# Análisis geométrico de la distancia lorentziana en subvariedades marginalmente atrapadas 

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Este trabajo ha sido parcialmente financiado por el proyecto MTM2012-34037, MICINN/FEDER, España

Seminario de Geometría IEMath - Granada
23 de octubre de 2015

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- Obviously, $p \ll q$ implies $p<q$. As usual, $p \leq q$ means that either $p<q$ or $p=q$.
- For a subset $S \subset M$, one defines the chronological future of $S$ as

$$
I^{+}(S)=\{q \in M: p \ll q \text { for some } p \in S\}
$$

and the causal future of $S$ as

$$
J^{+}(S)=\{q \in M: p \leq q \text { for some } p \in S\}
$$

Thus $S \cup I^{+}(S) \subset J^{+}(S)$.

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- The Lorentzian distance function $d: M \times M \rightarrow[0,+\infty]$ for an arbitrary spacetime may fail to be continuous in general, and may also fail to be finite valued.
- As a matter of fact, globally hyperbolic spacetimes ${ }^{1}$ turn out to be the natural class of spacetimes for which the Lorentzian distance function is finite-valued and continuous.

[^0]
## Lorentzian distance function from a point

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- Let $\left.T_{-1} M\right|_{p}$ be the fiber of the unit future observer bundle of $M$ at $p$, that is,
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- Define the function $s_{p}:\left.T_{-1} M\right|_{p} \rightarrow[0,+\infty]$ by

$$
s_{p}(v)=\sup \left\{t \geq 0: d_{p}\left(\gamma_{v}(t)\right)=t\right\}
$$

where $\gamma_{v}:[0, a) \rightarrow M$ is the future inextendible geodesic starting at $p$ with initial velocity $v$.

## Lorentzian distance function from a point

- Then, one can define the subset $\tilde{\mathcal{I}}^{+}(p) \subset T_{p} M$ given by

$$
\tilde{\mathcal{I}}^{+}(p)=\left\{t v: \text { for all }\left.v \in T_{-1} M\right|_{p} \text { and } 0<t<s_{p}(v)\right\}
$$

and consider the subset $\mathcal{I}^{+}(p) \subset M$ given by

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## Lemma 1 (Erkekoglu, García-Río and Kupeli, 2003)

Let $M$ be a spacetime and $p \in M$.
(1) If $M$ is strongly causal at $p^{a}$, then $s_{p}(v)>0$ for all $\left.v \in T_{-1} M\right|_{p}$ and $\mathcal{I}^{+}(p) \neq \emptyset$.
(2) If $\mathcal{I}^{+}(p) \neq \emptyset$, then the Lorentzian distance function $d_{p}$ is smooth on $\mathcal{I}^{+}(p)$ and its gradient $\bar{\nabla} d_{p}$ is a past-directed timelike (geodesic) unit vector field on $\mathcal{I}^{+}(p)$.
${ }^{a}$ Given any neighborhood $U$ of $p$ there is a neighborhood $V \subset U$ of $p$ such that every causal curve segment with endpoints in $V$ is entirely contained in $U$.

## Hessian comparison results for the Lorentzian distance

- For every $c \in \mathbb{R}$, let us define

$$
h_{c}(t)=\left\{\begin{array}{cl}
\frac{1}{\sqrt{c}} \sinh (\sqrt{c} t) & \text { if } c>0 \text { and } t>0 \\
t & \text { if } c=0 \text { and } t>0 \\
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- Observe that the index of a Jacobi field along a timelike geodesic in a Lorentzian space form of constant curvature $c$ is given by

$$
I_{\gamma_{c}}\left(J_{c}, J_{c}\right)=-\frac{h_{c}^{\prime}(t)}{h_{c}(t)}\langle x, x\rangle .
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- On the other hand, $\frac{h_{c}^{\prime}(t)}{h_{c}(t)}$ is the future mean curvature of the level set

$$
\Sigma_{c}(t)=\left\{q \in \mathcal{I}^{+}(p): d_{p}(q)=t\right\} \subset M_{c}^{n} .
$$

## Hessian comparison results for the Lorentzian distance

## Lemma 2 (Alías, Hurtado, Palmer, 2010)

Let $M$ be a spacetime such that $K_{M}(\Pi) \geq c, c \in \mathbb{R}$, for all timelike planes in $M$. Assume that there exists a point $p \in M$ such that $\mathcal{I}^{+}(p) \neq \emptyset$, and let $q \in \mathcal{I}^{+}(p)$ (with $d_{p}(q)<\pi / \sqrt{-c}$ when $\left.c<0\right)$. Then for every spacelike vector $x \in T_{q} M$ orthogonal to $\bar{\nabla} d_{p}(q)$

$$
\bar{\nabla}^{2} d_{p}(x, x) \leq-\frac{h_{c}^{\prime}}{h_{c}}\left(d_{p}(q)\right)\langle x, x\rangle,
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- The proof of Lemma 2 follows from the fact that

$$
\bar{\nabla}^{2} d_{p}(x, x)=I_{\gamma}(J, J)
$$

where $\gamma$ is the radial future directed unit timelike geodesic from $p$ to $q$ and $J$ is the Jacobi field along $\gamma$ with $J(0)=0$ and $J(s)=x$, and is strongly based on the maximality of the index of Jacobi fields.

## Hessian comparison results for the Lorentzian distance

- On the other hand, under the assumption that the sectional curvatures of the timelike planes of $M$ are bounded from above by a constant $c$, we get the following result.


## Lemma 3 (Alías, Hurtado, Palmer, 2010)

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\bar{\nabla}^{2} d_{p}(x, x) \geq-\frac{h_{c}^{\prime}}{h_{c}}\left(d_{p}(q)\right)\langle x, x\rangle,
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- The proof is similar to that of Lemma 2.


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- Let $r=d_{p}$ denote the Lorentzian distance function with respect to $p$, and let $u=r \circ \psi: \Sigma \rightarrow(0, \infty)$ be the function $r$ along the submanifold, which is a smooth function on $\Sigma$.


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- Our first objective is to compute the Hessian of $u$. To do that, observe that

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\bar{\nabla} r=\nabla u+(\bar{\nabla} r)^{\perp}
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along $\Sigma$, where $\nabla u=(\bar{\nabla} r)^{\top}$ stands for the gradient of $u$ on $\Sigma$ and $(\bar{\nabla} r)^{\perp}$ denotes the normal component of $\bar{\nabla} r$.

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- By Gauss and Weingarten formulae we get

$$
\bar{\nabla}_{x} \bar{\nabla} r=\nabla_{x} \nabla u-A_{\left(\nabla_{r}\right)^{\perp}} X+\mathrm{II}(X, \nabla u)+\nabla \frac{1}{X}(\bar{\nabla} r)^{\perp},
$$

for every tangent vector $X \in T \Sigma$, where II denotes the second fundamental form of the submanifold and, for every normal vector $\eta$, $A_{\eta}$ denotes the Weingarten endomorphism with respect to $\eta$.

- It follows from here that

$$
\nabla^{2} u(X, Y)=\bar{\nabla}^{2} r(X, Y)+\langle\mathrm{II}(X, Y), \bar{\nabla} r\rangle
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- Tracing this expression, one gets that the Laplacian of $u$ is given by

$$
\Delta u=\sum_{i=1}^{m} \bar{\nabla}^{2} r\left(E_{i}, E_{i}\right)+m\langle\mathbf{H}, \bar{\nabla} r\rangle,
$$

where $\left\{E_{1}, \ldots, E_{m}\right\}$ is a local orthonormal frame on $\Sigma$, and

$$
\mathbf{H}:=\frac{1}{m} \operatorname{tr}(\mathrm{II})=\frac{1}{m} \sum_{i=1}^{m} \mathrm{II}\left(E_{i}, E_{i}\right)
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- Consider the function $v=\phi_{c}(u)$, where $\phi_{c}(t)$ is a primitive of $h_{c}(t)$ :

$$
\phi_{c}(t)=\left\{\begin{array}{cl}
\frac{1}{c} \cosh (\sqrt{c} t) & \text { if } c>0 \text { and } t>0 \\
\frac{t^{2}}{2} & \text { if } c=0 \text { and } t>0 \\
\frac{1}{c} \cos (\sqrt{-c} t) & \text { if } c<0 \text { and } 0<t<\pi / \sqrt{-c} .
\end{array}\right.
$$

- Then, the Laplacian of $v$ is given by

$$
\begin{aligned}
\Delta v & =\phi_{c}^{\prime}(u) \Delta u+\phi_{c}^{\prime \prime}(u)|\nabla u|^{2} \\
& =h_{c}(u) \sum_{i=1}^{m} \bar{\nabla}^{2} r\left(E_{i}, E_{i}\right)+m h_{c}(u)\langle\mathbf{H}, \bar{\nabla} r\rangle+h_{c}^{\prime}(u)|\nabla u|^{2} .
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\end{aligned}
$$

- Assume now that $K_{M}(\Pi) \geq c$ (resp. $\left.K_{M}(\Pi) \leq c\right)$ for all timelike planes in $M$. Then by the Hessian comparison results for $r$ given in Lemma 2 (resp. Lemma 3), one gets that

$$
\bar{\nabla}^{2} r(X, X) \leq(\geq)-\frac{h_{c}^{\prime}}{h_{c}}(u)\left(1+\langle X, \nabla u\rangle^{2}\right)
$$

for every unit tangent vector field $X \in T \Sigma$.

- Then, the Laplacian of $v$ is given by

$$
\begin{aligned}
\Delta v & =\phi_{c}^{\prime}(u) \Delta u+\phi_{c}^{\prime \prime}(u)|\nabla u|^{2} \\
& =h_{c}(u) \sum_{i=1}^{m} \bar{\nabla}^{2} r\left(E_{i}, E_{i}\right)+m h_{c}(u)\langle\mathbf{H}, \bar{\nabla} r\rangle+h_{c}^{\prime}(u)|\nabla u|^{2} .
\end{aligned}
$$

- Assume now that $K_{M}(\Pi) \geq c$ (resp. $\left.K_{M}(\Pi) \leq c\right)$ for all timelike planes in $M$. Then by the Hessian comparison results for $r$ given in Lemma 2 (resp. Lemma 3), one gets that

$$
\bar{\nabla}^{2} r(X, X) \leq(\geq)-\frac{h_{c}^{\prime}}{h_{c}}(u)\left(1+\langle X, \nabla u\rangle^{2}\right)
$$

for every unit tangent vector field $X \in T \Sigma$.

- Therefore,

$$
h_{c}(u) \sum_{i=1}^{m} \bar{\nabla}^{2} r\left(E_{i}, E_{i}\right) \leq(\geq)-h_{c}^{\prime}(u)\left(m+|\nabla u|^{2}\right),
$$

which, jointly with the expression above, gives the following inequality for the Laplacian of $v$

$$
\Delta v \leq(\geq)-m h_{c}^{\prime}(u)+m h_{c}(u)\langle\mathbf{H}, \bar{\nabla} r\rangle .
$$

- Summarizing:
- $K_{M}(\Pi) \geq c$ implies that

$$
\Delta v \leq-m h_{c}^{\prime}(u)+m h_{c}(u)\langle\mathbf{H}, \bar{\nabla} r\rangle
$$

- $K_{M}(\Pi) \leq c$ implies that

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where $v=\phi_{c}(u)$ and $u$ is the Lorentzian distance function of $M$ restricted on the spacelike submanifold $\Sigma$.

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- Before stating our main results, we need to introduce some terminology about:
- Our analytical tool: the weak maximum principle.
- Our geometric objects: trapped submanifolds.
- Following the terminology introduced by Pigola, Rigoli and Setti (2005), the Omori-Yau maximum principle is said to hold on an $n$-dimensional Riemannian manifold $\Sigma$ if, for any smooth function $u \in \mathcal{C}^{2}(\Sigma)$ with $u^{*}=\sup _{\Sigma} u<+\infty$ there exists a sequence of points $\left\{p_{k}\right\}_{k \in \mathbb{N}}$ in $\Sigma$ with the properties

$$
\text { (i) } u\left(p_{k}\right)>u^{*}-\frac{1}{k}, \text { (ii) }\left|\nabla u\left(p_{k}\right)\right|<\frac{1}{k} \text {, and (iii) } \Delta u\left(p_{k}\right)<\frac{1}{k} \text {. }
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- Equivalently, for any $u \in \mathcal{C}^{2}(\Sigma)$ with $u_{*}=\inf _{\Sigma} u>-\infty$ there exists a sequence of points $\left\{p_{k}\right\}_{k \in \mathbb{N}}$ in $\Sigma$ satisfying

$$
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## The Omori-Yau maximum principle

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$$

- In this sense, the classical maximum principle given by Omori (1967) and Yau (1975) stays that the Omori-Yau maximum principle holds on every complete Riemannian manifold with Ricci curvature bounded from below.


## The weak maximum principle

- The weak maximum principle is said to hold on $\Sigma$ if, for any $u \in \mathcal{C}^{2}(\Sigma)$ with $u^{*}<+\infty$ there is a sequence $\left\{p_{k}\right\}_{k \in \mathbb{N}}$ in $\Sigma$ with

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$$

- Pigola, Rigoli and Setti (2003) proved that the weak maximum principle holds on $\Sigma$ if and only if $\Sigma$ is stochastically complete.
- $\Sigma$ is said to be stochastically complete if its Brownian motion is stochastically complete, i.e, the probability of a particle to be found in the state space is constantly equal to 1 . In other words,

$$
\int_{\Sigma} p(x, y, t) d y=1 \text { for any }(x, t) \in \Sigma \times(0,+\infty)
$$

where $p(x, y, t)$ is the heat kernel of the Laplacian operator ${ }^{2}$.

[^1]
## The weak maximum principle

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- This is equivalent (among other conditions) to the fact that for every $\lambda>0$, the only non-negative bounded smooth solution $u$ of $\Delta u \geq \lambda u$ on $\Sigma$ is the constant $u=0$.

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- This is equivalent (among other conditions) to the fact that for every $\lambda>0$, the only non-negative bounded smooth solution $u$ of $\Delta u \geq \lambda u$ on $\Sigma$ is the constant $u=0$.
- In particular, every parabolic manifold is stochastically complete. Hence, the weak max principle holds on every parabolic manifold.
${ }^{2}$ For any open $\Omega \subset \Sigma, \int_{\Omega} p(x, y, t) d y$ is the probability that a random path starting at $x$ lies in $\Omega$ at finite time $t$. Hence $\int_{\Sigma} p(x, y, t) d y<1$ means that there is a positive probability that a random path will reach infinity in 'finite time $\bar{t}$.
- Following the standard terminology in General Relativity, a spacelike submanifold $\Sigma^{m}$ (of arbitrary codimension) of a spacetime $M^{n}$ is said to be a future trapped submanifold if its mean curvature vector field $\mathbf{H}$ is timelike and future-pointing everywhere on $\Sigma$.
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- Similarly, $\Sigma^{m}$ is said to be a past trapped submanifold if $\mathbf{H}$ is timelike and past-pointing everywhere on $\Sigma$.
- On the other hand, if $\mathbf{H}$ is lightlike and future-pointing everywhere on $\Sigma$ then the spacelike submanifold is said to be marginally future trapped.


## Trapped submanifolds in a spacetime

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- Similarly, $\Sigma$ is said to be marginally past trapped if $\mathbf{H}$ is lightlike and past-pointing on $\Sigma$.
- Finally, $\Sigma$ is said to be weakly future trapped if $\mathbf{H}$ is causal (that is, timelike or lightlike) and future-pointing everywhere.


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- Similarly, $\Sigma$ is said to be marginally past trapped if $\mathbf{H}$ is lightlike and past-pointing on $\Sigma$.
- Finally, $\Sigma$ is said to be weakly future trapped if $\mathbf{H}$ is causal (that is, timelike or lightlike) and future-pointing everywhere.
- Analogously, $\boldsymbol{\Sigma}$ is said to be weakly past trapped if $\mathbf{H}$ is causal and past-pointing on $\Sigma$.


# Weakly trapped submanifolds in the chronological future of 

 a point. Case $K_{M}(\Pi) \geq c$
# Weakly trapped submanifolds in the chronological future of a point. Case $K_{M}(\Pi) \geq c$ 

## Theorem 1

Let $M$ be a spacetime with a reference point $p \in M$ such that $\mathcal{I}^{+}(p) \neq \emptyset$, and assume $K_{M}(\Pi) \geq c, c \in \mathbb{R}$, for all timelike planes in $M$.
(1) If $c \geq 0$ there exists no stochastically complete, weakly past trapped submanifold contained in $\mathcal{I}^{+}(p)$.
(2) If $c<0$ and $\Sigma$ is a stochastically complete, weakly past trapped submanifold contained in $\mathcal{I}^{+}(p) \cap B^{+}(p, \pi / \sqrt{-c})$, then

$$
u_{*}=\inf _{\Sigma} u \geq \frac{\pi}{2 \sqrt{-c}}
$$

where $u$ denotes the Lorentzian distance $d_{p}$ along the hypersurface. In other words, $\Sigma$ is contained in $B^{+}(p, \pi / \sqrt{-c}) \cap O^{+}(p, \pi / 2 \sqrt{-c})$.

# Weakly trapped submanifolds in the chronological future of a point. Case $K_{M}(\Pi) \geq c$ 

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- Here, for $\delta>0$, the subsets $B^{+}(p, \delta)$ and $O^{+}(p, \delta)$ denote the future inner ball and the future outer ball of radius $\delta$, that is,

$$
\begin{aligned}
& B^{+}(p, \delta)=\left\{q \in I^{+}(p): d_{p}(q)<\delta\right\} \\
& O^{+}(p, \delta)=\left\{q \in I^{+}(p): d_{p}(q)>\delta\right\} .
\end{aligned}
$$

## Proof of Theorem 1

- As $K_{M}(\Pi) \geq c$, we know that

$$
\Delta v \leq-m h_{c}^{\prime}(u)+m h_{c}(u)\langle\mathbf{H}, \bar{\nabla} r\rangle .
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- Applying the weak max principle to the function $v$, which satisfies $v_{*}=\inf _{\Sigma v}=\phi_{c}\left(u_{*}\right)$ with $u_{*}=\inf _{\Sigma u \geq 0}$, we get that

$$
-\frac{1}{k}<\Delta v\left(p_{k}\right) \leq-m h^{\prime}\left(u\left(p_{k}\right)\right)+m h\left(u\left(p_{k}\right)\right)\langle\mathbf{H}, \bar{\nabla} r\rangle\left(p_{k}\right),
$$

for $\left\{p_{k}\right\} \subset \Sigma$ with $\lim _{k \rightarrow \infty} v\left(p_{k}\right)=v_{*}$ and $\lim _{k \rightarrow \infty} u\left(p_{k}\right)=u_{*}$.

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- Observe that, since $\Sigma$ is weakly past trapped, then

$$
\langle\mathbf{H}, \bar{\nabla} r\rangle<0 \quad \text { everywhere on } \Sigma .
$$

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- Therefore,

$$
-\frac{1}{k}<\Delta v\left(p_{k}\right) \leq-m h^{\prime}\left(u\left(p_{k}\right)\right)
$$

and, making $k \rightarrow \infty$ here we get $h_{c}^{\prime}\left(u_{*}\right) \leq 0$.

- As $K_{M}(\Pi) \geq c$, we know that

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$$

and, making $k \rightarrow \infty$ here we get $h_{c}^{\prime}\left(u_{*}\right) \leq 0$.

- The result then follows by observing that, when $c \geq 0$ then $h_{c}^{\prime}(t)>0$, and if $c<0$ then $h_{c}^{\prime}(t) \leq 0$ when $\pi / 2 \sqrt{-c} \leq t<\pi / \sqrt{-c}$.


## Marginally trapped submanifolds in the chronological future of a point. Case $K_{M}(\Pi) \geq c$

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## Theorem 2

Let $M$ be a spacetime with a reference point $p \in M$ such that $\mathcal{I}^{+}(p) \neq \emptyset$, and assume $K_{M}(\Pi) \geq c, c \in \mathbb{R}$, for all timelike planes in $M$. Let $\Sigma$ be a stochastically complete, marginally trapped submanifold contained in $\mathcal{I}^{+}(p)$ (with $u_{*}<\pi / 2 \sqrt{-c}$ in the case $c<0$ ). Then

$$
\sup _{\Sigma}\left|\mathbf{H}_{0}\right| \geq \frac{h_{c}^{\prime}}{h_{c}}\left(u_{*}\right),
$$

where $\mathbf{H}_{0}$ stands for the spacelike component of the lightlike vector field H which is orthogonal to $\bar{\nabla} r$, and $u_{*}=\inf _{\Sigma} u$. In particular, if $u_{*}=0$ then $\sup _{M}\left|\mathbf{H}_{0}\right|=+\infty$.

## Marginally trapped submanifolds in the chronological future of a point. Case $K_{M}(\Pi) \geq c$

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## Corollary 1

Under the assumptions of Theorem 2, if $\left|\mathbf{H}_{0}\right|$ is bounded from above on $\Sigma$, then there exists some $\delta>0$ such that $\Sigma \subset O^{+}(p, \delta)$, where $O^{+}(p, \delta)$ denotes the future outer ball of radius $\delta$.

- We know from Theorem 1 that $\Sigma$ must be in fact marginally future trapped.


## Proof of Theorem 2

- We know from Theorem 1 that $\Sigma$ must be in fact marginally future trapped.
- Let us write

$$
\mathbf{H}=\mathbf{H}_{0}-\langle\mathbf{H}, \bar{\nabla} r\rangle \bar{\nabla} r,
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with $\left\langle\mathbf{H}_{0}, \bar{\nabla} r\right\rangle=0$.

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- Since $\mathbf{H}$ is lightlike and future-pointing we derive from here that

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- Therefore, as $K_{M}(\Pi) \geq c$, we have

$$
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- If $\sup _{\Sigma}\left|\mathbf{H}_{0}\right|=+\infty$ then there is nothing to prove.
- We know from Theorem 1 that $\Sigma$ must be in fact marginally future trapped.
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with $\left\langle\mathbf{H}_{0}, \bar{\nabla} r\right\rangle=0$.

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$$

- If $\sup _{\Sigma}\left|\mathbf{H}_{0}\right|=+\infty$ then there is nothing to prove.
- Otherwise, let us write

$$
\Delta v \leq-m h_{c}^{\prime}(u)+m h_{c}(u)\left|\mathbf{H}_{0}\right| \leq-m h_{c}^{\prime}(u)+m h_{c}(u) \sup _{\Sigma}\left|\mathbf{H}_{0}\right| .
$$

## Proof of Theorem 2

- Applying again the weak maximum principle on $\Sigma$ to the function $v=\phi_{c}(u)$, with $v_{*}=\inf _{\Sigma} v=\phi_{c}\left(u_{*}\right)$, we have

$$
-\frac{1}{k}<\Delta v\left(p_{k}\right) \leq-m h_{c}^{\prime}\left(u\left(p_{k}\right)\right)+m h_{c}\left(u\left(p_{k}\right)\right) \sup _{\Sigma}\left|\mathbf{H}_{0}\right|,
$$

for $\left\{p_{k}\right\} \subset \Sigma$ with $\lim _{k \rightarrow \infty} v\left(p_{k}\right)=v_{*}$ and $\lim _{k \rightarrow \infty} u\left(p_{k}\right)=u_{*}$.

- Applying again the weak maximum principle on $\Sigma$ to the function $v=\phi_{c}(u)$, with $v_{*}=\inf _{\Sigma} v=\phi_{c}\left(u_{*}\right)$, we have

$$
-\frac{1}{k}<\Delta v\left(p_{k}\right) \leq-m h_{c}^{\prime}\left(u\left(p_{k}\right)\right)+m h_{c}\left(u\left(p_{k}\right)\right) \sup _{\Sigma}\left|\mathbf{H}_{0}\right|
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- The last assertion follows from the fact that $h_{c}(0)=0$ and $h_{c}^{\prime}(0)=1$.


## Marginally trapped submanifolds in the chronological future of a point. Case $K_{M}(\Pi) \leq c$

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## Theorem 3

Let $M$ be a spacetime with a reference point $p \in M$ such that $\mathcal{I}^{+}(p) \neq \emptyset$, and assume $K_{M}(\Pi) \leq c, c \in \mathbb{R}$, for all timelike planes in $M$. Let $\Sigma$ be a stochastically complete, marginally future trapped submanifold contained in $\mathcal{I}^{+}(p) \cap B^{+}(p, \delta)$ for some $\delta>0$ (with $\delta \leq \pi / \sqrt{-c}$ when $c<0$ ). Then

$$
\inf _{\Sigma}\left|\mathbf{H}_{0}\right| \leq \frac{h_{c}^{\prime}}{h_{c}}\left(u^{*}\right)
$$

where $\mathbf{H}_{0}$ stands for the spacelike component of the lightlike vector field $\mathbf{H}$ which is orthogonal to $\bar{\nabla} r$, and $u^{*}=\sup _{\Sigma} u$.

## Proof of Theorem 3

- Since $K_{M}(\Pi) \leq c$ and $\langle\mathbf{H}, \bar{\nabla} r\rangle=\left|\mathbf{H}_{0}\right|>0$ on $\Sigma$, we have

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## Marginally future trapped submanifolds in Lorentzian space forms

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Let $M_{c}^{n}$ be a Lorentzian space form of constant sectional curvature $c$ and let $p \in M_{c}^{n}$. Let $\Sigma$ be a stochastically complete, marginally trapped submanifold of $M_{c}^{n}$ which is contained in $\mathcal{I}^{+}(p) \cap B^{+}(p, \delta)$ for some $\delta>0$ (with $\delta \leq \pi / 2 \sqrt{-c}$ if $c<0$ ). Then

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where $u_{*}=\inf _{\sum u} u$ and $u^{*}=\sup _{\Sigma} u$.

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where $u_{*}=\inf _{\Sigma} u$ and $u^{*}=\sup _{\Sigma} u$.

- The estimates are sharp as proved by considering $\Sigma$ as a constant mean curvature hypersurface of a level set of the Lorentzian distance in $M_{c}^{n}$.


## Lorentzian distance function from an achronal hypersurface

- Given $S \subset M^{n}$ an achronal spacelike hypersurface, one can define the Lorentzian distance function from $S, d_{S}: M \rightarrow[0,+\infty]$, by

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s(p)=\sup \left\{t \geq 0: d_{S}\left(\gamma_{p}(t)\right)=t\right\}
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- Then, we can define

$$
\tilde{\mathcal{I}}^{+}(S)=\left\{t \eta_{p}: \text { for all } p \in S \text { and } 0<t<s(p)\right\}
$$

and consider the subset $\mathcal{I}^{+}(S) \subset M$ given by

$$
\mathcal{I}^{+}(S)=\exp _{S}\left(\operatorname{int}\left(\tilde{\mathcal{I}}^{+}(S)\right)\right) \subset I^{+}(S)
$$

where $\exp _{S}$ denotes the exponential map with respect to the hypersurface $S$.

## Lorentzian distance function from an achronal hypersurface

Lemma 4 (Erkekoglu, García-Río and Kupeli, 2003)
Let $S$ be an achronal spacelike hyersurface in a spacetime $M$.
(1) If $S$ is compact and $(M, g)$ is globally hyperbolic, then $s(p)>0$ for all $p \in S$ and $\mathcal{I}^{+}(S) \neq \emptyset$.
(2) If $\mathcal{I}^{+}(S) \neq \emptyset$, then $d_{S}$ is smooth on $\mathcal{I}^{+}(S)$ and its gradient $\bar{\nabla} d_{S}$ is a past-directed timelike (geodesic) unit vector field on $\mathcal{I}^{+}(S)$.

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- Doing a similar analysis of the Lorentzian distance function to an achronal hypersurface $S$, we can derive also sharp estimates for the mean curvature of marginally trapped submanifolds which are contained in the chronological future of $S$.


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- Doing a similar analysis of the Lorentzian distance function to an achronal hypersurface $S$, we can derive also sharp estimates for the mean curvature of marginally trapped submanifolds which are contained in the chronological future of $S$.
That's all !!
Muchas gracias.


[^0]:    ${ }^{1} M$ is globally hyperbolic provided (a) $J^{+}(p) \cap J^{-}(q)$ is compact for any $p, q \in M$, and (b) $M$ is causal, i.e, there are no closed causal curves in $M$.

[^1]:    ${ }^{2}$ For any open $\Omega \subset \Sigma, \int_{\Omega} p(x, y, t) d y$ is the probability that a random path starting at $x$ lies in $\Omega$ at finite time $t$. Hence $\int_{\Sigma} p(x, y, t) d y<1$ means that there is a positive probability that a random path will reach infinity in finite time $\bar{t}$.

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