

Geodesic Connectedness in Spacetimes with Lightlike Killing Vector Fields

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Introduction

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Problem

When may two fixed points be connected by a geodesic?

When is \mathcal{M} geodesically connected?

Geodesic connectedness in Riemannian manifolds

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Theorem (Hopf–Rinow)

\mathcal{M}_0 complete with respect to the distance associated to $\langle \cdot, \cdot \rangle_R$ or, equivalently, \mathcal{M}_0 geodesically complete



\mathcal{M}_0 geodesically connected.

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Here, $d(x_1, x_2) = \inf \left\{ \int_a^b \sqrt{\langle \gamma', \gamma' \rangle_R} ds : \gamma \in A_{x_1, x_2} \right\}$

with $x_1, x_2 \in \mathcal{M}_0$ and $\gamma \in A_{x_1, x_2}$ if $\gamma : [a, b] \rightarrow \mathcal{M}_0$ is a piecewise smooth curve joining x_1 to x_2 .

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Classical variational principle

$\bar{z} : I \rightarrow \mathcal{M}$ is a geodesic joining p to q in \mathcal{M}



$\bar{z} = \bar{z}(s)$ is a critical point of the **action functional**

$$f(z) = \int_0^1 g(z(s))[z'(s), z'(s)] ds \quad \text{in } C^1(p, q),$$

with $C^1(p, q) = \{z \in C^1([0, 1], \mathcal{M}) : z(0) = p, z(1) = q\}$.

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Remark

Without loss of generality, we can take $I = [0, 1]$ as the set of geodesics is invariant by affine reparametrizations.

Abstract tools: existence result

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J satisfies the **Palais–Smale condition** on Ω , briefly **(PS)**, if any sequence $(x_k)_k \subset \Omega$ such that

$$(J(x_k))_k \text{ is bounded} \quad \text{and} \quad \lim_{k \rightarrow +\infty} J'(x_k) = 0$$

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Theorem (Existence)

Let Ω be complete. If J is a functional which satisfies (PS) and is bounded from below, then it attains its infimum.

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$H^1(I, \mathcal{M})$ is equipped with a structure of infinite dimensional manifold modelled on the Hilbert space $H^1(I, \mathbb{R}^n)$:

if $z \in H^1(I, \mathcal{M})$, the tangent space to $H^1(I, \mathcal{M})$ at z is

$$T_z H^1(I, \mathcal{M}) \equiv \{\zeta \in H^1(I, T\mathcal{M}) : \pi \circ \zeta = z\},$$

being $T\mathcal{M}$ the tangent bundle of \mathcal{M} and $\pi : T\mathcal{M} \rightarrow \mathcal{M}$ the corresponding bundle projection, i.e., $T_z H^1(I, \mathcal{M})$ is the set of the vector fields along z whose components with respect to a local chart are functions of class H^1 .

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Fixing $p, q \in \mathcal{M}$, we can consider

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with tangent space

$$T_z \Omega^1(p, q; \mathcal{M}) = \{\zeta \in T_z H^1(I, \mathcal{M}) : \zeta(0) = 0 = \zeta(1)\}$$

at $z \in \Omega^1(p, q; \mathcal{M})$.

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Fixing any $t_p, t_q \in \mathbb{R}$, it is

$$W^1(t_p, t_q) = \{t \in H^1(I, \mathbb{R}) : t(0) = t_p, t(1) = t_q\} = H_0^1(I, \mathbb{R}) + j^*,$$

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Whence, $W^1(t_p, t_q)$ is a closed affine submanifold of $H^1(I, \mathbb{R})$

with

$$T_t W^1(t_p, t_q) \equiv H_0^1(I, \mathbb{R}) \text{ for all } t \in W^1(t_p, t_q).$$

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By the Nash Embedding Theorem, \mathcal{M}_0 (at least C^2) is a submanifold of an Euclidean space \mathbb{R}^N (the embedding is closed in compact regions [Nash '63], complete regions [Müller '09]) and $\langle \cdot, \cdot \rangle_R$ is the restriction to \mathcal{M}_0 of the standard Euclidean metric of \mathbb{R}^N .

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Hence,

$$H^1(I, \mathcal{M}_0) \equiv \{x \in H^1(I, \mathbb{R}^N) : x(I) \subset \mathcal{M}_0\},$$

and, fixing any $x_p, x_q \in \mathcal{M}_0$, we have

$\Omega^1(x_p, x_q; \mathcal{M}_0) = \{x : I \rightarrow \mathcal{M}_0 : x \text{ absolutely continuous,}$

$$x(0) = x_p, x(1) = x_q, \int_0^1 \langle x', x' \rangle_R ds < +\infty\}.$$

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\mathcal{M}_0 complete $\implies H^1(I, \mathcal{M}_0), \Omega^1(x_p, x_q; \mathcal{M}_0)$ complete.

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is positive.

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Theorem (Hopf–Rinow)

\mathcal{M}_0 complete as metric space

\Downarrow

\mathcal{M}_0 geodesically connected.

Idea of the proof

Let $x_p, x_q \in \mathcal{M}_0$ be fixed. Denote $\|x'\|^2 = \int_0^1 \langle x', x' \rangle_R ds$.

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Lemma ("Splitting" Lemma)

Let \mathcal{M}_0 be a submanifold of \mathbb{R}^N and $(x_k)_k \subset \Omega^1(x_p, x_q; \mathcal{M}_0)$ a sequence so that $(\|x'_k\|)_k$ is bounded.

Then, $x \in H^1(I, \mathbb{R}^N)$ exists so that, up to subsequences, it is $x_k \rightharpoonup x$ weakly in $H^1(I, \mathbb{R}^N)$, $x_k \rightarrow x$ uniformly in I .

If \mathcal{M}_0 is complete, then $x \in \Omega^1(x_p, x_q; \mathcal{M}_0)$; furthermore, there exist two sequences $(\xi_k)_k, (\nu_k)_k \subset H^1(I, \mathbb{R}^N)$ such that $x_k - x = \xi_k + \nu_k$ with $\xi_k \in T_{x_k} \Omega^1(x_p, x_q; \mathcal{M}_0)$ for all $k \in \mathbb{N}$, $\xi_k \rightharpoonup 0$ weakly and $\nu_k \rightarrow 0$ strongly in $H^1(I, \mathbb{R}^N)$.

- V. Benci – D. Fortunato, *Adv. Math.* **105** (1994).

Variational proof

Variational proof of the Hopf–Rinow Theorem:

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f attains its infimum on $\Omega^1(x_p, x_q; \mathcal{M}_0)$.

Remark

\mathcal{M}_0 not contractible in itself \implies f has a diverging sequence of critical levels in $\Omega^1(x_p, x_q; \mathcal{M}_0)$.

Indefinite manifolds

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From a geometric point of view

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Example (anti-de Sitter spacetime)

$$\mathcal{M} =] - \frac{\pi}{2}, \frac{\pi}{2} [\times \mathbb{R}$$

equipped with the Lorentzian metric

$$\langle \cdot, \cdot \rangle_L = \frac{1}{\cos^2 x} (dx^2 - dt^2).$$

\mathcal{M} is geodesically complete but not geodesically connected.

- R. Penrose, *Conf. Board Math. Sci.* **7**, S.I.A.M. (1972).

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From an analytic point of view

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No general approach is known.

We select some special semi-Riemannian manifolds (stationary spacetimes, orthogonal splitting spacetimes, Gödel type spacetimes, plane wave type spacetimes, warped product spacetimes, ...) and develop *ad hoc* techniques.

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Definition

A **spacetime** is a connected and time-orientable Lorentzian manifold, with a prescribed time-orientation (a continuous choice of a causal cone at each $p \in \mathcal{M}$, which is called the **future** cone, in opposition to the non-chosen one or **past** cone).

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A C^1 curve $z : I \rightarrow \mathcal{M}$ is called timelike, lightlike, spacelike or causal when so it is $z'(s)$ for all $s \in I$.

For causal curves, this definition is extended to piecewise C^1 curves but the two limit tangent vectors on the breaks must belong to the same causal cone.

Accordingly, causal curves are called either future or past directed depending on the cone of $z'(s)$.

Causal character of a geodesic

A (non-constant) geodesic $z : I \rightarrow \mathcal{M}$ is:

- **timelike** if $E_z < 0$;
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- $\langle z'(s), z'(s) \rangle_L \equiv E_z$ for all $s \in I$;
- $\langle z'(s), K(z(s)) \rangle_L \equiv C_z$ for all $s \in I$.

Globally hyperbolic spacetime

Definition

A spacetime \mathcal{M} is **globally hyperbolic** if there exists a (smooth) spacelike Cauchy hypersurface \mathcal{S} in \mathcal{M} , i.e., a subset which is crossed exactly once by any inextendible timelike curve.

- E. Minguzzi – M. Sánchez. In: *Recent Developments in pseudo-Riemannian Geometry* (D.V. Alekseevsky & H. Baum Eds), EMS Publishing House, 2008.

Stationary Spacetime

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When the orthogonal distribution K^\perp to K is integrable, \mathcal{M} is a **static spacetime**.

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Remark

If one such a timelike Killing vector field K is chosen, then \mathcal{M} is time-oriented.

Standard Stationary Spacetime

Definition

$(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ is a **standard stationary spacetime** if splits globally as $\mathcal{M} = \mathcal{M}_0 \times \mathbb{R}$, with $(\mathcal{M}_0, \langle \cdot, \cdot \rangle_R)$ a finite dimensional connected Riemannian manifold, and metric $\langle \cdot, \cdot \rangle_L$ written as

$$\langle \cdot, \cdot \rangle_L = \langle \cdot, \cdot \rangle_R + 2\langle \delta(x), \cdot \rangle_R dt - \beta(x) dt^2$$

for each $T_z \mathcal{M} \equiv T_x \mathcal{M}_0 \times \mathbb{R}$, $z = (x, t) \in \mathcal{M}$, where δ and β are a smooth vector field and a smooth strictly positive scalar field on \mathcal{M}_0 , respectively.

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Fixing $p = (x_p, t_p)$, $q = (x_q, t_q) \in \mathcal{M} = \mathcal{M}_0 \times \mathbb{R}$, we have:

$$\Omega^1(p, q; \mathcal{M}) \equiv \Omega^1(x_p, x_q; \mathcal{M}_0) \times W^1(t_p, t_q),$$

$$T_z \Omega^1(p, q; \mathcal{M}) \equiv T_x \Omega^1(x_p, x_q; \mathcal{M}_0) \times H^1(I, \mathbb{R})$$

in each $z = (x, t) \in \Omega^1(p, q; \mathcal{M})$.

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We can distinguish two different variational approaches:

- (a) to transform the indefinite action functional f on $\Omega^1(p, q; \mathcal{M})$ in a new (hopefully bounded from below) functional \mathcal{J} on the Riemannian part $\Omega^1(x_p, x_q; \mathcal{M}_0)$;

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- (b) to study directly the strongly indefinite functional f but by making use of suitable (essentially finite–dimensional) “approximating” techniques.

Known results: extrinsic approach

Standard static spacetimes ($\delta \equiv 0$)

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Extrinsic approach: method (a)

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If $0 < \beta(x) \leq M$.

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If $0 < \beta(x) \leq \lambda d^2(x, \bar{x}) + \mu d^\alpha(x, \bar{x}) + k$.

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- L. Pisani, *Boll. Unione Mat. Ital. A* **7** (1991)
If some $\alpha < 1$ exists so that $0 < \epsilon \leq \beta(x) \leq \mu d^\alpha(x, \bar{x}) + k$,
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- A.M. C. and A. Salvatore, *J. Geom. Phys.* **44** (2002)
Multiplicity result in the same case.

Extrinsic approach, method (a)

$\mathcal{M} = \mathcal{M}_0 \times \mathbb{R}$ standard stationary spacetime,

$p = (x_p, t_p)$, $q = (x_q, t_q)$

Proposition (New variational principle)

$z^* = (x^*, t^*) \in \Omega^1(p, q; \mathcal{M})$ is a critical point of the action functional f in $\Omega^1(p, q; \mathcal{M})$ if and only if x^* is a critical point of the functional $\mathcal{J} : \Omega^1(x_p, x_q; \mathcal{M}_0) \rightarrow \mathbb{R}$ defined as

$$\mathcal{J}(x) = \int_0^1 \langle x', x' \rangle_R ds + \int_0^1 \frac{\langle \delta(x), x' \rangle_R^2}{\beta(x)} ds - \left(\int_0^1 \frac{\langle \delta(x), x' \rangle_R}{\beta(x)} ds - \Delta_t \right)^2 \left(\int_0^1 \frac{1}{\beta(x)} ds \right)^{-1}$$

and $t^* = \Psi(x^*)$, with $\Delta_t^2 = (t_q - t_p)^2$.

Moreover, $f(z^*) = \mathcal{J}(x^*)$.

Extrinsic approach, method (a)

In the previous proposition, it is

$\Psi : \Omega^1(x_p, x_q; \mathcal{M}_0) \rightarrow W^1(t_p, t_q)$ defined as

$$\Psi(x)(s) = t_0 + \int_0^s \frac{\langle \delta(x(\sigma)), \dot{x}(\sigma) \rangle}{\beta(x(\sigma))} d\sigma - \left(\int_0^1 \frac{\langle \delta(x), \dot{x} \rangle}{\beta(x)} ds - \Delta_t \right) \int_0^s \frac{1}{\beta(x(\sigma))} d\sigma \left(\int_0^1 \frac{1}{\beta(x)} ds \right)^{-1}.$$

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Extrinsic approach, method (a)

Theorem

Let $\mathcal{M} = \mathbb{R} \times \mathcal{M}_0$ be a standard stationary spacetime.
 If $(\mathcal{M}_0, \langle \cdot, \cdot \rangle_R)$ is complete and $\bar{x} \in \mathcal{M}_0$ exists such that

$$0 < \beta(x) \leq \lambda d^2(x, \bar{x}) + \mu d^\alpha(x, \bar{x}) + k,$$

$$\sqrt{\langle \delta(x), \delta(x) \rangle_R} \leq \lambda_1 d(x, \bar{x}) + \mu_1 d^{\alpha_1}(x, \bar{x}) + k_1,$$

for all $x \in \mathcal{M}_0$ and for suitable $\lambda, \lambda_1 \geq 0, \mu, \mu_1, k, k_1 \in \mathbb{R},$
 $\alpha, \alpha_1 \in [0, 1)$.

Then, \mathcal{M} is geodesically connected.

- R. Bartolo, A.M. C. and J.L. Flores, *J. Geom. Phys.* 56 (2006)

Idea of the proof

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Remark

\mathcal{M}_0 non-contractible in itself \implies any two points can be joined by a sequence of (spacelike) geodesics $(z_k)_k$ with diverging lengths.

Known results: intrinsic approach

- F. Giannoni and P. Piccione, *Comm. Anal. Geom.* **7** (1999).

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Geodesic connectedness in stationary spacetimes via an intrinsic approach.

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Applying the previous result to the standard stationary case:

$$0 < \epsilon \leq \beta(x) \leq M,$$

$$|\delta(x)| \leq \mu d^\alpha(x, \bar{x}) + k,$$

for all $x \in \mathcal{M}_0$ ($\alpha < 1$).

Remarks

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Every stationary spacetime is locally a standard stationary one with $K = \partial_t$ as timelike Killing vector field.

Theorem

A globally hyperbolic stationary spacetime is a standard stationary one, if one of its timelike Killing vector fields is complete.

- A.M. C., J.L. Flores and M. Sánchez, *Adv. Math.* **218** (2008)

A more general case

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Theorem (Part 1)

Let $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ be a globally hyperbolic spacetime admitting a complete causal Killing vector field K . Then, there exist a Riemannian manifold $(\mathcal{S}, \langle \cdot, \cdot \rangle)$, a differentiable vector field δ on \mathcal{S} and a differentiable non-negative function β on \mathcal{S} such that $\mathcal{M} = \mathcal{S} \times \mathbb{R}$ and

$$\langle \zeta, \zeta' \rangle_L = \langle \xi, \xi' \rangle + \langle \delta(x), \xi \rangle \tau' + \langle \delta(x), \xi' \rangle \tau - \beta(x) \tau \tau',$$

for all $z = (x, t) \in \mathcal{M}$ and $\zeta = (\xi, \tau), \zeta' = (\xi', \tau') \in T_z \mathcal{M} = T_x \mathcal{S} \times \mathbb{R}$.

- R. Bartolo, A.M. C. and J.L. Flores, *Rev. Mat. Iberoam.* (?)

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$$\langle \zeta, \zeta' \rangle_L = \langle \xi, \xi' \rangle + \langle \delta(x), \xi \rangle \tau' + \langle \delta(x), \xi' \rangle \tau,$$

for all $z = (x, t) \in \mathcal{M}$ and
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$$C_K^1(p, q) = \{z \in C^1(p, q) : \exists C_z \in \mathbb{R} \text{ such that } \langle z', K(z) \rangle_L \equiv C_z\}.$$

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If $z \in C_K^1(p, q)$ is a critical point of f restricted to $C_K^1(p, q)$, then z is a geodesic connecting p to q .

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Define $\Omega_K^1(p, q) = \{z \in \Omega^1(p, q; \mathcal{M}) : \exists C_z \in \mathbb{R} \text{ such that } \langle z', K(z) \rangle_L = C_z \text{ a.e. on } I\}$.

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If $z \in C_K^1(p, q)$ is a critical point of f restricted to $C_K^1(p, q)$, then z is a geodesic connecting p to q .

Define $\Omega_K^1(p, q) = \{z \in \Omega^1(p, q; \mathcal{M}) : \exists C_z \in \mathbb{R} \text{ such that } \langle z', K(z) \rangle_L = C_z \text{ a.e. on } I\}$.

Theorem

If $z \in \Omega_K^1(p, q)$ is a critical point of f restricted to $\Omega_K^1(p, q)$, then z is a geodesic connecting p and q .

Intrinsic approach

The following definition translates, essentially, classical Palais–Smale condition to the stationary ambient.

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Definition

Fixed $c \in \mathbb{R}$ the set $\Omega_K^1(p, q)$ is c -precompact for f if every sequence $(z_n)_n \subset \Omega_K^1(p, q)$ with $f(z_n) \leq c$ has a subsequence which converges weakly in $\Omega^1(p, q; \mathcal{M})$ (hence, uniformly in \mathcal{M}). Furthermore, the restriction of f to $\Omega_K^1(p, q)$ is pseudo-coercive if $\Omega_K^1(p, q)$ is c -precompact for all $c \geq \inf f(\Omega_K^1(p, q))$.

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If $\Omega_K^1(p, q)$ is not empty and there exists $c > \inf f(\Omega_K^1(p, q))$ such that $\Omega_K^1(p, q)$ is c -precompact, then there exists at least one geodesic joining p to q in \mathcal{M}

- F. Giannoni and P. Piccione, *Comm. Anal. Geom.* **7** (1999)

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Remark

The main limitation of Giannoni and Piccione’s results is that pseudo-coercivity condition is analytical and very technical. Furthermore, in general, the assumption $\Omega_K^1(p, q)$ non-empty must be imposed.

Intrinsic approach

In order to overcome the limitation of Giannoni and Piccione's result, the idea is to introduce purely geometric assumptions on \mathcal{M} .

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Theorem

Let $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ be a stationary spacetime with a complete timelike Killing vector field K . If \mathcal{M} is globally hyperbolic with a complete (smooth, spacelike) Cauchy hypersurface S , then it is geodesically connected.

- A.M. C., J.L. Flores and M. Sánchez, *Adv. Math.* **218** (2008)

Hint of the proof

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If the timelike Killing vector field K is complete, then it is $\Omega_K^1(p, q) \neq \emptyset$ for each $p, q \in \mathcal{M}$.

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Hence, the Giannoni - Piccione Theorem applies.

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Counterexamples can be constructed so that:

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Lightlike Killing case

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In general, the answer is: **NO**.

Counterexample

$\mathcal{M} = \mathbb{R}^3 \times \mathbb{R}$ equipped with the Lorentzian metric

$$\langle \zeta, \zeta' \rangle_L = \langle \xi, \xi' \rangle + \langle \delta(x), \xi \rangle \tau' + \langle \delta(x), \xi' \rangle \tau,$$

for all $\zeta = (\xi, \tau), \zeta' = (\xi', \tau') \in \mathbb{R}^4$, where $\langle \cdot, \cdot \rangle$ is the canonical scalar product on \mathbb{R}^3 and

$\delta : x = (x_1, x_2, x_3) \in \mathbb{R}^3 \mapsto \delta(x_1) \in \mathbb{R}^3$ satisfies

$$\delta(x_1) = \begin{cases} (-\cos^3 x_1, 0, 0) & \text{if } x_1 < \pi \\ (1, 0, 0) & \text{if } x_1 \geq \pi. \end{cases}$$

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In this spacetime:

- ∂_t is a complete lightlike Killing vector field,
- $\mathbb{R}^3 \times \{t\}$ is a complete Cauchy hypersurface for every $t \in \mathbb{R}$; but there is no geodesic which connects, for example, $x_p = (0, 0, 0)$ and $x_q = (3\pi/2, 0, 0)$.

Connectedness

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Theorem

Let $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ be a globally hyperbolic spacetime endowed with a complete lightlike Killing vector field K and a complete (smooth, spacelike) Cauchy hypersurface \mathcal{S} . Let $p, q \in \mathcal{M}$. Then:
 p and q are geodesically connected in \mathcal{M}



p and q can be connected by a C^1 curve φ on \mathcal{M} such that $\langle \dot{\varphi}, K(\varphi) \rangle_L$ has constant sign or is identically equal to 0.

- R. Bartolo, A.M. C. and J.L. Flores, *Rev. Mat. Iberoam.* (?)

Hint of the proof

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- Taking $p = (x_p, t_p)$, $q = (x_q, t_q) \in \mathcal{M}$ with $\Delta_t = t_q - t_p \geq 0$, there exists $n_0 \in \mathbb{N}$ such that p and q are connected by a geodesic $\gamma_n = (x_n, t_n)$ in $(\mathcal{M}_n, \langle \cdot, \cdot \rangle_n)$ for every $n \geq n_0$

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- If a C^1 curve φ exists such that $\langle \dot{\varphi}, K(\varphi) \rangle_L$ has constant sign or is identically equal to 0, then γ exists such that, up to subsequences, $\gamma_n \rightarrow \gamma$ strongly on $\Omega(x_p, x_q; \mathcal{S}) \times W(t_p, t_q)$

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- γ is a geodesic joining p to q in \mathcal{M} .

Applications: Avez–Seifert result

An alternative proof of the classical Avez–Seifert result:

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An alternative proof of the classical Avez–Seifert result:

Proposition

Let $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ be a globally hyperbolic spacetime endowed with a complete lightlike Killing vector field K and a complete Cauchy hypersurface S . Then, two points of \mathcal{M} can be connected by a causal geodesic if and only if they are causally related.

Applications: Generalized Plane Waves

Definition

A Lorentzian manifold $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ is called *generalized plane wave*, briefly *GPW*, if there exists a (connected) finite dimensional Riemannian manifold $(\mathcal{M}_0, \langle \cdot, \cdot \rangle_R)$ such that $\mathcal{M} = \mathcal{M}_0 \times \mathbb{R}^2$ and

$$\langle \cdot, \cdot \rangle_L = \langle \cdot, \cdot \rangle_R + 2dudv + \mathcal{H}(x, u)du^2,$$

where $x \in \mathcal{M}_0$, the variables (u, v) are the natural coordinates of \mathbb{R}^2 and the smooth function $\mathcal{H} : \mathcal{M}_0 \times \mathbb{R} \rightarrow \mathbb{R}$ is not identically zero.

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A GPW becomes a gravitational wave if $\mathcal{M}_0 = \mathbb{R}^2$ is equipped with the classical Euclidean metric and

$\mathcal{H}(x, u) = g_1(u)(x_1^2 - x_2^2) + 2g_2(u)x_1x_2$, $x = (x_1, x_2) \in \mathbb{R}^2$,
with g_1, g_2 smooth real functions such that $g_1^2 + g_2^2 \neq 0$.

Applications: Generalized Plane Waves

About geodesic connectedness and global hyperbolicity of GPWs:

Applications: Generalized Plane Waves

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Theorem

If the Riemannian manifold $(\mathcal{M}_0, \langle \cdot, \cdot \rangle_R)$ is complete with respect to its canonical distance and \mathcal{H} behaves subquadratically at spatial infinity, i.e., there exist $\bar{x} \in \mathcal{M}_0$ and (positive) continuous functions $R_1(u)$, $R_2(u)$, $p(u)$, with $p(u) < 2$, such that

$$-\mathcal{H}(x, u) \leq R_1(u)d^{p(u)}(x, \bar{x}) + R_2(u) \quad \text{for all } (x, u) \in \mathcal{M}_0 \times \mathbb{R},$$

then the spacetime is geodesically connected and globally hyperbolic.

- A.M. C., J.L. Flores, M. Sánchez, *Gen. Relativity Gravitation* **35** (2003)
- J.L. Flores, M. Sánchez, *Class. Quant. Grav.* **20** (2003)

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If $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ is a GPW, then $K = \partial_v$ is a complete lightlike Killing vector field on \mathcal{M} .

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If $(\mathcal{M}, \langle \cdot, \cdot \rangle_L)$ is a GPW, then $K = \partial_v$ is a complete lightlike Killing vector field on \mathcal{M} .

Moreover, taking any $p = (x_p, u_p, v_p), q = (x_q, u_q, v_q) \in \mathcal{M}$ and any curve $x = x(s)$ in \mathcal{M}_0 connecting x_p to x_q , if we denote $\Delta_u = u_q - u_p$ and $\Delta_v = v_q - v_p$, we have that the curve $\varphi(s) = (x(s), \Delta_u s, \Delta_v s)$ connects p to q , and the scalar product

$$\langle \dot{\varphi}, K(\varphi) \rangle_L = \dot{u} = \Delta_u$$

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Theorem

Any globally hyperbolic GPW with a complete Cauchy hypersurface is geodesically connected.