

The Willmore and other L^2 curvature functionals in Riemannian manifolds

Andrea Mondino
Scuola Normale Superiore

Granada, Seminario de Geometría, 7th March 2012

Introduction

NOTATION:

- ▶ (M, g) 3-d Riemannian manifold
- ▶ Σ **closed** (compact, $\partial\Sigma = \emptyset$) 2-d surface
- ▶ $f : \Sigma \hookrightarrow M$ immersion, \mathring{g} induced metric on Σ

NOTATION:

- ▶ (M, g) 3-d Riemannian manifold
- ▶ Σ **closed** (compact, $\partial\Sigma = \emptyset$) 2-d surface
- ▶ $f : \Sigma \hookrightarrow M$ immersion, \mathring{g} induced metric on Σ
- ▶ $A_{ij} = - \langle \nabla_{\partial_{x^i}} N, \partial_{x^j} \rangle$ II fundamental form of $f(\Sigma)$
- ▶ $H = A_{ij} \mathring{g}^{ij} = k_1 + k_2 =$ mean curvature
- ▶ $A_{ij}^{\circ} = A_{ij} - \frac{1}{2} H \mathring{g}_{ij} =$ traceless II fundamental form

NOTATION:

- ▶ (M, g) 3-d Riemannian manifold
- ▶ Σ **closed** (compact, $\partial\Sigma = \emptyset$) 2-d surface
- ▶ $f : \Sigma \hookrightarrow M$ immersion, \mathring{g} induced metric on Σ
- ▶ $A_{ij} = - \langle \nabla_{\partial_{x^i}} N, \partial_{x^j} \rangle$ II fundamental form of $f(\Sigma)$
- ▶ $H = A_{ij} \mathring{g}^{ij} = k_1 + k_2 =$ mean curvature
- ▶ $A_{ij}^{\circ} = A_{ij} - \frac{1}{2} H \mathring{g}_{ij} =$ traceless II fundamental form

Question

Which are the best immersions f ?

Classical special immersions

Classical special immersions

- ▶ $H \equiv 0 \Rightarrow$ MINIMAL immersion (\rightsquigarrow critical point of Area)

Classical special immersions

- ▶ $H \equiv 0 \Rightarrow$ MINIMAL immersion (\rightsquigarrow critical point of Area)
- ▶ $A \equiv 0 \Rightarrow$ TOTALLY GEODESIC immersion

Classical special immersions

- ▶ $H \equiv 0 \Rightarrow$ MINIMAL immersion (\rightsquigarrow critical point of Area)
- ▶ $A \equiv 0 \Rightarrow$ TOTALLY GEODESIC immersion
- ▶ $A^\circ \equiv 0 \Rightarrow k_1 = k_2$ TOTALLY UMBILIC immersion

Classical special immersions

- ▶ $H \equiv 0 \Rightarrow$ MINIMAL immersion (\rightsquigarrow critical point of Area)
- ▶ $A \equiv 0 \Rightarrow$ TOTALLY GEODESIC immersion
- ▶ $A^\circ \equiv 0 \Rightarrow k_1 = k_2$ TOTALLY UMBILIC immersion

FACT: in general they may not exist (ex. minimal in \mathbb{R}^3 or totally umbilical in Berger Spheres)

Classical special immersions

- ▶ $H \equiv 0 \Rightarrow$ MINIMAL immersion (\rightsquigarrow critical point of Area)
- ▶ $A \equiv 0 \Rightarrow$ TOTALLY GEODESIC immersion
- ▶ $A^\circ \equiv 0 \Rightarrow k_1 = k_2$ TOTALLY UMBILIC immersion

FACT: in general they may not exist (ex. minimal in \mathbb{R}^3 or totally umbilical in Berger Spheres)

Question

How it is possible to relax the definitions in order to get existence?

→ Look for minimizers (or critical points) of

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

$$\int_{f(\Sigma)} |A|^p, p > 1$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

$$\int_{f(\Sigma)} |A|^p, p > 1 \rightsquigarrow \text{"generalized totally geodesic"}$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

$$\int_{f(\Sigma)} |A|^p, p > 1 \rightsquigarrow \text{"generalized totally geodesic"}$$

$$\int_{f(\Sigma)} |A^\circ|^p, p > 1$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

$$\int_{f(\Sigma)} |A|^p, p > 1 \rightsquigarrow \text{"generalized totally geodesic"}$$

$$\int_{f(\Sigma)} |A^\circ|^p, p > 1 \rightsquigarrow \text{"generalized totally umbilic"}$$

→ Look for minimizers (or critical points) of

$$\int_{f(\Sigma)} |H|^p, p > 1 \rightsquigarrow \text{"generalized minimal"}$$

$$\int_{f(\Sigma)} |A|^p, p > 1 \rightsquigarrow \text{"generalized totally geodesic"}$$

$$\int_{f(\Sigma)} |A^\circ|^p, p > 1 \rightsquigarrow \text{"generalized totally umbilic"}$$

Remark

(M, g) and Σ are fixed at the beginning, minimize in the immersion f

$p = 2 \rightsquigarrow$ Willmore functionals

$p = 2 \rightsquigarrow$ Willmore functionals

Definition

In case $p = 2$,

$$W(f) := \frac{1}{4} \int_{f(\Sigma)} |H|^2 \quad \text{Willmore functional}$$

$$W_{\text{cnf}}(f) := \frac{1}{2} \int_{f(\Sigma)} |A^\circ|^2 \quad \text{Conformal Willmore functional}$$

$$E(f) := \frac{1}{2} \int_{f(\Sigma)} |A|^2 \quad \text{Energy functional}$$

$p = 2 \rightsquigarrow$ Willmore functionals

Definition

In case $p = 2$,

$$W(f) := \frac{1}{4} \int_{f(\Sigma)} |H|^2 \quad \text{Willmore functional}$$

$$W_{\text{cnf}}(f) := \frac{1}{2} \int_{f(\Sigma)} |A^\circ|^2 \quad \text{Conformal Willmore functional}$$

$$E(f) := \frac{1}{2} \int_{f(\Sigma)} |A|^2 \quad \text{Energy functional}$$

Remark: if $(M, g) = (\mathbb{R}^3, \text{eucl})$ then by Gauss Bonnet Theorem

$$W(f) = W_{\text{cnf}}(f) + 2\pi\chi_E(\Sigma) = \frac{1}{2}E(f) + \pi\chi_E(\Sigma)$$

Conformal invariance

Theorem (Wiener)

$W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ is conformally invariant, i.e.

$$\forall u \in C^\infty(M) \text{ called } g[u] := e^{2u}g \Rightarrow W_{cnf}(f)[u] = W_{cnf}(f)$$

where $W_{cnf}(f)[u]$ is the conformal Willmore functional evaluated on $f(\Sigma)$ immersed in $(M, g[u])$.

Theorem (Wiener)

$W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ is conformally invariant, i.e.

$$\forall u \in C^\infty(M) \text{ called } g[u] := e^{2u}g \Rightarrow W_{cnf}(f)[u] = W_{cnf}(f)$$

where $W_{cnf}(f)[u]$ is the conformal Willmore functional evaluated on $f(\Sigma)$ immersed in $(M, g[u])$.

Remark

W is conformal invariant in \mathbb{R}^3 but not in a general manifold \Rightarrow
 W_{cnf} is the "correct" Willmore functional from a conformal point of view.

Applications

- ▶ General Relativity: Hawking mass

$$Mass(\Sigma) := \sqrt{\frac{Area(\Sigma)}{16\pi}} \left(1 - \frac{1}{16\pi} \int_{\Sigma} |H|^2\right)$$

- ▶ General Relativity: Hawking mass

$$Mass(\Sigma) := \sqrt{\frac{Area(\Sigma)}{16\pi}} \left(1 - \frac{1}{16\pi} \int_{\Sigma} |H|^2\right)$$

- ▶ String Theory: Polyakov extrinsic action

- ▶ General Relativity: Hawking mass

$$Mass(\Sigma) := \sqrt{\frac{Area(\Sigma)}{16\pi}} \left(1 - \frac{1}{16\pi} \int_{\Sigma} |H|^2\right)$$

- ▶ String Theory: Polyakov extrinsic action
- ▶ Biology: Helfrich Energy

- ▶ General Relativity: Hawking mass

$$Mass(\Sigma) := \sqrt{\frac{Area(\Sigma)}{16\pi}} \left(1 - \frac{1}{16\pi} \int_{\Sigma} |H|^2\right)$$

- ▶ String Theory: Polyakov extrinsic action
- ▶ Biology: Helfrich Energy
- ▶ Reilly Theorem: if $\Sigma \hookrightarrow (\mathbb{R}^3, eucl)$

$$\lambda_1(\Sigma) \leq \frac{2}{Area(\Sigma)} \int_{\Sigma} |H|^2$$

- ▶ General Relativity: Hawking mass

$$Mass(\Sigma) := \sqrt{\frac{Area(\Sigma)}{16\pi}} \left(1 - \frac{1}{16\pi} \int_{\Sigma} |H|^2\right)$$

- ▶ String Theory: Polyakov extrinsic action
- ▶ Biology: Helfrich Energy
- ▶ Reilly Theorem: if $\Sigma \hookrightarrow (\mathbb{R}^3, eucl)$

$$\lambda_1(\Sigma) \leq \frac{2}{Area(\Sigma)} \int_{\Sigma} |H|^2$$

- ▶ Nonlinear elasticity theory, as Γ -limit of energy functionals (Friesecke-James-Müller)

Our problem

GOAL: Minimize or more generally find critical points of W , W_{cnf} , E and related functionals

→ prove existence of "generalized special immersions".

Some literature about existence of minimizers or critical points

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):

$$\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi \text{ and } W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$$

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)
- ▶ Multiplicity results in genus 1 by Pinkall

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)
- ▶ Multiplicity results in genus 1 by Pinkall
- ▶ Recent works by Rivière, Kuwert, Schätzle, Topping, Bernard, Schygulla etc.

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e.
 $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)
- ▶ Multiplicity results in genus 1 by Pinkall
- ▶ Recent works by Rivière, Kuwert, Schätzle, Topping, Bernard, Schygulla etc.

In **manifolds**?

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e. $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)
- ▶ Multiplicity results in genus 1 by Pinkall
- ▶ Recent works by Rivière, Kuwert, Schätzle, Topping, Bernard, Schygulla etc.

In **manifolds**? Just in space forms: Bang-Yen Chen, Guo, Li-Yau, Montiel, Ritoré, Ros, Urbano, Wiener, etc.

Some literature about existence of minimizers or critical points

Willmore functional $W = \frac{1}{4} \int H^2$ In **Euclidean Space**, i.e. $(M, g) = (\mathbb{R}^3, eucl)$:

- ▶ Strict global minimum on standard spheres S_p^ρ (Willmore '60):
 $\forall \Sigma, \forall f : \Sigma \hookrightarrow \mathbb{R}^3 \Rightarrow W(f) \geq 4\pi$ and $W(f) = 4\pi \Leftrightarrow f(\Sigma) = S_p^\rho$
- ▶ For each genus the infimum ($> 4\pi$) is reached: Simon (1993) and Bauer-Kuwert (2003), different proof by Rivière (2010)
- ▶ Multiplicity results in genus 1 by Pinkall
- ▶ Recent works by Rivière, Kuwert, Schätzle, Topping, Bernard, Schygulla etc.

In **manifolds**? Just in space forms: Bang-Yen Chen, Guo, Li-Yau, Montiel, Ritoré, Ros, Urbano, Wiener, etc.

TODAY: give results, i.e. existence or non-existence of minimizers or critical points, in non constantly curved manifolds

Perturbative setting

Ambient manifold: $(M, g) = (\mathbb{R}^3, g_\epsilon)$ where $(g_\epsilon)_{\mu\nu} := \delta_{\mu\nu} + \epsilon h_{\mu\nu}$,
 $h_{\mu\nu}$ is symmetric $(2, 0)$ tensor field.

Ambient manifold: $(M, g) = (\mathbb{R}^3, g_\epsilon)$ where $(g_\epsilon)_{\mu\nu} := \delta_{\mu\nu} + \epsilon h_{\mu\nu}$, $h_{\mu\nu}$ is symmetric (2,0) tensor field.

IDEA: for $\epsilon = 0$ the ambient manifold is $\mathbb{R}^3 \Rightarrow$ the round spheres form a 4-d manifold of critical points

Ambient manifold: $(M, g) = (\mathbb{R}^3, g_\epsilon)$ where $(g_\epsilon)_{\mu\nu} := \delta_{\mu\nu} + \epsilon h_{\mu\nu}$, $h_{\mu\nu}$ is symmetric $(2,0)$ tensor field.

IDEA: for $\epsilon = 0$ the ambient manifold is $\mathbb{R}^3 \Rightarrow$ the round spheres form a 4-d manifold of critical points \rightarrow use a perturbative method lying on a Lyapunov-Schmidt reduction.

Existence for W in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: if $(M, g) = (\mathbb{R}^3, g_\epsilon := \text{eucl} + \epsilon h)$, write
 $R = \epsilon R_1 + o(\epsilon)$

Existence for W in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: if $(M, g) = (\mathbb{R}^3, g_\epsilon := \text{eucl} + \epsilon h)$, write
 $R = \epsilon R_1 + o(\epsilon)$

Theorem [M.(Math. Zeit. '10)]

Assume

- $\exists \bar{p} \in \mathbb{R}^3$ such that $R_1(\bar{p}) \neq 0$,
- Said $\|h(p)\| := \sup_{|v|=1} |h_p(v, v)|$
 - $\lim_{|p| \rightarrow \infty} \|h(p)\| = 0$.
 - $\exists C > 0$ and $\alpha > 2$ s.t. $|D_\lambda h_{\mu\nu}(p)| < \frac{C}{|p|^\alpha} \quad \forall \lambda, \mu, \nu = 1 \dots 3$.

Existence for W in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: if $(M, g) = (\mathbb{R}^3, g_\epsilon := \text{eucl} + \epsilon h)$, write $R = \epsilon R_1 + o(\epsilon)$

Theorem [M.(Math. Zeit. '10)]

Assume

- $\exists \bar{p} \in \mathbb{R}^3$ such that $R_1(\bar{p}) \neq 0$,

- Said $\|h(p)\| := \sup_{|v|=1} |h_p(v, v)|$

i) $\lim_{|p| \rightarrow \infty} \|h(p)\| = 0$.

ii) $\exists C > 0$ and $\alpha > 2$ s.t. $|D_\lambda h_{\mu\nu}(p)| < \frac{C}{|p|^\alpha} \quad \forall \lambda, \mu, \nu = 1 \dots 3$.

Then, for ϵ small enough, there exists a perturbed standard sphere $S_{\rho_\epsilon}^{\rho_\epsilon}(w_\epsilon(p_\epsilon, \rho_\epsilon))$ (where $w_\epsilon(p_\epsilon, \rho_\epsilon) \in C^{4,\alpha}(S^2)$) which is a Willmore immersion of S^2 in $(\mathbb{R}^3, g_\epsilon)$

Existence for W in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: if $(M, g) = (\mathbb{R}^3, g_\epsilon := \text{eucl} + \epsilon h)$, write $R = \epsilon R_1 + o(\epsilon)$

Theorem [M.(Math. Zeit. '10)]

Assume

- $\exists \bar{p} \in \mathbb{R}^3$ such that $R_1(\bar{p}) \neq 0$,

- Said $\|h(p)\| := \sup_{|v|=1} |h_p(v, v)|$

i) $\lim_{|p| \rightarrow \infty} \|h(p)\| = 0$.

ii) $\exists C > 0$ and $\alpha > 2$ s.t. $|D_\lambda h_{\mu\nu}(p)| < \frac{C}{|p|^\alpha} \quad \forall \lambda, \mu, \nu = 1 \dots 3$.

Then, for ϵ small enough, there exists a perturbed standard sphere $S_{\rho_\epsilon}^{\rho_\epsilon}(w_\epsilon(p_\epsilon, \rho_\epsilon))$ (where $w_\epsilon(p_\epsilon, \rho_\epsilon) \in C^{4,\alpha}(S^2)$) which is a Willmore immersion of S^2 in $(\mathbb{R}^3, g_\epsilon)$

Lemma[M. (Math. Zeit. '10)]: Let (M, g) be a general ambient manifold with scalar curvature R ,

Existence for W in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: if $(M, g) = (\mathbb{R}^3, g_\epsilon := \text{eucl} + \epsilon h)$, write $R = \epsilon R_1 + o(\epsilon)$

Theorem [M.(Math. Zeit. '10)]

Assume

- $\exists \bar{p} \in \mathbb{R}^3$ such that $R_1(\bar{p}) \neq 0$,

- Said $\|h(p)\| := \sup_{|v|=1} |h_p(v, v)|$

i) $\lim_{|p| \rightarrow \infty} \|h(p)\| = 0$.

ii) $\exists C > 0$ and $\alpha > 2$ s.t. $|D_\lambda h_{\mu\nu}(p)| < \frac{C}{|p|^\alpha} \quad \forall \lambda, \mu, \nu = 1 \dots 3$.

Then, for ϵ small enough, there exists a perturbed standard sphere $S_{\rho_\epsilon}^{\rho_\epsilon}(w_\epsilon(p_\epsilon, \rho_\epsilon))$ (where $w_\epsilon(p_\epsilon, \rho_\epsilon) \in C^{4,\alpha}(S^2)$) which is a Willmore immersion of S^2 in $(\mathbb{R}^3, g_\epsilon)$

Lemma[M. (Math. Zeit. '10)]: Let (M, g) be a general ambient manifold with scalar curvature R , then the following expansion of W on small geodesic spheres hold:

$$W(S_{p,\rho}) = 4\pi - \frac{2\pi}{3} R(p)\rho^2 + O_p(\rho^3)$$

Remark + non Existence for W

REMARK: g_ϵ is close and asymptotical to euclidean but **NOT**
CONSTANT CURVATURE

REMARK: g_ϵ is close and asymptotical to euclidean but **NOT CONSTANT CURVATURE**

Theorem (M.(Math. Zeit. '10))

Let (M, g) be a 3-d Riemannian manifold and assume that at the point $\bar{p} \in M$ the scalar curvature is non null:

$$R(\bar{p}) \neq 0.$$

*Then, for radius ρ and perturbation $w \in C^{4,\alpha}(S^2)$ small enough, the perturbed geodesic spheres $S_{\bar{p},\rho}(w)$ are **not** critical points of the Willmore functional W .*

Remark + non Existence for W

REMARK: g_ϵ is close and asymptotical to euclidean but **NOT CONSTANT CURVATURE**

Theorem (M.(Math. Zeit. '10))

Let (M, g) be a 3-d Riemannian manifold and assume that at the point $\bar{p} \in M$ the scalar curvature is non null:

$$R(\bar{p}) \neq 0.$$

*Then, for radius ρ and perturbation $w \in C^{4,\alpha}(S^2)$ small enough, the perturbed geodesic spheres $S_{\bar{p},\rho}(w)$ are **not** critical points of the Willmore functional W .*

REMARK: different behavior from flat case where all the spheres are critical points

Results for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in $(\mathbb{R}^3, g_\epsilon)$

Results for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: traceless Ricci tensor of a Riemannian manifold

$$S_{\mu\nu} := Ric_{\mu\nu} - \frac{1}{3}R g_{\mu\nu}$$

in $(\mathbb{R}^3, g_\epsilon)$ one has $\|S_p\|^2 = \epsilon^2 \tilde{s}_p + o(\epsilon^2)$

Results for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in $(\mathbb{R}^3, g_\epsilon)$

NOTATION: traceless Ricci tensor of a Riemannian manifold

$$S_{\mu\nu} := Ric_{\mu\nu} - \frac{1}{3}R g_{\mu\nu}$$

in $(\mathbb{R}^3, g_\epsilon)$ one has $\|S_p\|^2 = \epsilon^2 \tilde{s}_p + o(\epsilon^2)$

Theorem (M. (J.G.A. '11))

Let $h_{\mu\nu} \in C_0^\infty(\mathbb{R}^3)$ and let c be such that

$$c := \sup\{\|h_{\mu\nu}\|_{H^1(\pi)} : \pi \text{ is an affine plane in } \mathbb{R}^3, \mu, \nu = 1, 2, 3\}.$$

Then there exists a constant $A_c > 0$ depending on c with the following property: if there exists a point \bar{p} such that

$$\tilde{s}_{\bar{p}} > A_c$$

then, for ϵ small enough, there exists a perturbed standard sphere $S_{p_\epsilon}^{\rho_\epsilon}(w_\epsilon)$ which is a critical point of the conformal Willmore functional W_{cnf} converging to a standard sphere as $\epsilon \rightarrow 0$.

Non existence for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in General 3-Manifolds

Non existence for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in General 3-Manifolds

Since S_ρ^ρ are critical in \mathbb{R}^3 , may expect that small perturbations of small geodesic spheres $S_{\rho,\rho}$ are critical in manifolds, but

Non existence for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in General 3-Manifolds

Since S_ρ^ρ are critical in \mathbb{R}^3 , may expect that small perturbations of small geodesic spheres $S_{\rho,\rho}$ are critical in manifolds, but

Theorem (M. (J.G.A. '11))

Let (M, g) be a Riemannian manifold. Assume that the traceless Ricci tensor of M at the point \bar{p} is not null:

$$\|S_{\bar{p}}\| \neq 0.$$

Then there exist $\rho_0 > 0$ and $r > 0$ such that for radius $\rho < \rho_0$ and perturbation $w \in C^{4,\alpha}(S^2)$ with $\|w\|_{C^{4,\alpha}(S^2)} < r$, the surfaces $S_{\bar{p},\rho}(w)$ are not critical points of W_{cnf} .

Non existence for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in General 3-Manifolds

Since S_ρ^ρ are critical in \mathbb{R}^3 , may expect that small perturbations of small geodesic spheres $S_{\rho,\rho}$ are critical in manifolds, but

Theorem (M. (J.G.A. '11))

Let (M, g) be a Riemannian manifold. Assume that the traceless Ricci tensor of M at the point \bar{p} is not null:

$$\|S_{\bar{p}}\| \neq 0.$$

Then there exist $\rho_0 > 0$ and $r > 0$ such that for radius $\rho < \rho_0$ and perturbation $w \in C^{4,\alpha}(S^2)$ with $\|w\|_{C^{4,\alpha}(S^2)} < r$, the surfaces $S_{\bar{p},\rho}(w)$ are not critical points of W_{cnf} .

Remark:- The condition $\|S_{\bar{p}}\| \neq 0$ is generic.

Non existence for $W_{cnf} = \frac{1}{2} \int |A^\circ|^2$ in General 3-Manifolds

Since S_p^ρ are critical in \mathbb{R}^3 , may expect that small perturbations of small geodesic spheres $S_{p,\rho}$ are critical in manifolds, but

Theorem (M. (J.G.A. '11))

Let (M, g) be a Riemannian manifold. Assume that the traceless Ricci tensor of M at the point \bar{p} is not null:

$$\|S_{\bar{p}}\| \neq 0.$$

Then there exist $\rho_0 > 0$ and $r > 0$ such that for radius $\rho < \rho_0$ and perturbation $w \in C^{4,\alpha}(S^2)$ with $\|w\|_{C^{4,\alpha}(S^2)} < r$, the surfaces $S_{\bar{p},\rho}(w)$ are not critical points of W_{cnf} .

Remark:- The condition $\|S_{\bar{p}}\| \neq 0$ is generic.

- If (M, g) has not constant sectional curvature then there exists at least one point \bar{p} such that $\|S_{\bar{p}}\| \neq 0$.

Minimization of $E = \frac{1}{2} \int |A|^2$ in compact manifolds: global setting

Minimization of $E = \frac{1}{2} \int |A|^2$ in compact manifolds: global setting

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact 3-dimensional Riemannian manifold with strictly positive sectional curvature $\bar{K} > 0$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$$E(f) = \inf\{E(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g)\}.$$

Minimization of $E = \frac{1}{2} \int |A|^2$ in compact manifolds: global setting

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact 3-dimensional Riemannian manifold with strictly positive sectional curvature $\bar{K} > 0$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$$E(f) = \inf\{E(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g)\}.$$

REMARK- By compactness there exists a $\lambda > 0$ such that

$$\bar{K} \geq \lambda > 0. \tag{1}$$

- the theorem is non trivial in the sense that there are examples of compact 3-manifolds with $\bar{K} > 0$ which do not contain totally geodesic immersions; for instance Berger Spheres [Souam-Toubiana (Comm. Math. Helv. '09)]

Sketch of proof-1: Framework

TECHNIQUE: direct methods in the calculus of variations

Sketch of proof-1: Framework

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence

Sketch of proof-1: Framework

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence
- ▶ prove that the minimizing sequence does **not degenerate**

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence
- ▶ prove that the minimizing sequence does **not degenerate**
- ▶ prove **lower semicontinuity** of the functional under weak convergence

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence
- ▶ prove that the minimizing sequence does **not degenerate**
- ▶ prove **lower semicontinuity** of the functional under weak convergence
- ▶ prove **regularity** of the weak limit object

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence
- ▶ prove that the minimizing sequence does **not degenerate**
- ▶ prove **lower semicontinuity** of the functional under weak convergence
- ▶ prove **regularity** of the weak limit object

Enlarged space: take a minimizing sequence of immersions

$$f_k : \mathbb{S}^2 \hookrightarrow M$$

Sketch of proof-1: Framework

TECHNIQUE: direct methods in the calculus of variations

- ▶ enlarge the space for proving **compactness** of the minimizing sequence
- ▶ prove that the minimizing sequence does **not degenerate**
- ▶ prove **lower semicontinuity** of the functional under weak convergence
- ▶ prove **regularity** of the weak limit object

Enlarged space: take a minimizing sequence of immersions

$$f_k : \mathbb{S}^2 \hookrightarrow M$$

associate the **Radon measures**

$$\mu_k : \mu_k(B) := \text{Area}_{(f_k^*g)}(f_k^{-1}(B))'' = \text{Area}(B \cap f_k(\mathbb{S}^2))'' \text{ for every } B \subset M \text{ Borel set}$$

Sketch of proof-2: Compactness

- ▶ By Banach Alaoglu, for having **compactness** of the measures we need a **uniform area bound** on f_k

Sketch of proof-2: Compactness

- ▶ By Banach Alaoglu, for having **compactness** of the measures we need a **uniform area bound** on f_k

Lemma Let (M, g) be a closed 3-dimensional manifold with positive sectional curvature \bar{K} : $\exists \lambda$ such that $\bar{K} > \lambda^2 > 0$. Then, for every smooth immersion $f : \mathbb{S}^2 \hookrightarrow (M, g)$, the following area estimate holds:

$$|f(\mathbb{S}^2)|_g \leq \frac{1}{\lambda^2} (4\pi + E(f)) \quad (2)$$

where $|f(\mathbb{S}^2)|_g := \int_{\mathbb{S}^2} d\mu_g$ is the area of \mathbb{S}^2 equipped with the pull back metric f^*g given by the immersion.

Sketch of proof-2: Compactness

- ▶ By Banach Alaoglu, for having **compactness** of the measures we need a **uniform area bound** on f_k

Lemma Let (M, g) be a closed 3-dimensional manifold with positive sectional curvature \bar{K} : $\exists \lambda$ such that $\bar{K} > \lambda^2 > 0$. Then, for every smooth immersion $f : \mathbb{S}^2 \hookrightarrow (M, g)$, the following area estimate holds:

$$|f(\mathbb{S}^2)|_g \leq \frac{1}{\lambda^2} (4\pi + E(f)) \quad (2)$$

where $|f(\mathbb{S}^2)|_g := \int_{\mathbb{S}^2} d\mu_g$ is the area of \mathbb{S}^2 equipped with the pull back metric f^*g given by the immersion.

Idea of Proof: play with the Gauss equation

$$\bar{K}(T_x f) = K_G - k_1 k_2 = K_G - \frac{1}{4} H^2 + \frac{1}{2} |A^\circ|^2$$

Sketch of the proof-3: nondegeneracy

\Rightarrow there exists a Radon measure μ on M such that $\mu_k \rightarrow \mu$ up to subsequences

Sketch of the proof-3: nondegeneracy

\Rightarrow there exists a Radon measure μ on M such that $\mu_k \rightarrow \mu$ up to subsequences

Problem. The sequence may **degenerate**: f_k may shrink to a point or μ may be 0

Sketch of the proof-3: nondegeneracy

\Rightarrow there exists a Radon measure μ on M such that $\mu_k \rightarrow \mu$ up to subsequences

Problem. The sequence may **degenerate**: f_k may shrink to a point or μ may be 0

Lemma Let (M, g) be a closed Riemannian 3-manifold whose scalar curvature is strictly positive at a point:

$$\exists \bar{p} \in M : R_g(\bar{p}) > 0.$$

Then for a minimizing sequence f_k of E

$$\liminf_k (\text{diam}_g f_k(\mathbb{S}^2)) > 0$$

where $\text{diam}_g f_k(\mathbb{S}^2)$ is the diameter of $f_k(\mathbb{S}^2)$ in the Riemannian manifold (M, g) .

Sketch of the proof-4: Proof of nondegeneracy

- ▶ **IDEA:** Perform a **blow up** procedure.

Sketch of the proof-4: Proof of nondegeneracy

- ▶ **IDEA:** Perform a **blow up** procedure.
- ▶ On small geodesic spheres

$$E(S_{\bar{p},\rho}) = 4\pi - \frac{2\pi}{3}R(\bar{p})\rho^2 + o(\rho^2) < 4\pi$$

for small ρ .

Sketch of the proof-4: Proof of nondegeneracy

- ▶ **IDEA:** Perform a **blow up** procedure.
- ▶ On small geodesic spheres

$$E(S_{\bar{p},\rho}) = 4\pi - \frac{2\pi}{3}R(\bar{p})\rho^2 + o(\rho^2) < 4\pi$$

for small ρ .

$$\Rightarrow 4\pi - \delta > \inf_{f:\mathbb{S}^2 \hookrightarrow (M,g)} E(f) = \lim E(f_k).$$

Sketch of the proof-4: Proof of nondegeneracy

- ▶ **IDEA:** Perform a **blow up** procedure.
- ▶ On small geodesic spheres

$$E(S_{\bar{p},\rho}) = 4\pi - \frac{2\pi}{3}R(\bar{p})\rho^2 + o(\rho^2) < 4\pi$$

for small ρ .

$$\Rightarrow 4\pi - \delta > \inf_{f:\mathbb{S}^2 \hookrightarrow (M,g)} E(f) = \lim E(f_k).$$

- ▶ By Willmore

$$\inf_{f:\mathbb{S}^2 \hookrightarrow \mathbb{R}^3} E(f) = 4\pi$$

Sketch of the proof-4: Proof of nondegeneracy

- ▶ **IDEA:** Perform a **blow up** procedure.
- ▶ On small geodesic spheres

$$E(S_{\bar{p},\rho}) = 4\pi - \frac{2\pi}{3}R(\bar{p})\rho^2 + o(\rho^2) < 4\pi$$

for small ρ .

$$\Rightarrow 4\pi - \delta > \inf_{f:\mathbb{S}^2 \hookrightarrow (M,g)} E(f) = \lim E(f_k).$$

- ▶ By Willmore

$$\inf_{f:\mathbb{S}^2 \hookrightarrow \mathbb{R}^3} E(f) = 4\pi$$

- ▶ \Rightarrow if f_k shrink then blow up

$$\liminf E(f_k) \geq 4\pi$$

Sketch of proof-5: Existence of candidate minimizer

- ▶ \Rightarrow using the curvature assumptions on (M, g) we proved that the **minimizing sequence** is **compact** and does **not degenerate**

Sketch of proof-5: Existence of candidate minimizer

- ▶ \Rightarrow using the curvature assumptions on (M, g) we proved that the **minimizing sequence** is **compact** and does **not degenerate**
- ▶ \Rightarrow there exists a non null limit measure μ (with a weak notion of second fundamental form, by Hutchinson Theory)

Sketch of proof-5: Existence of candidate minimizer

- ▶ \Rightarrow using the curvature assumptions on (M, g) we proved that the **minimizing sequence** is **compact** and does **not degenerate**
- ▶ \Rightarrow there exists a non null limit measure μ (with a weak notion of second fundamental form, by Hutchinson Theory)
- ▶ **FACT:** the functional E is lower semicontinuous (with respect to varifold convergence)

$$\Rightarrow E(\mu) \leq \liminf E(f_k) = \inf E$$

Sketch of proof-5: Existence of candidate minimizer

- ▶ \Rightarrow using the curvature assumptions on (M, g) we proved that the **minimizing sequence** is **compact** and does **not degenerate**
- ▶ \Rightarrow there exists a non null limit measure μ (with a weak notion of second fundamental form, by Hutchinson Theory)
- ▶ **FACT:** the functional E is lower semicontinuous (with respect to varifold convergence)

$$\Rightarrow E(\mu) \leq \liminf E(f_k) = \inf E$$

- ▶ $\Rightarrow \mu$ is a candidate minimizer and we have to **prove regularity** i.e. this measure is associated to a smooth immersion of a sphere

Sketch of proof-6: Regularity

- ▶ Take inspiration from [Simon (CAG '93)] and do a partition of $\text{spt}\mu$ into **good** and **bad points**:

Sketch of proof-6: Regularity

- ▶ Take inspiration from [Simon (CAG '93)] and do a partition of $spt\mu$ into **good** and **bad points**:
- ▶ fixed a small $\epsilon > 0$ we say that $\xi \in spt\mu$ is a **bad point** if

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon^2;$$

the complementary are the **good points**

Sketch of proof-6: Regularity

- ▶ Take inspiration from [Simon (CAG '93)] and do a partition of $spt\mu$ into **good** and **bad points**:
- ▶ fixed a small $\epsilon > 0$ we say that $\xi \in spt\mu$ is a **bad point** if

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon^2;$$

the complementary are the **good points**

- ▶ From energy bound \Rightarrow only **finitely many bad points**

Sketch of proof-7: Graphical Decomposition Lemma

Adapting Simon setting we get Graphical decomposition in Riemannian manifolds:

IDEA: in a neighborhood of a good point, each surface is overlapping of many sheets. Each one is union of a Lipschitz graph (with holes) and small "pimples"

Sketch of proof-8: Towards $C^{1,\alpha}$ regularity

GOAL: prove $C^{1,\alpha}$ regularity near good points

Sketch of proof-8: Towards $C^{1,\alpha}$ regularity

GOAL: prove $C^{1,\alpha}$ regularity near good points

IDEA: use Morrey Lemma

Sketch of proof-8: Towards $C^{1,\alpha}$ regularity

GOAL: prove $C^{1,\alpha}$ regularity near good points

IDEA: use Morrey Lemma

Lemma Let (M, g) , f_k and μ as before. Let ξ_0 a ε_0 -good point for $\varepsilon > 0$ small enough.

Sketch of proof-8: Towards $C^{1,\alpha}$ regularity

GOAL: prove $C^{1,\alpha}$ regularity near good points

IDEA: use Morrey Lemma

Lemma Let (M, g) , f_k and μ as before. Let ξ_0 a ε_0 -good point for $\varepsilon > 0$ small enough.

Then we have for all $\xi \in \text{spt}\mu \cap B_{\frac{\rho_0}{2}}(\xi_0)$ and all $\rho \leq \frac{\rho_0}{4}$ that

$$\liminf_{k \rightarrow \infty} \int_{B_{\frac{\rho}{8}}(\xi)} |A_k|^2 d\mu_k \leq c\rho^\alpha \quad \text{where } c = c(\rho_0) \text{ and } \alpha \in (0, 1).$$

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0
- ▶ replace the pimples with biharmonic graphs

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0
- ▶ replace the pimples with biharmonic graphs
- ▶ get new graph functions \bar{u}_k^l on the planes L^l with uniform bound on Lipschitz (then also $W^{1,2}$) norms

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0
- ▶ replace the pimples with biharmonic graphs
- ▶ get new graph functions \bar{u}'_k on the planes L^l with uniform bound on Lipschitz (then also $W^{1,2}$) norms
- ▶ \Rightarrow there exist $u' \in W^{1,\infty}$ such that

$$\bar{u}'_k \rightarrow u' \text{ in } C^0$$

$$\bar{u}'_k \rightharpoonup u' \text{ in } W^{1,2}$$

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0
- ▶ replace the pimples with biharmonic graphs
- ▶ get new graph functions \bar{u}_k^l on the planes L^l with uniform bound on Lipschitz (then also $W^{1,2}$) norms
- ▶ \Rightarrow there exist $u^l \in W^{1,\infty}$ such that

$$\bar{u}_k^l \rightarrow u^l \text{ in } C^0$$

$$\bar{u}_k^l \rightharpoonup u^l \text{ in } W^{1,2}$$

Lemma: $\mu_{\mathbb{L}} B_\rho(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^{\mathbb{L}}}^2(\text{graph } u^l \cap B_\rho(\xi_0))$.

Sketch of the proof-9: construction of the limit graphs

- ▶ Work locally in a neighborhood of a good point ξ_0
- ▶ replace the pimples with biharmonic graphs
- ▶ get new graph functions \bar{u}_k^l on the planes L^l with uniform bound on Lipschitz (then also $W^{1,2}$) norms
- ▶ \Rightarrow there exist $u^l \in W^{1,\infty}$ such that

$$\bar{u}_k^l \rightarrow u^l \text{ in } C^0$$

$$\bar{u}_k^l \rightharpoonup u^l \text{ in } W^{1,2}$$

Lemma: $\mu_{\perp} B_{\rho}(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^l}^2(\text{graph } u^l \cap B_{\rho}(\xi_0))$.

Proof By Radon Nikodym and a modification of Poincaré inequality by Simon

Sketch of the proof-10: $C^{1,\alpha} \cap W^{2,2}$ regularity near the good points

Sketch of the proof-10: $C^{1,\alpha} \cap W^{2,2}$ regularity near the good points

Lemma

The functions u^l such that

$\mu \llcorner B_\rho(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^\perp}^2(\text{graph } u^l \cap B_\rho(\xi_0))$ are $C^{1,\alpha} \cap W^{2,2}$ and satisfy the power decay

$$\int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha.$$

Sketch of the proof-10: $C^{1,\alpha} \cap W^{2,2}$ regularity near the good points

Lemma

The functions u^l such that

$\mu \llcorner B_\rho(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^\perp}^2(\text{graph } u^l \cap B_\rho(\xi_0))$ are $C^{1,\alpha} \cap W^{2,2}$ and satisfy the power decay

$$\int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha.$$

Proof

- ▶ μ has weak mean curvature in L^2 and $u^l \in W^{1,2}$ are weak solutions of the mean curvature equation $\Rightarrow u^l \in W^{2,2}$

Sketch of the proof-10: $C^{1,\alpha} \cap W^{2,2}$ regularity near the good points

Lemma

The functions u^l such that

$\mu \llcorner B_\rho(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^\perp}^2(\text{graph } u^l \cap B_\rho(\xi_0))$ are $C^{1,\alpha} \cap W^{2,2}$ and satisfy the power decay

$$\int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha.$$

Proof

- ▶ μ has weak mean curvature in L^2 and $u^l \in W^{1,2}$ are weak solutions of the mean curvature equation $\Rightarrow u^l \in W^{2,2}$
- ▶ Power decay of $\int |A|^2 \Rightarrow \int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha$

Sketch of the proof-10: $C^{1,\alpha} \cap W^{2,2}$ regularity near the good points

Lemma

The functions u^l such that

$\mu \llcorner B_\rho(\xi_0) = \sum_{l=1}^M \mathcal{H}_{g^\perp}^2(\text{graph } u^l \cap B_\rho(\xi_0))$ are $C^{1,\alpha} \cap W^{2,2}$ and satisfy the power decay

$$\int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha.$$

Proof

- ▶ μ has weak mean curvature in L^2 and $u^l \in W^{1,2}$ are weak solutions of the mean curvature equation $\Rightarrow u^l \in W^{2,2}$
- ▶ Power decay of $\int |A|^2 \Rightarrow \int_{B_\sigma} |D^2 u^l|^2 \leq C \sigma^\alpha$
- ▶ conclude by Morrey Lemma

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

- ▶ Since the bad points are discrete, in a neighbourhood of ξ_0 there are no other bad points

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

- ▶ Since the bad points are discrete, in a neighbourhood of ξ_0 there are no other bad points
- ▶ Consider an annulus $B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ and perform graphical decomposition there

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

- ▶ Since the bad points are discrete, in a neighbourhood of ξ_0 there are no other bad points
- ▶ Consider an annulus $B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ and perform graphical decomposition there
- ▶ parametrize each "component" of $f_k(\mathbb{S}^2) \cap B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ with graph functions on $[\frac{\rho}{2}, \rho] \times [0, 2\pi\omega_k]$ plus pimples

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

- ▶ Since the bad points are discrete, in a neighbourhood of ξ_0 there are no other bad points
- ▶ Consider an annulus $B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ and perform graphical decomposition there
- ▶ parametrize each "component" of $f_k(\mathbb{S}^2) \cap B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ with graph functions on $[\frac{\rho}{2}, \rho] \times [0, 2\pi\omega_k]$ plus pimples
- ▶ **Problem:** we can have more windings, i.e $\omega_k > 1$

Sketch of the proof-11: Non existence of bad points-a

- ▶ Assume by contradiction there exists a bad point $\xi_0 \in \text{spt}\mu$, then by definition there exists ϵ_0 such that

$$\lim_{\rho \rightarrow 0} \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi, \rho)} |A|^2 > \epsilon_0^2.$$

- ▶ Since the bad points are discrete, in a neighbourhood of ξ_0 there are no other bad points
- ▶ Consider an annulus $B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ and perform graphical decomposition there
- ▶ parametrize each "component" of $f_k(\mathbb{S}^2) \cap B_\rho \setminus B_{\frac{\rho}{2}}(\xi_0)$ with graph functions on $[\frac{\rho}{2}, \rho] \times [0, 2\pi\omega_k]$ plus pimples
- ▶ **Problem:** we can have more windings, i.e $\omega_k > 1 \rightarrow$ branch point in the limit.

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$
 $\Rightarrow \omega_k = 1$ just one winding

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$

$\Rightarrow \omega_k = 1$ just one winding

\Rightarrow we can glue inside $B_\rho(\xi)$ biharmonic graphs and repeat the proof of the power decay of $\int |A|^2$

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$

$\Rightarrow \omega_k = 1$ just one winding

\Rightarrow we can glue inside $B_\rho(\xi)$ biharmonic graphs and repeat the proof of the power decay of $\int |A|^2$

$\Rightarrow \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi_0, \rho)} |A|^2 \leq c\rho^\alpha$

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$

$\Rightarrow \omega_k = 1$ just one winding

\Rightarrow we can glue inside $B_\rho(\xi)$ biharmonic graphs and repeat the proof of the power decay of $\int |A|^2$

$\Rightarrow \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi_0, \rho)} |A|^2 \leq c\rho^\alpha$

\Rightarrow contradiction with definition of bad point

Sketch of the proof-11: Non existence of bad points-b

Lemma If there exists $\delta > 0$ such that $\frac{1}{2} \int_{f_k} |A_k|^2 \leq 4\pi - \delta$ then the number of windings $\omega_k = 1$

Proof Topological argument using Gauss Bonnet

By curvature conditions we know that $\lim E(f_k) < 4\pi$

$\Rightarrow \omega_k = 1$ just one winding

\Rightarrow we can glue inside $B_\rho(\xi)$ biharmonic graphs and repeat the proof of the power decay of $\int |A|^2$

$\Rightarrow \liminf_{k \rightarrow \infty} \int_{f_k(\mathbb{S}^2) \cap B(\xi_0, \rho)} |A|^2 \leq c\rho^\alpha$

\Rightarrow contradiction with definition of bad point

Sketch of the proof-12:smoothness

\Rightarrow local $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

Sketch of the proof-12:smoothness

⇒ **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

globally? How do the graphs match together?

Sketch of the proof-12:smoothness

⇒ **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

GLOBALLY? How do the graphs match together?

Simple: there exists an abstract smooth surface Σ parametrizing μ

Sketch of the proof-12:smoothness

\Rightarrow **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

GLOBALLY? How do the graphs match together?

Simple: there exists an abstract smooth surface Σ parametrizing μ

Difficoult: is $\Sigma = \mathbb{S}^2$?

Sketch of the proof-12:smoothness

⇒ **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

GLOBALLY? How do the graphs match together?

Simple: there exists an abstract smooth surface Σ parametrizing μ

Difficult: is $\Sigma = \mathbb{S}^2$?

YES! by a compactness theorem of Breuning (2011) generalizing the compactness of Langer

Sketch of the proof-12:smoothness

⇒ **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

GLOBALLY? How do the graphs match together?

Simple: there exists an abstract smooth surface Σ parametrizing μ

Difficult: is $\Sigma = \mathbb{S}^2$?

YES! by a compactness theorem of Breuning (2011) generalizing the compactness of Langer

⇒ μ is $C^{1,\alpha} \cap W^{2,2}$ parametrized on \mathbb{S}^2 and is extremal for E

Sketch of the proof-12:smoothness

⇒ **local** $C^{1,\alpha} \cap W^{2,2}$ regularity everywhere

GLOBALLY? How do the graphs match together?

Simple: there exists an abstract smooth surface Σ parametrizing μ

Difficult: is $\Sigma = \mathbb{S}^2$?

YES! by a compactness theorem of Breuning (2011) generalizing the compactness of Langer

⇒ μ is $C^{1,\alpha} \cap W^{2,2}$ parametrized on \mathbb{S}^2 and is extremal for E

⇒ equation+bootstrap gives the smoothness of the immersion

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact Riemannian 3-manifold with sectional curvature $K^M \leq 2$ and scalar curvature $R^M(\bar{x}) > 6$ for some point $\bar{x} \in M$.

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact Riemannian 3-manifold with sectional curvature $K^M \leq 2$ and scalar curvature $R^M(\bar{x}) > 6$ for some point $\bar{x} \in M$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$W_1(f) = \inf \{ W_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g) \}$.

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact Riemannian 3-manifold with sectional curvature $K^M \leq 2$ and scalar curvature $R^M(\bar{x}) > 6$ for some point $\bar{x} \in M$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$W_1(f) = \inf \{ W_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g) \}$.

REMARK- the curvature conditions can be fulfilled, for instance they hold for a round sphere $\mathbb{S}^3(R)$ if $\frac{1}{\sqrt{2}} \leq R < 1$,

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact Riemannian 3-manifold with sectional curvature $K^M \leq 2$ and scalar curvature $R^M(\bar{x}) > 6$ for some point $\bar{x} \in M$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$W_1(f) = \inf \{ W_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g) \}$.

REMARK- the curvature conditions can be fulfilled, for instance they hold for a round sphere $\mathbb{S}^3(R)$ if $\frac{1}{\sqrt{2}} \leq R < 1$,
-the condition on the scalar curvature implies that $\inf W_1 < 4\pi$ so the minimizing sequence does not shrink to a point,

Minimization of $W_1 = \int \left(\frac{|H|^2}{4} + 1 \right)$ in compact manifolds

Theorem (Kuwert- M.- Schygulla '11)

Let (M, g) be a compact Riemannian 3-manifold with sectional curvature $K^M \leq 2$ and scalar curvature $R^M(\bar{x}) > 6$ for some point $\bar{x} \in M$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$$W_1(f) = \inf \{ W_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g) \}.$$

REMARK- the curvature conditions can be fulfilled, for instance they hold for a round sphere $\mathbb{S}^3(R)$ if $\frac{1}{\sqrt{2}} \leq R < 1$,
-the condition on the scalar curvature implies that $\inf W_1 < 4\pi$ so the minimizing sequence does not shrink to a point,
-the condition on the sectional curvature implies by Gauss equations that $\frac{1}{2} \int |A|^2 < 4\pi$ on the minimizing sequence, so it prevents branch points in the limit

Minimization of Willmore type functionals in NONCOMPACT manifolds

Minimization of Willmore type functionals in NONCOMPACT manifolds

PROBLEMS: the minimizing sequences

- a) may become **larger and larger** in area and diameter
- b) may **escape to infinity**

Minimization of Willmore type functionals in NONCOMPACT manifolds

PROBLEMS: the minimizing sequences

- a) may become **larger and larger** in area and diameter
- b) may **escape to infinity**

FUNCTIONALS of Willmore type : $E_1 := \int \left(\frac{|A|^2}{2} + 1 \right)$ and

$$W_1 := \int \left(\frac{|H|^2}{4} + 1 \right)$$

Minimization of Willmore type functionals in NONCOMPACT manifolds

PROBLEMS: the minimizing sequences

- a) may become **larger and larger** in area and diameter
- b) may **escape to infinity**

FUNCTIONALS of Willmore type : $E_1 := \int \left(\frac{|A|^2}{2} + 1 \right)$ and
 $W_1 := \int \left(\frac{|H|^2}{4} + 1 \right)$

+1 \rightarrow Area bound on the minimizing sequences \rightarrow also diameter bound (by the monotonicity formula) \rightarrow **a) is solved** by the choice of the functionals

Minimization of Willmore type functionals in NONCOMPACT manifolds

PROBLEMS: the minimizing sequences

- a) may become **larger and larger** in area and diameter
- b) may **escape to infinity**

FUNCTIONALS of Willmore type : $E_1 := \int \left(\frac{|A|^2}{2} + 1 \right)$ and
 $W_1 := \int \left(\frac{|H|^2}{4} + 1 \right)$

+1 \rightarrow Area bound on the minimizing sequences \rightarrow also diameter bound (by the monotonicity formula) \rightarrow **a) is solved** by the choice of the functionals

b) is solved by the choice of the manifold: positive curvature in some point at finite + asymptotically euclidean or hyperbolic

Asymptotic conditions

1) (M, g) is said **asymptotically euclidean** if there exist compact subsets $\Omega_1 \subset\subset M$ and $\Omega_2 \subset\subset \mathbb{R}^3$ such that

$(M \setminus \Omega_1)$ is isometric to $(\mathbb{R}^3 \setminus \Omega_2, eucl + o_1(1))$,

Asymptotic conditions

1) (M, g) is said **asymptotically euclidean** if there exist compact subsets $\Omega_1 \subset\subset M$ and $\Omega_2 \subset\subset \mathbb{R}^3$ such that

$$(M \setminus \Omega_1) \text{ is isometric to } (\mathbb{R}^3 \setminus \Omega_2, \text{eucl} + o_1(1)), \quad (3)$$

where $o_1(1)$ denotes a symmetric bilinear form which goes to 0 with its first derivatives at infinity,

$$\lim_{|x| \rightarrow \infty} (|o_1(1)(x)| + |\nabla o_1(1)(x)|) = 0.$$

Asymptotic conditions

1) (M, g) is said **asymptotically euclidean** if there exist compact subsets $\Omega_1 \subset\subset M$ and $\Omega_2 \subset\subset \mathbb{R}^3$ such that

$$(M \setminus \Omega_1) \text{ is isometric to } (\mathbb{R}^3 \setminus \Omega_2, \text{eucl} + o_1(1)), \quad (3)$$

where $o_1(1)$ denotes a symmetric bilinear form which goes to 0 with its first derivatives at infinity,

$$\lim_{|x| \rightarrow \infty} (|o_1(1)(x)| + |\nabla o_1(1)(x)|) = 0.$$

2) (M, g) is said **hyperbolic outside a compact subset** if there exists $\Omega \subset\subset M$ such that the sectional curvature $K^M \leq 0$ on $M \setminus \Omega$.

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

*ii) there exists a point \bar{p} where the **scalar curvature** is $R(\bar{p}) > 6$,*

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

ii) there exists a point \bar{p} where the *scalar curvature* is $R(\bar{p}) > 6$,

iii) the *sectional curvature* \bar{K} of (M, g) is $\bar{K} \leq 2$.

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

ii) there exists a point \bar{p} where the *scalar curvature* is $R(\bar{p}) > 6$,

iii) the *sectional curvature* \bar{K} of (M, g) is $\bar{K} \leq 2$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$$W_1(f) = \inf \{ W_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g) \}.$$

Minimization of E_1

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

ii) there exists a point \bar{p} where the scalar curvature is strictly greater than 6, $R(\bar{p}) > 6$.

Theorem (M.-Schygulla '11)

Let (M, g) be a 3-dimensional non compact Riemannian manifold with bounded geometry such that:

i) (M, g) is asymptotically euclidean or hyperbolic outside a compact subset

ii) there exists a point \bar{p} where the scalar curvature is strictly greater than 6, $R(\bar{p}) > 6$.

Then there exists a smooth immersion $f : \mathbb{S}^2 \hookrightarrow M$ such that

$$E_1(f) = \inf\{E_1(h) \mid h : \mathbb{S}^2 \hookrightarrow (M, g) \text{ is a } C^\infty \text{ immersion in } (M, g)\}.$$

Remarks on asymptotic conditions

Remarks on asymptotic conditions

1) the asymptotically euclidean condition is very mild: just C^1 closeness to euclidean metric, so the curvature may not vanish at infinity

Remarks on asymptotic conditions

- 1) the asymptotically euclidean condition is very mild: just C^1 closeness to euclidean metric, so the curvature may not vanish at infinity
- 2) asymptotically spatial Schwarzschild 3-manifolds with mass or the metric of the positive mass theorem of Schoen-Yau fit in our asymptotically euclidean assumption

Remarks on asymptotic conditions

- 1) the asymptotically euclidean condition is very mild: just C^1 closeness to euclidean metric, so the curvature may not vanish at infinity
- 2) asymptotically spatial Schwarzschild 3-manifolds with mass or the metric of the positive mass theorem of Schoen-Yau fit in our asymptotically euclidean assumption ← spacelike timeslices of solutions to the Einstein vacuum equation, **null** cosmological constant

Remarks on asymptotic conditions

- 1) the asymptotically euclidean condition is very mild: just C^1 closeness to euclidean metric, so the curvature may not vanish at infinity
- 2) asymptotically spatial Schwarzschild 3-manifolds with mass or the metric of the positive mass theorem of Schoen-Yau fit in our asymptotically euclidean assumption ← spacelike timeslices of solutions to the Einstein vacuum equation, **null** cosmological constant
- 3) asymptotic Anti-de Sitter-Schwarzschild metrics with mass (considered for instance by Neves and Tian) are hyperbolic outside a compact subset

Remarks on asymptotic conditions

- 1) the asymptotically euclidean condition is very mild: just C^1 closeness to euclidean metric, so the curvature may not vanish at infinity
- 2) asymptotically spatial Schwarzschild 3-manifolds with mass or the metric of the positive mass theorem of Schoen-Yau fit in our asymptotically euclidean assumption \leftarrow spacelike timeslices of solutions to the Einstein vacuum equation, **null** cosmological constant
- 3) asymptotic Anti-de Sitter-Schwarzschild metrics with mass (considered for instance by Neves and Tian) are hyperbolic outside a compact subset \leftarrow spacelike timeslices of solutions to the Einstein vacuum equation, **negative** cosmological constant

Minimization of $\int |H|^p$ and $\int |A|^p$, $p > 2$

Minimization of $\int |H|^p$ and $\int |A|^p$, $p > 2$

PROBLEM: given (M, g) a 3-d Riemannian manifold, do exist surfaces minimizing $\int |H|^p$ or $\int |A|^p$, $p > 2$?

Minimization of $\int |H|^p$ and $\int |A|^p$, $p > 2$

PROBLEM: given (M, g) a 3-d Riemannian manifold, do exist surfaces minimizing $\int |H|^p$ or $\int |A|^p$, $p > 2$?

TECHNIQUE: Geometric measure theory (varifolds: "generalized surfaces")

Minimization of $\int |H|^p$ and $\int |A|^p$, $p > 2$

PROBLEM: given (M, g) a 3-d Riemannian manifold, do exist surfaces minimizing $\int |H|^p$ or $\int |A|^p$, $p > 2$?

TECHNIQUE: Geometric measure theory (varifolds: "generalized surfaces")

RESULT[M. (ArXiv'10)]: if (M, g) is compact + other technical conditions (ex: $M =$ closure of a bounded open in \mathbb{R}^3) then there exists a "generalized surface" minimizing $\int |H|^p$ (or $\int |A|^p$), $p > 2$.

Minimization of $\int |H|^p$ and $\int |A|^p$, $p > 2$

PROBLEM: given (M, g) a 3-d Riemannian manifold, do exist surfaces minimizing $\int |H|^p$ or $\int |A|^p$, $p > 2$?

TECHNIQUE: Geometric measure theory (varifolds: "generalized surfaces")

RESULT[M. (ArXiv'10)]: if (M, g) is compact + other technical conditions (ex: $M =$ closure of a bounded open in \mathbb{R}^3) then there exists a "generalized surface" minimizing $\int |H|^p$ (or $\int |A|^p$), $p > 2$.

REMARK: proved in any dimension and codimension.

Fix $p > 2$. NEW TOOLS

Fix $p > 2$. **NEW TOOLS:1) isoperimetric inequalities.** If (M, g) is compact and does not contain "generalized minimal surfaces" (resp. "generalized totally geodesic surfaces") then $\exists C > 0$ such that for every generalized surface $\Sigma \subset M$

$$\text{Area}(\Sigma) \leq C \int |H|^p \text{ (resp. } \leq C \int |A|^p \text{)}$$

Fix $p > 2$. **NEW TOOLS:1) isoperimetric inequalities.** If (M, g) is compact and does not contain "generalized minimal surfaces" (resp. "generalized totally geodesic surfaces") then $\exists C > 0$ such that for every generalized surface $\Sigma \subset M$

$$\text{Area}(\Sigma) \leq C \int |H|^p \quad (\text{resp. } \leq C \int |A|^p)$$

2) **Monotonicity formula.** Let $\Sigma \subset \mathbb{R}^n$ be a generalized surface. Fixed a point $x_0 \in \Sigma$ and $0 < \sigma < \rho < \infty$

$$\left[\frac{\text{Area}(\Sigma \cap B_\sigma(x_0))}{\sigma^2} \right]^{\frac{1}{p}} \leq \left[\frac{\text{Area}(\Sigma \cap B_\rho(x_0))}{\rho^2} \right]^{\frac{1}{p}} + \frac{\rho^2}{p-2} \rho^{1-\frac{2}{p}} \left[\int_{B_\rho(x_0) \cap \Sigma} |H|^p \right]^{\frac{1}{p}}.$$

Fix $p > 2$. **NEW TOOLS:1) isoperimetric inequalities.** If (M, g) is compact and does not contain "generalized minimal surfaces" (resp. "generalized totally geodesic surfaces") then $\exists C > 0$ such that for every generalized surface $\Sigma \subset M$

$$\text{Area}(\Sigma) \leq C \int |H|^p \quad (\text{resp. } \leq C \int |A|^p)$$

2) **Monotonicity formula.** Let $\Sigma \subset \mathbb{R}^n$ be a generalized surface. Fixed a point $x_0 \in \Sigma$ and $0 < \sigma < \rho < \infty$

$$\left[\frac{\text{Area}(\Sigma \cap B_\sigma(x_0))}{\sigma^2} \right]^{\frac{1}{p}} \leq \left[\frac{\text{Area}(\Sigma \cap B_\rho(x_0))}{\rho^2} \right]^{\frac{1}{p}} + \frac{\rho^2}{p-2} \rho^{1-\frac{2}{p}} \left[\int_{B_\rho(x_0) \cap \Sigma} |H|^p \right]^{\frac{1}{p}}.$$

$$\Rightarrow \text{diam}(\Sigma) \geq \frac{1}{C \left(\int_\Sigma |H|^p \right)^{\frac{1}{p-m}}}, \quad \text{Area}(\Sigma) \geq \frac{1}{C \left(\int_\Sigma |H|^p \right)^{\frac{m}{p-m}}}$$

- ▶ A. Mondino, *Some results about the existence of critical points for the Willmore functional*, Math. Zeit., Vol. 266, Num. 3, (2010), 583-622.
- ▶ A. Mondino, *The conformal Willmore Functional: a perturbative approach*, to appear in JGA (2011).
- ▶ A. Mondino, *Existence of Integral m -Varifolds minimizing $\int |A|^p$ and $\int |H|^p$ in Riemannian Manifolds*, arXiv:1010.4514, submitted, (2010).
- ▶ E. Kuwert, A. Mondino, J. Schygulla *Existence of immersed spheres minimizing curvature functionals in compact 3-manifolds*, ArXiv: 1111.4893, submitted (2011).
- ▶ A. Mondino, J. Schygulla *Existence of immersed spheres minimizing curvature functionals in noncompact 3-manifolds*, submitted (2012)

!!THANK YOU FOR THE
ATTENTION!!