Genus-g Helicoids

Brian White (joint work with David Hoffman and Martin Traizet)

June 18, 2013 (Granada)

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First, I will prove a special, very concrete case of our results about ${\bm S}^2 \times {\bm R}.$

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Then I will indicate how exactly the same proof gives a more general result.

The boundary curve **F**



This curve Γ lies on the boundary $X \times \mathbf{R}$ of a solid cylinder. (Here X is a great circle in \mathbf{S}^2 .) It consists of the great circle X (at height 0), two vertical segments passing through a pair of diametrically opposite points O and O* on X, and two horizontal great semicircles at heights h and -h.

The boundary curve **F**



The curve Γ has many symmetries, including reflection μ in a totally geodesic cylinder that switches O and O^* . Throughout this talk, all objects (surfaces, jacobi fields, etc) are required to have all of those symmetries.

To show: Γ bounds many embedded minimal surfaces inside the solid cylinder.

Note: in today's talk, all surfaces are embedded. Thus "surface" means "embedded surface having all the symmetries of Γ ".

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Suppose Γ is "bumpy", i.e., bounds no minimal surfaces (inside the cylinder) with nontrivial jacobi fields. Let k be an even integer ≤ 2 . Then Γ bounds:

• an odd number of positive minimal surfaces (inside the cylinder) with Euler characteristic k, and

• an odd number of negative minimal surfaces (inside the cylinder) with Euler characteristic k.

Corollary

Without assuming "bumpiness", the theorem remains true with "an odd number of" replaced by "at least one".

Remark: Repeated Schwarz reflection gives complete, properly embedded minimal surfaces (without boundary) in $S^2 \times R$.

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Positive and negative surfaces

In a neighborhood of O, the curve Γ divides the cylinder $X \times \mathbf{R}$ into four quadrants. We call two of the (non-adjacent) quadrants "positive" and the other two "negative":



A surface M (in the solid cylinder) with boundary Γ is called positive it is tangent to the positive quadrants at O, and negative if it is tangent to the negative quadrants at $O_{n+1} = 0$

Let $N \approx \mathbf{B}^3$ be a mean convex, compact Riemannian 3-manifold that contains no closed minimal surfaces. Let C be a smooth, simple closed curve in ∂N . Suppose C is bumpy. Then C bounds • an odd number of embedded minimal disks, and • an even number of embedded surfaces of each other topological type.

(cf. Tomi and Tromba (1978): disks in \mathbb{R}^3 .)

David and I generalized this theorem to N with piecewise smooth boundary, and to curves and surfaces invariant under a group of symmetries of N.

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(cf. Tomi and Tromba (1978): disks in R³.)

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Proof of main theorem

Let $\Gamma(t)$ be obtained from Γ by rounding the corners (as illustrated) to make it embedded. Here $\Gamma(t) \rightarrow \Gamma$ as $t \rightarrow 0$.



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Let S(t) be a one-parameter family of minimal surfaces with $\partial S(t) = \Gamma(t)$.

Then as $t \to 0$, S(t) converges to a surface S bounded by Γ .

Question

How are the topologies (i.e, Euler characteristics) of S and S(t) related?

(Note: here S denotes the open surface: $S = \overline{S} \setminus \Gamma$.)

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(Note: here S denotes the open surface: $S = \overline{S} \setminus \Gamma$.)

How are the Euler characteristics of S and S(t) related?

It depends on the sign of *S*:

If S is negative, then S and S(t) are homeomorphic, so $\chi(S) = \chi(S(t))$.

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In the case k = 2, this becomes:

Recall

Claim

For small t,

#(minimal surfaces bounded by $\Gamma(t)$ with $\chi = k$)

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The first number is odd (by the Hoffman-White counting theorem). Also, F(4, +) = 0 (trivially). So F(2, -) is odd. Similarly for F(2, +).

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In the preceding argument, the cylinder in $S^2 \times R$ can be replaced by any helicoid H in $S^2 \times R$.

The argument above shows that the curve Γ bounds positive and negative embedded minimal surfaces S (lying on one side of H) of each Euler characteristic ≤ 2 . Reflecting in Z (or equivalently Z^*) gives a surface M bounded by two horizontal great circles, at heights $\pm h$.

Letting $h \to \infty$ gives a properly embedded minimal surface M^* such that

$$M^* \cap H = X \cup Z \cup Z^*.$$

In this way, for each helicoid H, each sign \pm , and each even genus g, we get at least one M^* with the specified sign and genus.

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When taking limits (as in Martin's talk tomorrow), it is important for us to have the handles lined up along the *y*-axis, i.e., that the surfaces we produce be "*Y*-surfaces" (as defined in David's talk yesterday).

The inductive argument above works equally well if we restrict ourselves to Y-surfaces.

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Let M_i be a sequence of minimal surfaces in a Riemannian manifold Ω . Let Z be the area blowup set: Z is the set of points p such that

 $\limsup \operatorname{area}(M_i \cap \mathbf{B}(p, r)) = \infty \qquad \text{for every } r > 0.$

Theorem (W)

Suppose the boundaries ∂M_i have locally uniformly bounded length:

 $\sup \mathsf{length}(U \cap \partial M_i) < \infty$ for $U \subset \subset \Omega$.

Then Z obeys the same maximum principles that hold for properly embedded minimal surfaces without boundary.

In particular, if Z lies on one side of a connected minimal surface M and if Z and M touch at a point, then Z contains M.

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Corollary (Halfspace Theorem)

Suppose $\Omega = \mathbf{R}^3$ and that Z is contained in a half space. Suppose also that Z contains no plane. Then $Z = \emptyset$.

The corollary follows from the theorem because the Hoffman-Meeks proof of their halfspace theorem only uses the maximum principle, and hence the same proof works for area blowup sets Z.

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Here is one example of how we use the area blowup theorem.

When we take a limit M (as sets) of genus g helicoids M_i in $\mathbf{S}^2(R) \times \mathbf{R}$ as $R \to \infty$, we first show that M converges nicely outside of some (possibly very large) solid cylinder C about the *z*-axis. Thus the area blowup set Z lies in the solid cylinder C.

Now *C* is contained in a halfspace and does not contain a plane, so the same is true for the blowup set *Z*. But now by the halfspace theorem, *Z* must be empty.

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Now C is contained in a halfspace and does not contain a plane, so the same is true for the blowup set Z. But now by the halfspace theorem, Z must be empty.

Alternatively, one can argue as follows. Let Σ be a catenoid whose axis is the *z*-axis and that is disjoint from *C*. If the area blowup set *Z* were nonempty, we could shrink Σ until it just touched *Z*, violating the maximum principle. Hence *Z* is empty.