Surfaces immersed in a half-space with the same Gaussian curvature induced by the Euclidean and Hyperbolic metrics

> Pedro Roitman (Univ. de Brasília) joint with Nilton Barroso

Granada's Geometry Seminar, Jan. 2014

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We will consider a particular case of the problem of finding submanifolds $N \subset M$ with a desired geometric property that is defined in terms of both metrics: g_1 and g_2 .

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The Problem

Let S be an immersed \mathbb{R}^3_+ , and denote by K_e and K_h the Gaussian curvatures of S induced by the Euclidean and hyperbolic metrics. Find surfaces such that $K_h = K_e$.

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Terminology

Surfaces such that $K_h = K_e$ will be called *isocurved surfaces*.

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Some simple examples

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• horizontal planes (Horospheres)

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- horizontal planes (Horospheres)
- spheres (properly placed)

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For example: A ruled surface with horizontal rulings that are orthogonal to a vertical plane P and pass through a tractrix contained in P that has line in $\partial \mathbb{R}^3_+$ as its asymptotic line.

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Question

Are there other examples? How to construct them?

The associated PDE

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$$k_{hi} = x_3 k_{ei} + n_3.$$

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So K_{hext} and K_e are related by:

$$K_h ext = x_3^2 K_e + 2H_e x_3 n_3 + n_3^2, \tag{1}$$

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We also recall that Gauss' equation gives us $K_h ext = K_h + 1$.

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$$(1-x_3^2)K_e - 2H_ex_3n_3 + 1 - n_3^2 = 0.$$

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$$(1-x_3^2)K_e - 2H_ex_3n_3 + 1 - n_3^2 = 0.$$

and for an isocurved graph we have the PDE:

$$A(\varphi_{uu}\varphi_{vv} - \varphi_{uv}^2) + B\varphi_{uu} + D\varphi_{vv} + 2C\varphi_{uv} + E = 0, \quad (2)$$

where $A = (1 - \varphi^2), B = -\varphi(1 + \varphi_v^2), C = \varphi\varphi_v\varphi_u,$
 $D = -\varphi(1 + \varphi_u^2), \text{ and } E = (1 + \varphi_u^2 + \varphi_v^2)(\varphi_u^2 + \varphi_v^2).$

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Note that it seems difficult to find explicit solutions without
symmetry assumptions.

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Reminder about Monge-Ampère equations

A PDE with the following form

$$A(\varphi_{uu}\varphi_{vv}-\varphi_{uv}^{2})+B\varphi_{uu}+D\varphi_{vv}+2C\varphi_{uv}+E=0, \quad (3)$$

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$$A(\varphi_{uu}\varphi_{vv} - \varphi_{uv}^2) + B\varphi_{uu} + D\varphi_{vv} + 2C\varphi_{uv} + E = 0, \quad (3)$$

where A, B, C, D and E are functions of u, v, φ, φ_u and φ_v is a Monge-Ampère equation.

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- eliptic if $\Delta < 0$,
- hiperbolic if $\Delta > 0$,
- parabolic if $\Delta = 0$.

Remark

The PDE for isocurved graphs is a mixed type equation

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Question:

How to construct such congruence of geodesics?

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Intuition

Since isocurved surfaces are defined using both metrics, maybe we should think of a geometric construction that involves both geometries.

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The geometric method

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Start with an oriented immersed surface Σ , with orientation given by a unit vector field N.

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For each $p \in \Sigma$, we define a (hyperbolic)geodesic as follows:

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For each $p \in \overline{\Sigma}$, we define a (hyperbolic)geodesic as follows:

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For each $p \in \Sigma$, we define a (hyperbolic)geodesic as follows:

- the center of the circle is $\pi_{hor}(p)$.
- The direction of the circle is defined by the vertical plane parallel to $J\pi_{hor}(N(p))$.

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- The direction of the circle is defined by the vertical plane parallel to $J\pi_{hor}(N(p))$.
- The radius of the circle is $R(p) = \frac{1}{|\pi_{hor}(N(p))|}$.

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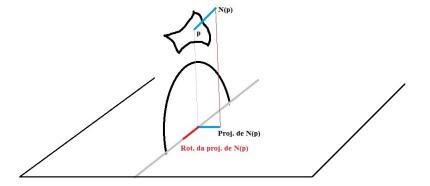
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This procedure defines a congruence of geodesics: C_{Σ} .

A picture might help...

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Natural question

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Integrability Condition

 C_{Σ} is integrable if and only if Σ is a minimal surface (euclidean sense).

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Intriguing Property

If Σ is minimal, then the orthogonal surfaces of C_{Σ} are isocurved (at smooth points).

The integrable system

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Let Σ be the graph of $\psi(u, v)$. Let's look for the surfaces orthogonal to C_{Σ} .

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A local parametrization of such surfaces would look like:

$$\mathbf{Y} = \boldsymbol{\sigma} + R\left(\cos\theta \mathbf{e_1} + \sin\theta \mathbf{e_3}\right), \qquad (4)$$

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where σ is the center of the circle and so on... The orthogonality condition is equivalent to

$$\langle d\mathbf{Y}, -\sin\theta\mathbf{e_1} + \cos\theta\mathbf{e_3} \rangle = 0,$$

where \langle , \rangle stands for the euclidean inner product.

the integrable system

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After some computations...we arrive at this system

$$\theta_{u} = \frac{\sin\theta}{R} \langle \boldsymbol{\sigma}_{u}, \mathbf{e_{1}} \rangle, \quad \theta_{v} = \frac{\sin\theta}{R} \langle \boldsymbol{\sigma}_{v}, \mathbf{e_{1}} \rangle$$
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(5)

It is better to make the following change of variables: $\sin \theta = 1/\cosh \beta$ e $\cos \theta = \tanh \beta$, and work with the equations:

$$\beta_u = -\frac{\langle \sigma_u, \mathbf{e_1} \rangle}{R}, \quad \beta_v = -\frac{\langle \sigma_v, \mathbf{e_1} \rangle}{R},$$
 (6)

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Integrability condition

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Integrability condition

Frobenius' theorem gives us the integrability condition:

$$\left(\frac{\langle \sigma_u, \mathbf{e}_1 \rangle}{R}\right)_v = \left(\frac{\langle \sigma_v, \mathbf{e}_1 \rangle}{R}\right)_u.$$
 (7)

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Since

$$\sigma(u, v) = (u, v, 0),$$

$$R = \frac{\sqrt{1 + \psi_u^2 + \psi_v^2}}{\sqrt{\psi_u^2 + \psi_v^2}},$$

$$\mathbf{e_1} = \frac{(-\psi_v, \psi_u)}{\sqrt{\psi_u^2 + \psi_v^2}},$$

it follows from simple computations that (7) is equivalent to

$$(1+\psi_{\mathbf{v}}^2)\psi_{\mathbf{u}\mathbf{u}}-2\psi_{\mathbf{u}}\psi_{\mathbf{v}}\psi_{\mathbf{u}\mathbf{v}}+(1+\psi_{\mathbf{u}}^2)\psi_{\mathbf{v}\mathbf{v}}=\mathbf{0},$$

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Integrable system for β

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$$\begin{split} \beta_{u} &= -\frac{\psi_{v}}{\sqrt{1+|\nabla\psi|^{2}}};\\ \beta_{v} &= \frac{\psi_{u}}{\sqrt{1+|\nabla\psi|^{2}}}. \end{split}$$

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 We need to start with a minimal graph(there aren't many explicit solutions).

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Apparently weak points for the constructions of explicit examples:

- We need to start with a minimal graph(there aren't many explicit solutions).
- Integration can be difficult.

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Remarks about the geometric construction

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 The existence of β assures the existence of the map Y. But Y is not always an immersion. (In other words, we may have natural singularities).

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- The existence of β assures the existence of the map Y. But Y is not always an immersion.(In other words, we may have natural singularities).
- If we start with an immersion Y into ℝ³₊ and ask if Y comes from a surface by the inverse process then Y must be isocurved.
- Stricktly speaking, we actually don't need a surface to start our geometric construction, all we need is a smooth two parameter family of contact elements of R³.

Geometric Remark

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Bonus

The integrable system for β admits an interpretation in terms of the minimal surface.

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The solutions of the integrable system associated to a minimal surface Σ has the form $\beta = x_3^* + C$, where x_3^* is the height function of the conjugate surface Σ^* .

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A few examples

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Surface of Revolution Consider $f(z) = ie^z$ and $g(z) = ce^{-z}$, $c \in \mathbb{R}$, $c \neq 0$.

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A few examples

Surface of Revolution Consider $f(z) = ie^z$ and $g(z) = ce^{-z}$, $c \in \mathbb{R}$, $c \neq 0$. Using f and g as Weierstrass data we have a helicoid. The associated isocurved surface is a surface of revolution. As an example let's choose c = 2:

$$\mathbf{X}(x,y) = (\alpha(x) \sin y, \alpha(x) \cos y, \gamma(x)),$$

where

$$\alpha(x) = \frac{1}{4} \frac{\left(-\mathrm{e}^{5\,x} + 8\,\mathrm{e}^{3\,x} + 45\,\mathrm{e}^{x} - 8\,\mathrm{e}^{-x} + 16\,\mathrm{e}^{-3\,x}\right)}{\left(4\,\mathrm{e}^{-2\,x} + 1\right)\left(\mathrm{e}^{4\,x} + 1\right)},$$

and

$$\gamma(x) = \frac{1}{2} \frac{e^{3x} \sqrt{1 + 8e^{-2x} + 16e^{-4x}}}{e^{4x} + 1}$$

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Surface of Revolution



Figure: Isocurved of revolution

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Consider the function defined in a fundamental domain:

$$\varphi(x,y) = \ln \frac{\cos y}{\cos x}.$$

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From our method we get the following isocurved parametrized surface:

$$\mathbf{X}(x, y) = (x - \Lambda_1 \sin y \cos x, y - \Lambda_1 \sin x \cos y, \Lambda_2),$$

where

$$\Lambda_1 = \frac{\sqrt{\cos^2 x + \cos^2 y - \cos^2 x \cos^2 y} \tanh(\arcsin(\sin x \sin y))}{\sin^2 x \cos^2 y + \sin^2 y \cos^2 x},$$

and

$$\Lambda_2 = \frac{\sqrt{\cos^2 x + \cos^2 y - \cos^2 x \cos^2 y}}{\cosh(\arcsin(\sin x \sin y))\sqrt{\cos^2 x + \cos^2 y - 2\cos^2 x \cos^2 y}}.$$

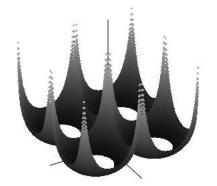


Figure: 2-periodic Scherk type Isocurved

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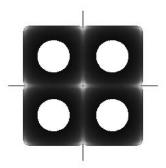


Figure: Top view

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Are all isocurved generated in this way?

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• No, not all isocurved are generated by our method.

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- The hyperbolic isocurved surfaces are generated in a similar way using timelike minimal surfaces in L³.

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- However, locally we can generate all the elliptic isocurved surfaces.
- The hyperbolic isocurved surfaces are generated in a similar way using timelike minimal surfaces in L³.
- There are also parabolic examples and probably a degenerate type of minimal surface can be associated to it.

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Final Remarks

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Muchas Gracias!!

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