weierstrass representation in terms of meromorphic data, (Gálvez, Martínez, M, 2000).

- Study of ends and singularities.


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- Generic behaviour and existence of complete examples with curves of singularities, (Kokubu, Rossman, Saji, Umehara, Yamada, Roitman)


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## Weierstrass representation

We consider the upper half-space model of $\mathbb{H}^{3}$, that is,

$$
\mathbb{R}_{+}^{3}=\left\{\left(x_{1}, x_{2}, x_{3}\right) \in \mathbb{R}^{3}: x_{3}>0\right\}
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## endowed with the metric

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$$
\mathbb{C}_{\infty}=\left\{\left(x_{1}, x_{2}, 0\right): x_{1}, x_{2} \in \mathbb{R}\right\} \cup\{\infty\} \equiv \mathbb{S}^{2}
$$

## Weierstrass representation

Let $\Sigma$ be a $2-$ manifold and

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\psi: \Sigma \longrightarrow \mathbb{H}^{3}
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be a flat immersion. Then, the second fundamental form $d \sigma^{2}$ is definite. In fact, if the induced metric is given by

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If we consider the Riemann surface $\left(\Sigma, d \sigma^{2}\right)$, then the hyperbolic Gauss maps $g, g_{*}: \Sigma \longrightarrow \mathbb{C}_{\infty} \equiv \mathbb{S}^{2}$ are holomorphic.

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## Weierstrass representation

- With these holomorphic data we obtained a conformal representation and different results for flat surfaces in $\mathbb{H}^{3}$ :
- Description of classical examples.
- A complete end is conformal to a disk minus a point $z_{0}$. - $g$ extends to $z_{0}$ iff the associated ODE has a regular singularity - A regular end is embedded iff $z_{0}$ is not a branch point of $g$


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- Kokubu, Umehara and Yamada extended our representation to flat fronts, that is, flat surfaces with admissible singularities, $\left(\left(g, g_{*}\right): \Sigma \longrightarrow \mathbb{S}^{2} \times \mathbb{S}^{2}\right.$ is an immersion $)$, (2004) curves of singularities and studied their properties, (2005)


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Let $g$ and $g_{*}$ be non-constant meromorphic functions on a Riemann surface $\Sigma$, such that $g(p) \neq g_{*}(p)$ for all $p \in \Sigma$,
(1) all the poles of the 1 -form $\frac{d g}{g-g_{*}}$ are of order 1 ,
(2) $\operatorname{Re} \int_{\gamma} \frac{d g}{g-g_{*}}=0$, for each loop $\gamma$ on $\Sigma$ and
(3) $g$ and $g_{*}$ have no common branch points.

If $\xi:=c \exp \int \frac{d g}{g-g_{*}}$, with $c \in \mathbb{C} \backslash\{0\}$.
Then, the map $\psi=\left(\psi_{1}, \psi_{2}, \psi_{3}\right): \Sigma \longrightarrow \mathbb{H}^{3}$ given by
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\psi_{1}+\mathrm{i} \psi_{2}=g-\frac{|\xi|^{4}\left(g-g_{*}\right)}{|\xi|^{4}+\left|g-g_{*}\right|^{2}}, \quad \psi_{3}=\frac{|\xi|^{2}\left|g-g_{*}\right|^{2}}{|\xi|^{4}+\left|g-g_{*}\right|^{2}}
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From this theorem, one has:

- A harmonic function $u: \Sigma \backslash \mathcal{P}_{g} \longrightarrow \mathbb{R}$, given by

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u:=\operatorname{Re} \int \frac{d g}{g-g_{*}},
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where $\mathcal{P}_{g}$ is the set of poles of $g$. (In our examples $\mathcal{P}_{g}=\emptyset$ ).

- A holomorphic function $F:=\frac{1}{g-g_{*}}$ on $\Sigma$, determined by

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## Theorem (Corro, Martínez, M (2010))

Let $g$ be a non-constant meromorphic function on a Riemann surface $\Sigma$ and $u$ be a harmonic function as above.

$$
d s^{2}=\exp (-4 u)\left|\exp (4 u)\left(d F+F^{2} d g\right)-\overline{d g}\right|^{2}
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is a Riemannian metric, then the map $\psi=\left(\psi_{1}, \psi_{2}, \psi_{3}\right): \Sigma \longrightarrow \mathbb{H}^{3}$
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## Weierstrass representation

## Remark (Corro (2006))

The hyperbolic Gauss map $g$ defines a horospheres congruence and $\exp (2 u) / 2$ is the radius function of each tangent horosphere to $\psi(\Sigma)$.


## Flat surfaces with isolated singularities

## Definition

Let $\Sigma$ be a differentiable surface without boundary, $\psi: \Sigma \rightarrow \mathbb{H}^{3}$ a continuous map and $\mathcal{F}=\left\{p_{1}, \cdots, p_{n}\right\} \subset \Sigma$ a finite set. We say that $\psi$ is a complete flat immersion with isolated singularities $\psi\left(p_{1}\right), \cdots, \psi\left(p_{n}\right)$, if $\psi$ is a flat immersion in $\Sigma \backslash \mathcal{F}$, but $\psi$ is not $C^{1}$ at the points $p_{1}, \cdots, p_{n}$, and every divergent curve in $\Sigma$ has infinite length for the induced (singular) metric.

- Around an (embedded) isolated singularity we have the conformal structure of an annulus (and a convex graph) (Gálvez and Mira (2005)).
- $d s^{2} \leq 2 \exp (-4 u)|d g|^{2}$ and from the classical result of Huber:


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Let $\psi: \Sigma \rightarrow \mathbb{H}^{3}$ be a complete flat immersion with isolated singularities $\psi\left(p_{1}\right), \cdots, \psi\left(p_{n}\right)$.
Then there is a compact Riemannian surface $\bar{\Sigma}, n$ disjoint discs $\mathcal{D}_{1}, \cdots, \mathcal{D}_{n} \subset \bar{\Sigma}$ and points $q_{1}, \cdots, q_{m} \in \bar{\Sigma} \backslash\left\{\mathcal{D}_{1} \cup \cdots \cup \mathcal{D}_{n}\right\}$ such that
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\bar{\Sigma} \backslash\left\{\mathcal{D}_{1} \cup \cdots \cup \mathcal{D}_{n} \cup\left\{q_{1}, \cdots, q_{m}\right\}\right\}
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The points $q_{1}, \cdots, q_{m}$ are called the ends of $\psi$.

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Each embedded complete end of a flat surface in $\mathbb{H}^{3}$ is
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## Notes of the Proof

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If $\psi: \Sigma \rightarrow \mathbb{H}^{3}$ is a complete flat embedding with a finite number of isolated singularities, then $\psi$ is globally convex.

Corollary
Every complete flat embedding $\psi: \Sigma \rightarrow \mathbb{H}^{3}$ with a finite number of isolated singularities and only one end is a graph over a finitely punctured horosphere and

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$$
\Sigma \backslash\left\{p_{1}, \cdots, p_{n}\right\} \cong \mathbb{S}^{2} \backslash\left\{\mathcal{D}_{1} \cup \cdots \cup \mathcal{D}_{n} \cup\{q\}\right\} .
$$

## Flat surfaces with isolated singularities

## Consequence

The existence of complete flat embedding in $\mathbb{H}^{3}$ with $n$ isolated singularities and only one end is equivalent to the existence of the appropriate data $\left(g, g_{*}\right)$ or $(g, u)$ on $\mathbb{C} \backslash\left\{\mathcal{D}_{1} \cup \cdots \cup \mathcal{D}_{n}\right\}$.

## Flat surfaces with isolated singularities

## First approach

As $d s^{2}=0$ on $\partial \mathcal{D}_{j}, j=1, \ldots, n$, one has

$$
\left|\frac{\exp (4 u)\left(d F+F^{2} d g\right)}{d g}\right|=1
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Then, we tried to recover $(g, u)$ from meromorphic functions $\widetilde{f}, \tilde{g}$ on $\mathbb{C} \backslash\left\{\mathcal{D}_{1} \cup \cdots \cup \mathcal{D}_{n}\right\}$ such that $\left|\frac{d \tilde{f}}{d \tilde{g}}\right|=1$ on the boundary. But the way is complicated.

> However, this idea gives directly the data for the regular solution of the Monge-Ampère equation $\phi_{x x} \phi_{y y}-\phi_{x y}^{2}=1$, in the plane minus n points, (Gálvez, Martínez, Mira (2005)).

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## Rotational examples



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$$
g(z)=z, \quad g_{*}(z)=\frac{a+1}{a-1} z,
$$

## Rotational examples

with

$$
z \in \Sigma=\mathbb{D}_{r}^{*}=\{z \in \mathbb{C} / 0<|z|<r\} \cong \mathbb{C} \backslash \mathcal{D}_{1}
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$$
\left.4 r^{2 a}=1-a^{2} \text { and } a \in\right] 0,1[.
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- The singularity is $\psi\left(\mathbb{S}_{r}\right)$, with $\mathbb{S}_{r}=\{z \in \mathbb{C} /|z|=r\}$


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## Solved Problem

We find the data $(g, u)$ from an aproppriate holomorphic function $R: \mathbb{A}_{r}^{*} \longrightarrow \mathbb{C}$, where

$$
\begin{gathered}
\mathbb{A}_{r}^{*}=\mathbb{A}_{r} \backslash\left\{z_{0}\right\} \cong \mathbb{C} \backslash \mathcal{D}_{1} \cup \mathcal{D}_{2} \\
\mathbb{A}_{r}=\{z \in \mathbb{C} / r<|z|<1\}
\end{gathered}
$$

$0<r<1$ and $z_{0} \in \mathbb{A}_{r}$.
In fact, if we want
with $c \in \mathbb{R}^{+} \backslash\{1\}$. Then, from our conformal representation,

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where $R$ is the holomorphic function $F(g-0)$.

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These conditions determine $R$, also $g \sim \sqrt{R / 1-R}$ and $u$ from $F=R / g$. Thus, we are going to construct new examples that we will call canonical examples.

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It is more difficult, because the singularities are not in the same vertical line $\{0\} \times \mathbb{R}^{+}$and one has different undetermined holomorphic functions

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## It satisfies

$\vartheta_{1}(z)=\overline{\vartheta_{1}(\bar{z})}=-r^{2} z \vartheta_{1}\left(r^{2} z\right)=-\frac{1}{z} \vartheta_{1}(1 / z), \quad \vartheta_{1}\left(z / r^{2}\right)=-z \vartheta_{1}(z)$
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Thus, for any $\left.z_{j} \in\right]-1,-r[$, the classical holomorphic bijection $q_{j}: \mathbb{A}_{r} \backslash\left\{z_{j}\right\} \longrightarrow \mathbb{C} \backslash\left(I_{1} \cup I_{r}\right)$ given by

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q_{j}(z)=-\frac{\vartheta_{1}^{\prime}\left(z_{j} / z\right)}{z \vartheta_{1}\left(z_{j} / z\right)}-\frac{z \vartheta_{1}^{\prime}\left(z_{j} z\right)}{\vartheta_{1}\left(z_{j} z\right)},
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maps the circles $\mathbb{S}_{1}$ and $\mathbb{S}_{r}$, onto two real intervals $I_{1}$ and $I_{r}$, respectively.

## Characterization (see Ahlfords)

$q_{j}$ is the unique (up to real additive constants) holomorphic map in
$\mathbb{A}_{r} \backslash\left\{z_{j}\right\}$, which maps each boundary component of $\mathbb{A}_{r}$ onto a real
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## Remark

If one takes $\left.z_{0} \in\right]-1,-r[$, then

$$
\left.q_{0}:\right] z_{0},-r\left[\cup \mathbb{S}_{r} \cup[r, 1] \cup \mathbb{S}_{1} \cup\right]-1, z_{0}[\longrightarrow \mathbb{R}
$$



## Canonical examples

## Definition

Given $\left.z_{0}, z_{1}, z_{2} \in\right]-1,-r\left[\right.$, we define $R: \mathbb{A}_{r} \backslash\left\{z_{0}\right\} \longrightarrow \mathbb{C}$ by

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R(z)=a q_{0}(z)+b
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where $a$ and $b$ are real constants, determined by $R\left(z_{1}\right)=1$, $R\left(z_{2}\right)=0$ and such that $0<R<1$ on $\partial \mathbb{A}_{r}$.

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If $\left.z_{0}, z_{1}, z_{2} \in\right]-1,-r[$ and $m \in \mathbb{R}$ satisfy
(C1) $m+c_{1} z_{1}-z_{1} R^{\prime}\left(z_{1}\right)=-z_{2} R^{\prime}\left(z_{2}\right)$,
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Then the functions $g: \mathbb{A}_{r} \longrightarrow \mathbb{C}$ and $u: \mathbb{A}_{r} \backslash\left\{z_{0}\right\} \longrightarrow \mathbb{R}$ given by

with $Q_{j}(z)=\frac{\vartheta_{1}\left(z_{j} / z\right)}{\vartheta_{1}\left(z_{j} z\right)}, \quad j=1,2$, are the data of a well-defined flat surface $\psi: \mathbb{A}_{r} \backslash\left\{z_{0}\right\} \rightarrow \mathbb{H}^{3}$, with $\psi\left(\mathbb{S}_{1}\right)$ and $\psi\left(\mathbb{S}_{r}\right)$ as isolated singularities

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Then the functions $g: \mathbb{A}_{r} \longrightarrow \mathbb{C}$ and $u: \mathbb{A}_{r} \backslash\left\{z_{0}\right\} \longrightarrow \mathbb{R}$ given by

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g(z)=\sqrt{\frac{R(z)}{1-R(z)} \frac{Q_{1}(z)}{Q_{2}(z)} z^{-2}}, \quad u(z)=\frac{1}{2} \log \left|\frac{Q_{1}(z)}{1-R(z)} z^{m}\right|
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## Canonical examples

Notes of the Proof

- As $z_{j}$ is a simple zero of $Q_{j}, g$ is a holomorphic function and $u(z)-\frac{1}{2} \log \left|z-z_{0}\right|$ is a harmonic function in $\mathbb{A}_{r}$.
- From (C1), (C2) and $d \log Q_{j}(z)=\frac{z_{j}}{z} q_{j}(z) d z$ we get
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d u+\mathrm{i} * d u=\frac{R}{g} d g \Rightarrow F=\frac{R}{g}
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\psi\left(\mathbb{S}_{r}\right)=\left(0,0,\left|z_{1}\right| r^{m+1}\right)
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## Canonical examples

## Existence

For any $r \in] 0,1[$ and $s \in]-1,0[$, there exist

$$
m \in]-3,-2[
$$

and

$$
\left.z_{0}, z_{1}, z_{2} \in\right]-1,-r[,
$$

$z_{2}<z_{0}<z_{1}$, which satisfy the conditions (C1), (C2), (C3), with

$$
s=-z_{2} c_{2}=-z_{2} q_{2}\left(z_{0}\right) .
$$

In particular, for $s=-1 / 2$, there is a solution with $m=-5 / 2$ and $z_{0}^{2}=r=z_{1} z_{2}$.

## Canonical examples

## Notes of the Proof

The conditions can be written as
(C1) $m=2 h\left(r^{-2(m+2)}\right)-1-f_{0}\left(z_{2}\right)$,
(C2) $-2=f_{0}\left(z_{1}\right)-f_{0}\left(z_{2}\right)$,
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with $h(z)=\frac{z \vartheta_{1}^{\prime}(z)}{\vartheta_{1}(z)}, \quad f_{0}(z)=h\left(z / z_{0}\right)+h\left(z z_{0}\right)$.



## Canonical examples

## Theorem

Each canonical example $\psi: \mathbb{A}_{r} \backslash\left\{z_{0}\right\} \longrightarrow \mathbb{H}^{3}$ is a complete flat embedding with two isolated singularities and one end.


## Canonical examples

Notes of the Proof

- The holomorphic function $g$ is one to one on $\partial \mathbb{A}_{r}$, (covering map with $g^{-1}(g(\widetilde{z}))=\{\tilde{z}\}$, for $\left.\tilde{z} \in\{ \pm 1, \pm r\}\right)$, and it is a diffemorphism on $\mathbb{A}_{r}$.
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p(z)=\left(\frac{Q_{1}(z)}{1-R(z)} z^{m}\right)^{2}\left(\frac{F^{\prime}(z)}{g^{\prime}(z)}+F^{2}(z)\right)
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verifies $|p(z)|=1$ on $\partial \mathbb{A}_{r} \Rightarrow|p(z)|<1$ on $\mathbb{A}_{r}$,
$d s^{2}=\exp (-4 u) \overline{d g}-\left.p d g\right|^{2} \geq \exp (-4 u)|d g|^{2}\left(1-|p|^{2}\right)=d \sigma^{2}$
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- Only one embedded end $\psi\left(z_{0}\right)$ and $\psi$ is an embedding.


## Characterizations

## Theorem ( $\mathrm{n}=1$ )

The revolution examples are the unique complete flat embedding in $\mathbb{H}^{3}$ with only one isolated singularity and one end.

## Theorem

Each complete flat embedding in $\mathbb{H}^{3}$ with only two isolated singularities and one end must be congruent to one of the
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## Characterizations

## Notes of the Proofs

The conditions on the boundary and in $z_{0}$ determine the above $R$, $g$ and $u$.
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## Characterizations

## Remark

There are not compact embedded flat surfaces, with less than three isolated singularities, because $R$ is constant only for the revolution examples.

