# The Minkowski problem and constant curvature surfaces in $\mathbb{R}^3$

Rabah Souam

Institut de Mathématiques de Jussieu, Paris

Joint work with Antonio Alarcón

Workshop on Geometric and Complex Analysis

Granada, November 2012

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# Aim

The aim of this talk is to classify the family of surfaces with

- positive constant Gauss curvature in  $\mathbb{R}^3$ ,
- Gauss map a *diffeomorphism* onto a finitely punctured  $\mathbb{S}^2$ , and
- extrinsic conformal structure a circular domain in  $\overline{\mathbb{C}}$ .

We will derive some applications:

• Harmonic diffeomorphisms between certain domains of S<sup>2</sup>.

- Capillary surfaces in  $\mathbb{R}^3$ .
- A Hessian equation of Monge-Ampère type on  $\mathbb{S}^2$ .

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- A. Alarcón and R. Souam, The Minkowski problem, new constant curvature surfaces in R<sup>3</sup>, and some applications. Preprint 2012 (arXiv:1206.6066).

#### Definition

By a K-surface we mean a surface in  $\mathbb{R}^3$  with constant Gauss curvature K=1.

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- Let S be a smooth surface and let  $X : S \to \mathbb{R}^3$  be a K-immersion.
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- $z = u + \iota v$  conformal parameter on  $\mathcal{R}$ .
- Gálvez-Martínez 2000 The Gauss map  $N: \mathcal{R} \to \mathbb{S}^2$  satisfies

$$X_u = N \times N_v$$
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hence it is a harmonic local diffeomorphism. Conversely...

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 The outer parallel surface at distance 1 to a K-surface is an H-surface with H = 1/2 and intrinsic conformal structure R.

• K-surfaces of revolution are classified.



• The round sphere is the only complete *K*-surface in  $\mathbb{R}^3$ . There are no complete ends in the theory.

# Peaked spheres

• K-surfaces of revolution are classified.



## Peaked spheres

- Gálvez-Hauswirth-Mira 2010 studied the family of *K*-surfaces with isolated singularities (peaked spheres).
  - The extrinsic conformal structure is a circular domain  $\mathcal{R} \subset \mathbb{S}^2 \equiv \overline{\mathbb{C}}$ .
  - There is no peaked sphere with exactly one singularity.
  - The only peaked spheres with exactly two singularities are the rotational ones.
  - For n > 2 there is a 3n 6 parameter family of peaked spheres with exactly n singularities, which can be parameterized by the *intrinsic* conformal structures.
  - The Gauss map is solution to the Neumann problem for harmonic diffeomorphisms

$$N: \overline{\mathcal{R}} \to \mathbb{S}^2, \quad \left. \frac{\partial N}{\partial \mathbf{n}} \right|_{\partial \overline{\mathcal{R}}} = 0.$$

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- There is a 1-parameter family depending on the radius of the cover discs.
- The extrinsic conformal structure is a circular domain  $\mathcal{R} \subset \overline{\mathbb{C}}$ .
- The Gauss map is a (harmonic) diffeomorphism

$$N: \mathcal{R} \to \mathbb{S}^2 - \{(0, 0, 1), (0, 0, -1)\},\$$

hence extends continuously to  $\overline{\mathcal{R}}$  being constant over each connected component of  $\partial \overline{\mathcal{R}}$ .



 Are there K-surfaces satisfying that properties but with m ∈ ℕ ends?

#### Question

Let  $\{p_1, \ldots, p_m\} \subset \mathbb{S}^2$ . Do there exist K-surfaces whose extrinsic conformal structures are circular domains  $\mathcal{R} \subset \overline{\mathbb{C}}$  and their Gauss maps harmonic diffeomorphisms  $\mathcal{R} \to \mathbb{S}^2 - \{p_1, \ldots, p_m\}$ ?

• Let  $\{p_1, \ldots, p_m\}$  be a subset of  $\mathbb{S}^2$ .

#### Theorem (Alarcón-S., 2012)

The following statements are equivalent:

(i) There exists a K-surface  $S \subset \mathbb{R}^3$  whose extrinsic conformal structure is a circular domain  $\mathcal{R} \subset \overline{\mathbb{C}}$  and its Gauss map is a (harmonic) diffeomorphism

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(ii) There exist positive real constants  $a_1, \ldots, a_m$  such that

$$\sum_{j=1}^m a_j p_j = 0 \in \mathbb{R}^3.$$

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- There is no such S for m = 1.
- If m = 2 then  $p_2 = -p_1$ .

#### Theorem (Alarcón-S., 2012)

Furthermore, if S is as above and  $\gamma_j$  denotes the component of  $\overline{S} - S$  corresponding to  $p_j$  via the Gauss map, then

- (1)  $\gamma_j$  is a Jordan curve contained in an affine plane  $\Pi_j \subset \mathbb{R}^3$ orthogonal to  $p_j$ , and
- (II)  $\mathscr{S} := S \cup (\bigcup_{j=1}^{m} \overline{D}_{j})$  is the boundary surface of a smooth convex body in  $\mathbb{R}^{3}$ , where  $D_{j}$  denotes the bounded component of  $\Pi_{j} \gamma_{j}$ .

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In addition, given  $(a_1, \ldots, a_m)$  satisfying (ii), there exists a unique, up to translations, K-surface S satisfying (i) such that  $\operatorname{Area}(D_j) = a_j$  for all j.

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• If m = 2 then S is rotational.

- Let  $\{p_1, \ldots, p_m\} \subset \mathbb{S}^2$ .
- Assume there exists a K-surface S ⊂ ℝ<sup>3</sup> satisfying (i) and let us show that {p<sub>1</sub>,..., p<sub>m</sub>} and S satisfy (ii), (I), and (II).
- Denote by  $N_S: S \to \mathbb{S}^2 \{p_1, \dots, p_m\}$  the outer Gauss map of S.

Main ingredient: The Legendre transform

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- Fix  $j \in \{1, ..., m\}$  and assume that  $p_j = (0, 0, 1) \in \mathbb{R}^3$ .
- Consider

$$H = \{p \in S \colon x_3(N_S(p)) \in [1 - \epsilon, 1)\}$$

for  $\epsilon > 0$ .

- Assume that *H* is a topological annulus with boundary and a local graph in the *x*<sub>3</sub>-direction at any point.
- Write  $(X_1, X_2, X_3) : H \to \mathbb{R}^3$  the inclusion map, and  $(N_S)|_H = (N_1, N_2, N_3) : H \to \mathbb{S}^2 \cap \{x_3 \in [1 - \epsilon, 1)\} \subset \mathbb{R}^3.$

• The Legendre transform of H,

$$\mathcal{L}=\left(rac{N_1}{N_3}, rac{N_2}{N_3}, rac{N_1}{N_3}X_1+rac{N_2}{N_3}X_2+X_3
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defines a strongly positively curved surface  $\mathcal{L}(H)$  with boundary in  $\mathbb{R}^3$ , that is a local graph in the  $x_3$ -direction at any point.

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defines a strongly positively curved surface  $\mathcal{L}(H)$  with boundary in  $\mathbb{R}^3$ , that is a local graph in the  $x_3$ -direction at any point.

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hence  $(X_1, X_2) : H \to \mathbb{R}^2$  is bounded and so  $X_3 : H \to \mathbb{R}$  has a limit  $(= \varphi(0, 0))$ .

• So the component  $\gamma_j$  of  $\overline{S} - S$  corresponding to  $p_j$  via  $N_S$  lies in an affine plane  $\prod_j \perp p_j$ 

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- $N_S: S \to \mathbb{S}^2 \{p_1, \dots, p_m\}$  is one to one  $\Rightarrow \mathscr{S}$  is (globally) convex.
- *S* has a unique supporting plane at every point ⇒ *S* bounds a
   smooth convex body ⇒ *S* is C<sup>1</sup> and embedded.

• Equilibrium condition:

• 
$$\int_{S} N_{S}(p) dp = \int_{S^{2} - \{p_{1}, \dots, p_{m}\}} p dp = \int_{S^{2}} p dp = 0.$$

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• 
$$0 = \int_{\mathscr{S}-S} N_S(p) = \int_{\bigcup_{j=1}^m D_j} N_S(p) = \sum_{j=1}^m \operatorname{Area}(D_j) p_j.$$

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•  $\mathcal{R}$  is a circular domain  $\Rightarrow$  Area $(D_j) > 0 \ \forall j$ .

## Classification Result

• Let 
$$\{p_1, \ldots, p_m\}$$
 be a subset of  $\mathbb{S}^2$ .

#### Theorem (Alarcón-S., 2012)

The following statements are equivalent:

(i) There exists a K-surface  $S \subset \mathbb{R}^3$  whose extrinsic conformal structure is a circular domain  $\mathcal{R} \subset \overline{\mathbb{C}}$  and its Gauss map is a harmonic diffeomorphism

$$\mathcal{R} \to \mathbb{S}^2 - \{p_1, \ldots, p_m\}.$$

(ii) There exist positive real constants  $a_1, \ldots, a_m$  such that

$$\sum_{j=1}^m a_j p_j = 0 \in \mathbb{R}^3.$$

#### Theorem (Alarcón-S., 2012)

- Furthermore, if S is as above and  $\gamma_j$  denotes the component of  $\overline{S} S$  corresponding to  $p_j$  via the Gauss map, then
- (I)  $\gamma_j$  is a Jordan curve contained in an affine plane  $\Pi_j \subset \mathbb{R}^3$ orthogonal to  $p_j$ , and
- (II)  $\mathscr{S} := S \cup (\bigcup_{j=1}^{m} \overline{D}_{j})$  is the boundary surface of a smooth convex body in  $\mathbb{R}^{3}$ , where  $D_{j}$  denotes the bounded component of  $\Pi_{j} \gamma_{j}$ .

In addition, given  $(a_1, \ldots, a_m)$  satisfying (ii), there exists a unique, up to translations, K-surface S satisfying (i) such that  $Area(D_j) = a_j$  for all j.

- Let  $X : \mathbb{S}^2 \to \mathbb{R}^3$  be an immersion such that  $X(\mathbb{S}^2)$  is a closed strictly convex surface in  $\mathbb{R}^3$ .
- Then the Gauss map  $N_X : \mathbb{S}^2 \to \mathbb{S}^2$  of X is a homeomorphism.

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- Define  $\kappa : \mathbb{S}^2 \to \mathbb{R}$ ,  $\kappa = K \circ N_X^{-1}$ , where  $K : \mathbb{S}^2 \to \mathbb{R}$  denotes the Gauss curvature function of X.

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- Minkowski observed that  $\kappa$  must satisfy

$$\int_{\mathbb{S}^2} \frac{p}{\kappa(p)} \, dp = 0.$$

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• Minkowski asked for the converse.

 Let S be a compact convex surface in ℝ<sup>3</sup>, not necessarily smooth; i.e., S is the boundary of a general convex body in ℝ<sup>3</sup>.

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• If S is  $C^2$  and strictly convex, then:

$$\mu(S) = \frac{1}{\kappa} \mu_{S^2},$$

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where  $\mu_{S^2}$  denotes the canonical Lebesgue measure on  $S^2$ .

• If S is a polyhedron, then:

$$\mu(S) = \sum_{j=1}^n c_j \, \delta_{\nu_j},$$

where  $\delta_{\nu_j}$  is the Dirac measure at  $\nu_j$  and  $c_j$  is the Euclidean area of the face of S with outer normal  $\nu_j$ .

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• The convex surface  $\mathscr{S}$  in (II) agrees with the solution to the *generalized Minkowski problem* for the Borel measure

$$\mu(\mathscr{S}) = \mu_{\mathbb{S}^2} + \sum_{j=1}^m a_j \delta_{p_j} \quad (a_j = \operatorname{Area}(D_j)).$$

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$$\int_{\mathbb{S}^2} \mathrm{i}_{\mathbb{S}^2}\,\mu = \mathsf{0} \in \mathbb{R}^3$$

and  $\mu(H) > 0$  for any hemisphere  $H \subset \mathbb{S}^2$ . Then there exists a unique, up to translations, convex body  $\mathcal{K}$  in  $\mathbb{R}^3$  such that  $\mu$  is the *area function* of  $\partial \mathcal{K}$ .

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- This gives the uniqueness part of the theorem.
- The theorem gives no information about the regularity of  $\partial \mathcal{K}$ .

Pogorelov 1952, Nirenberg 1953, Cheng-Yau 1976 (for higher dimensions)Let κ : S<sup>2</sup> → ℝ be a smooth positive function satisfying

$$\int_{\mathbb{S}^2} \frac{p}{\kappa(p)} \, dp = 0.$$

Then there exists a unique, up to translations, *smooth* embedding  $X : \mathbb{S}^2 \to \mathbb{R}^3$  such that  $X(\mathbb{S}^2)$  is a closed *strictly convex* surface and the curvature function  $K : \mathbb{S}^2 \to \mathbb{R}$  of X is given by

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- Idea: Construct approximate solutions and take limits.

- Let  $\{p_1, \ldots, p_m\} \subset \mathbb{S}^2$ .
- Assume there exists positive constants  $(a_1, \ldots, a_m)$  such that

$$\sum_{j=1}^m a_j p_j = 0 \in \mathbb{R}^3$$
 ,

and let us show a K-surface S satisfying (i) (hence (I) and (II)) with  $Area(D_j) = a_j$  for all j.

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• Denote by B(p, r) the metric ball in  $\mathbb{S}^2$  centered at  $p \in \mathbb{S}^2$  with radius r > 0, and by  $A(p, r) = B(p, 2r) - \overline{B(p, r)}$ .

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• 
$$\Sigma_n := \mathbb{S}^2 - \bigcup_{j=1}^m B(p_j, 2/n).$$

- Denote by B(p, r) the metric ball in S<sup>2</sup> centered at p ∈ S<sup>2</sup> with radius r > 0, and by A(p, r) = B(p, 2r) B(p, r).
  Σ<sub>n</sub> := S<sup>2</sup> ∪<sup>m</sup><sub>i=1</sub>B(p<sub>j</sub>, 2/n).
- Let  $\kappa_n: \mathbb{S}^2 \to \mathbb{R}$  be a smooth function such that

$$(rac{1}{\kappa_n})|_{\Sigma_n} = 1, \quad (rac{1}{\kappa_n})|_{B(p_j, 1/n)} = rac{n^2}{\pi} \, a_j, \quad 1 \leq (rac{1}{\kappa_n})|_{A(p_j, 1/n)} \leq rac{n^2}{\pi} \, a_j$$

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- Let  $\kappa_n: \mathbb{S}^2 \to \mathbb{R}$  be a smooth function such that

$$\begin{aligned} (\frac{1}{\kappa_n})|_{\Sigma_n} &= 1, \quad (\frac{1}{\kappa_n})|_{B(p_j, 1/n)} = \frac{n^2}{\pi} a_j, \quad 1 \le (\frac{1}{\kappa_n})|_{A(p_j, 1/n)} \le \frac{n^2}{\pi} a_j, \\ \int_{A(p_j, 1/n)} \frac{p}{\kappa_n(p)} dp &= \frac{4\pi}{n^2} p_j \quad \left( = \int_{B(p_j, 2/n)} p \, dp \right). \end{aligned}$$

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Then
$$\int_{S^2} \frac{p}{\kappa_n(p)} dp = 0$$

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- Then  $\int_{\mathbb{S}^2} \frac{p}{\kappa_n(p)} dp = 0$  and the Minkowski problem can be solved for  $\kappa_n : \mathbb{S}^2 \to \mathbb{R}$ .
- There exists a smooth embedding X<sub>n</sub> : S<sup>2</sup> → ℝ<sup>3</sup> such that
   𝒮<sub>n</sub> := X<sub>n</sub>(S<sup>2</sup>) is a closed smooth strictly convex surface,
  - **2** the Gauss map of  $X_n$  is the identity map of  $\mathbb{S}^2$ ,
  - the curvature function of X<sub>n</sub> agrees κ<sub>n</sub>; in particular
     S<sub>n</sub> := X<sub>n</sub>(Σ<sub>n</sub>) is a K-surface,
  - Area $(X_n(B(p_j, 1/n))) = a_j$  for all j.

### • Denote by $\mathscr{K}_n \subset \mathbb{R}^3$ the strictly convex body bordered by $\mathscr{S}_n$ .

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#### Claim

There exists  $\xi > 0$  (not depending on n) such that  $\mathbb{B}(\xi) \subset \mathscr{K}_n \subset \mathbb{B}(1/\xi) \ \forall n$ . (adapting arguments in Cheng-Yau 1976.)

Solution Blaschke selection theorem ⇒  $\{\mathscr{K}_n\}_{n \in \mathbb{N}}$  converges in the Hausforff distance to a convex body  $\mathscr{K}$ .

•  $\mathscr{S}_n := X_n(\mathbb{S}^2)$  is a closed smooth strictly convex surface,

- **2** the Gauss map of  $X_n$  is the identity map of  $\mathbb{S}^2$ ,
- the curvature function of X<sub>n</sub> agrees κ<sub>n</sub>; in particular
   S<sub>n</sub> := X<sub>n</sub>(Σ<sub>n</sub>) is a K-surface,
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- the extrinsic conformal structure of S is a circular domain in  $\overline{\mathbb{C}}$ .

# Application: Harmonic diffeomorphims

- Liouville There is no non-constant harmonic map  $\mathbb{C}\to\mathbb{D},$  with the Euclidean metric.
- Heinz 1952 There is no harmonic diffeomorphism  $\mathbb{D}\to\mathbb{C}$  with the Euclidean metric.

## Question (Schoen-Yau 1985)

Are Riemannian surfaces which are related by a harmonic diffeomorphism quasiconformally related? In particular, are there harmonic diffeomorphisms from  $\mathbb{C}$  onto the hyperbolic plane  $\mathbb{H}^2$ ?

Collin-Rosenberg 2010 There exists an entire minimal graph Σ over ℍ<sup>2</sup> in the Riemannian product ℍ<sup>2</sup> × ℝ with the conformal type of ℂ.
 In particular, the vertical projection Σ → ℍ<sup>2</sup> is a harmonic

diffeomorphism from  $\mathbb C$  into  $\mathbb H^2.$
### Theorem (Alarcón-S.; CMH, in press)

For any m ∈ N, m ≥ 2, and any subet {p<sub>1</sub>,..., p<sub>m</sub>} ⊂ S<sup>2</sup> there exist a circular domain R ⊂ C and a harmonic diffeomorphism R → S<sup>2</sup> - {p<sub>1</sub>,..., p<sub>m</sub>}.

### Theorem (Alarcón-S.; CMH, in press)

• For any  $m \in \mathbb{N}$ ,  $m \ge 2$ , and any subet  $\{p_1, \ldots, p_m\} \subset \mathbb{S}^2$  there exist a circular domain  $\mathcal{R} \subset \overline{\mathbb{C}}$  and a harmonic diffeomorphism  $\mathcal{R} \to \mathbb{S}^2 - \{p_1, \ldots, p_m\}$ .

 There exists no harmonic diffeomorphism D → S<sup>2</sup> - {p}, p ∈ S<sup>2</sup>.

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- There exists no harmonic diffeomorphism D → S<sup>2</sup> {p}, p ∈ S<sup>2</sup>.
- The harmonic diffeomorphism R → S<sup>2</sup> {p<sub>1</sub>,..., p<sub>m</sub>} appears as the vertical projection Σ → S<sup>2</sup> {p<sub>1</sub>,..., p<sub>m</sub>}, where Σ is a maximal graph over S<sup>2</sup> {p<sub>1</sub>,..., p<sub>m</sub>} in the Lorentzian manifold S<sup>2</sup> × ℝ<sub>1</sub>, with Σ ≅ R.

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- Such a maximal graph  $\Sigma$  is constructed by solving Dirichlet problems.
- The non-existence of harmonic diffeomorphisms  $\mathbb{D} \to \mathbb{S}^2 \{p\}$  follows from *K*-surface theory.

#### Corollary

Let  $\{p_1, \ldots, p_m\} \subset \mathbb{S}^2$  with  $\sum_{j=1}^m a_j p_j = 0 \in \mathbb{R}^3$  for some positive numbers  $a_1, \ldots, a_m$ . Then there exists a circular domain  $\mathcal{R}$  in  $\overline{\mathbb{C}}$  and a harmonic diffeomorphism  $\mathcal{R} \to \mathbb{S}^2 - \{p_1, \ldots, p_m\}$ .

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- We do not know if those harmonic diffeomorphisms given as Gauss maps of K-surfaces in R<sup>3</sup> and those given as vertical projections of maximal graphs in S<sup>2</sup> × R<sub>1</sub> are the same or not.

• The support function of S,

$$\begin{split} h: \mathbb{S}^2 - \{p_1, \dots, p_m\} \to \mathbb{R}, \quad h(p) = \langle p, N_S^{-1}(p) \rangle, \\ \text{satisfies} \quad \left( \det(\nabla^2 h + h\mathrm{I}) \right) \circ N_S = 1 \ \left( = 1/\mathcal{K} \right) \quad \text{on } S. \end{split}$$

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• A parameterization  $X:\mathbb{S}^2-\{p_1,\ldots,p_m\}
ightarrow\mathbb{R}^3$  of S is given by

$$X(p) = \nabla h(p) + h(p)p.$$

• Fully nonlinear, elliptic second order partial differential equations of the form

$$\mathscr{F}[h] := F(\nabla^2 h + A(\cdot, h, \nabla h)) = B(\cdot, h, \nabla h) \quad \text{on } \Omega \subset \mathcal{M},$$

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• The space of solutions to the Hessian one equation

det 
$$abla^2 h = 1$$
 on  $\mathbb{R}^2 - \{q_1, \dots, q_k\}$ 

was described by Gálvez-Martínez-Mira 2005 (Jorgens 1955 for k = 1).

• Jorgens 1954 The only solutions for k = 0 are quadratic polynomials.

• Two solution u and v of the Hessian equation

$$\det \left( \nabla^2 h + h \mathbf{I} \right) = 1 \quad \text{on } \mathbb{S}^2 - \{ p_1, \dots, p_m \}$$

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are equivalent,  $u \sim v$ , if u - v is the restriction to  $\mathbb{S}^2 - \{p_1, \dots, p_m\}$  of a linear function of  $\mathbb{R}^3$ .

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The space of equivalence classes of solutions of the above equation, under  $\sim$ , with non-removable singularities at the points  $\{p_1, \ldots, p_m\}$ , is in bijection with the set  $\{(a_1, \ldots, a_m) \in \mathbb{R}^m \mid a_j > 0 \ \forall j, \sum_{i=1}^m a_j p_j = 0\}.$ 

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- h: S<sup>2</sup> {p<sub>1</sub>,..., p<sub>m</sub>} → ℝ is solution to the equation iff it is the support function of a surface S as those in the theorem.
- The only solution for m = 0 is the round sphere and there is no solution for m = 1.

- A capillary surface in a region B in ℝ<sup>3</sup> is a compact CMC surface meeting ∂B at a constant angle γ ∈ [0, π] along its boundary. They model liquid drops inside a container in the absence of gravity.
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- The outer parallel surface at distance 1 to a K-surface is a CMC surface with H = 1/2 (i.e., an H-surface).

# Application: Capillary surfaces

• Let 
$$\{p_1, \ldots, p_m\}$$
 be a subset of  $\mathbb{S}^2$ .

#### Corollary

The following statements are equivalent:

(i) There exists a (positively curved) *H*-surface  $S \subset \mathbb{R}^3$  whose intrinsic conformal structure is a circular domain  $\mathcal{R} \subset \overline{\mathbb{C}}$  and its Gauss map is a harmonic diffeomorphism

$$\mathcal{R} \to \mathbb{S}^2 - \{p_1, \ldots, p_m\}.$$

(ii) There exist positive real constants  $a_1, \ldots, a_m$  such that

$$\sum_{j=1}^m a_j p_j = 0 \in \mathbb{R}^3.$$

# Application: Capillary surfaces

### Corollary

Furthermore, if S is as above and  $\gamma_j$  denotes the component of  $\overline{S} - S$  corresponding to  $p_j$  via the Gauss map, then

- (I)  $\gamma_j$  is a Jordan curve contained in an affine plane  $\Pi_j \subset \mathbb{R}^3$ orthogonal to  $p_j$ , and
- (II)  $\mathscr{S} := S \cup (\bigcup_{j=1}^{m} \overline{D}_{j})$  is the boundary surface of a smooth convex body in  $\mathbb{R}^{3}$ , where  $D_{j}$  denotes the bounded component of  $\Pi_{j} \gamma_{j}$ .

In addition, given  $(a_1, \ldots, a_m)$  satisfying (ii), there exists a unique, up to translations, H-surface S satisfying (i) such that  $Area(D_j) = a_j$  for all j.

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 In particular, S is an embedded H-surface of genus zero which meets tangentially all the faces of the polyhedral region determined by the affine planes Π<sub>j</sub>, j = 1,..., m.