# The Minkowski problem and constant curvature surfaces in $\mathbb{R}^{3}$ 

Rabah Souam<br>Institut de Mathématiques de Jussieu, Paris

Joint work with Antonio Alarcón

Workshop on Geometric and Complex Analysis
Granada, November 2012

## Aim

The aim of this talk is to classify the family of surfaces with

- positive constant Gauss curvature in $\mathbb{R}^{3}$,
- Gauss map a diffeomorphism onto a finitely punctured $\mathrm{S}^{2}$, and
- extrinsic conformal structure a circular domain in $\overline{\mathbb{C}}$.

We will derive some applications:

- Harmonic diffeomorphisms between certain domains of $\mathrm{S}^{2}$.
- Capillary surfaces in $\mathbb{R}^{3}$.
- A Hessian equation of Monge-Ampère type on $S^{2}$.


## Aim and reference

The aim of this talk is to classify the family of surfaces with

- positive constant Gauss curvature in $\mathbb{R}^{3}$,
- Gauss map a diffeomorphism onto a finitely punctured $\mathrm{S}^{2}$, and
- extrinsic conformal structure a circular domain in $\overline{\mathbb{C}}$.

We will derive some applications:

- Harmonic diffeomorphisms between certain domains of $\mathrm{S}^{2}$.
- Capillary surfaces in $\mathbb{R}^{3}$.
- A Hessian equation of Monge-Ampère type on $\mathrm{S}^{2}$.
- A. Alarcón and R. Souam, The Minkowski problem, new constant curvature surfaces in $\mathbb{R}^{3}$, and some applications. Preprint 2012 (arXiv:1206.6066).


## K-surfaces

## Definition

By a $K$-surface we mean a surface in $\mathbb{R}^{3}$ with constant Gauss curvature $K=1$.

## K-surfaces

## Definition

By a $K$-surface we mean a surface in $\mathbb{R}^{3}$ with constant Gauss curvature $K=1$.

- Let $S$ be a smooth surface and let $X: S \rightarrow \mathbb{R}^{3}$ be a $K$-immersion.
- $I_{X}$ positive definite metric $\Rightarrow I I_{X}$ induces on $S$ a conformal structure, $\mathcal{R} \equiv$ extrinsic conformal structure.


## K-surfaces

## Definition

By a $K$-surface we mean a surface in $\mathbb{R}^{3}$ with constant Gauss curvature $K=1$.

- Let $S$ be a smooth surface and let $X: S \rightarrow \mathbb{R}^{3}$ be a $K$-immersion.
- $I_{X}$ positive definite metric $\Rightarrow I I_{X}$ induces on $S$ a conformal structure, $\mathcal{R} \equiv$ extrinsic conformal structure.
- $z=u+\imath v$ conformal parameter on $\mathcal{R}$.
- Gálvez-Martínez 2000 The Gauss map $N: \mathcal{R} \rightarrow \mathrm{S}^{2}$ satisfies

$$
X_{u}=N \times N_{v} \quad \text { and } \quad X_{v}=-N \times N_{u}
$$

hence it is a harmonic local diffeomorphism.
Conversely...

## K-surfaces

## Definition

By a $K$-surface we mean a surface in $\mathbb{R}^{3}$ with constant Gauss curvature $K=1$.

- Let $S$ be a smooth surface and let $X: S \rightarrow \mathbb{R}^{3}$ be a $K$-immersion.
- $I_{X}$ positive definite metric $\Rightarrow I_{X}$ induces on $S$ a conformal structure, $\mathcal{R} \equiv$ extrinsic conformal structure.
- $z=u+\imath v$ conformal parameter on $\mathcal{R}$.
- Gálvez-Martínez 2000 The Gauss map $N: \mathcal{R} \rightarrow \mathrm{S}^{2}$ satisfies

$$
X_{u}=N \times N_{v} \quad \text { and } \quad X_{v}=-N \times N_{u}
$$

hence it is a harmonic local diffeomorphism.
Conversely...

- The outer parallel surface at distance 1 to a $K$-surface is an H-surface with $H=1 / 2$ and intrinsic conformal structure $\mathcal{R}$.


## K-surfaces of revolution

- K-surfaces of revolution are classified.

- The round sphere is the only complete $K$-surface in $\mathbb{R}^{3}$. There are no complete ends in the theory.


## Peaked spheres

- K-surfaces of revolution are classified.


## Peaked spheres

- Gálvez-Hauswirth-Mira 2010 studied the family of $K$-surfaces with isolated singularities (peaked spheres).
- The extrinsic conformal structure is a circular domain $\mathcal{R} \subset \mathbb{S}^{2} \equiv \overline{\mathbb{C}}$.
- There is no peaked sphere with exactly one singularity.
- The only peaked spheres with exactly two singularities are the rotational ones.
- For $n>2$ there is a $3 n-6$ parameter family of peaked spheres with exactly $n$ singularities, which can be parameterized by the intrinsic conformal structures.
- The Gauss map is solution to the Neumann problem for harmonic diffeomorphisms

$$
N: \overline{\mathcal{R}} \rightarrow \mathrm{S}^{2},\left.\quad \frac{\partial N}{\partial \mathbf{n}}\right|_{\partial \overline{\mathcal{R}}}=0
$$

## K-surfaces of revolution

- K-surfaces of revolution are classified.



## $K$-surfaces of revolution

- They tangentially meet planes at the ends.


## $K$-surfaces of revolution

- They tangentially meet planes at the ends.
- Adding the cover discs one gets a smooth convex surface.


## $K$-surfaces of revolution

- They tangentially meet planes at the ends.
- Adding the cover discs one gets a smooth convex surface.
- There is a 1-parameter family depending on the radius of the cover discs.



## $K$-surfaces of revolution

- They tangentially meet planes at the ends.
- Adding the cover discs one gets a smooth convex surface.
- There is a 1-parameter family depending on the radius of the cover discs.



## $K$-surfaces of revolution

- They tangentially meet planes at the ends.
- Adding the cover discs one gets a smooth convex surface.
- There is a 1-parameter family depending on the radius of the cover discs.
- The extrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$.



## $K$-surfaces of revolution

- They tangentially meet planes at the ends.
- Adding the cover discs one gets a smooth convex surface.
- There is a 1-parameter family depending on the radius of the cover discs.
- The extrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$.
- The Gauss map is a (harmonic) diffeomorphism

$$
N: \mathcal{R} \rightarrow \mathrm{S}^{2}-\{(0,0,1),(0,0,-1)\}
$$

hence extends continuously to $\overline{\mathcal{R}}$ being constant over each connected component of $\partial \overline{\mathcal{R}}$.


## Aim

- Are there $K$-surfaces satisfying that properties but with $m \in \mathbb{N}$ ends?


## Question

Let $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$.
Do there exist $K$-surfaces whose extrinsic conformal structures are circular domains $\mathcal{R} \subset \overline{\mathbb{C}}$ and their Gauss maps harmonic diffeomorphisms $\mathcal{R} \rightarrow \mathbb{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ ?

## Classification Result

- Let $\left\{p_{1}, \ldots, p_{m}\right\}$ be a subset of $S^{2}$.

Theorem (Alarcón-S., 2012)
The following statements are equivalent:
(i) There exists a $K$-surface $S \subset \mathbb{R}^{3}$ whose extrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and its Gauss map is a (harmonic) diffeomorphism

$$
\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

(ii) There exist positive real constants $a_{1}, \ldots, a_{m}$ such that

$$
\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}
$$

## Classification Result

- Let $\left\{p_{1}, \ldots, p_{m}\right\}$ be a subset of $S^{2}$.

Theorem (Alarcón-S., 2012)
The following statements are equivalent:
(i) There exists a $K$-surface $S \subset \mathbb{R}^{3}$ whose extrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and its Gauss map is a (harmonic) diffeomorphism

$$
\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

(ii) There exist positive real constants $a_{1}, \ldots, a_{m}$ such that

$$
\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}
$$

- There is no such $S$ for $m=1$.
- If $m=2$ then $p_{2}=-p_{1}$.


## Classification Result

## Theorem (Alarcón-S., 2012)

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{S}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.

## Classification Result

## Theorem (Alarcón-S., 2012)

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{S}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.
In addition, given $\left(a_{1}, \ldots, a_{m}\right)$ satisfying (ii), there exists a unique, up to translations, $K$-surface $S$ satisfying (i) such that $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$.

## Classification Result

## Theorem (Alarcón-S., 2012)

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{S}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.
In addition, given $\left(a_{1}, \ldots, a_{m}\right)$ satisfying (ii), there exists a unique, up to translations, $K$-surface $S$ satisfying (i) such that $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$.

- If $m=2$ then $S$ is rotational.


## Convexity and the equilibrium condition

- Let $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$.
- Assume there exists a $K$-surface $S \subset \mathbb{R}^{3}$ satisfying (i) and let us show that $\left\{p_{1}, \ldots, p_{m}\right\}$ and $S$ satisfy (ii), (I), and (II).
- Denote by $N_{S}: S \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ the outer Gauss map of $S$.


## Convexity and the equilibrium condition

Main ingredient: The Legendre transform

## Convexity and the equilibrium condition

Main ingredient: The Legendre transform

- Fix $j \in\{1, \ldots, m\}$ and assume that $p_{j}=(0,0,1) \in \mathbb{R}^{3}$.
- Consider

$$
H=\left\{p \in S: x_{3}\left(N_{S}(p)\right) \in[1-\epsilon, 1)\right\}
$$

for $\epsilon>0$.

- Assume that $H$ is a topological annulus with boundary and a local graph in the $x_{3}$-direction at any point.
- Write $\left(X_{1}, X_{2}, X_{3}\right): H \rightarrow \mathbb{R}^{3}$ the inclusion map, and $\left.\left(N_{S}\right)\right|_{H}=\left(N_{1}, N_{2}, N_{3}\right): H \rightarrow S^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \subset \mathbb{R}^{3}$.


## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

- The map $\mathrm{S}^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \rightarrow \Omega-\{(0,0)\}$, $\left(x_{1}, x_{2}, x_{3}\right) \mapsto\left(x_{1} / x_{3}, x_{2} / x_{3}\right)$, is a diffeomorphism.


## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

- The map $\mathrm{S}^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \rightarrow \Omega-\{(0,0)\}$,
$\left(x_{1}, x_{2}, x_{3}\right) \mapsto\left(x_{1} / x_{3}, x_{2} / x_{3}\right)$, is a diffeomorphism.
- $\mathcal{L}(H)$ is the graph of a function $\varphi: \Omega-\{(0,0)\} \rightarrow \mathbb{R}$.


## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

- The map $\mathbb{S}^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \rightarrow \Omega-\{(0,0)\}$,
$\left(x_{1}, x_{2}, x_{3}\right) \mapsto\left(x_{1} / x_{3}, x_{2} / x_{3}\right)$, is a diffeomorphism.
- $\mathcal{L}(H)$ is the graph of a function $\varphi: \Omega-\{(0,0)\} \rightarrow \mathbb{R}$.
- Nelli-Rosenberg $1997 \varphi$ extends continuously to $\Omega$ and its graph $\overline{\mathcal{L}(H)}$ is a convex $\mathcal{C}^{0}$ surface with boundary.


## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

- The map $\mathbb{S}^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \rightarrow \Omega-\{(0,0)\}$,
$\left(x_{1}, x_{2}, x_{3}\right) \mapsto\left(x_{1} / x_{3}, x_{2} / x_{3}\right)$, is a diffeomorphism.
- $\mathcal{L}(H)$ is the graph of a function $\varphi: \Omega-\{(0,0)\} \rightarrow \mathbb{R}$.
- Nelli-Rosenberg $1997 \varphi$ extends continuously to $\Omega$ and its graph $\overline{\mathcal{L}(H)}$ is a convex $\mathcal{C}^{0}$ surface with boundary.
- The Gauss map of $\mathcal{L}$ is given by

$$
N_{\mathcal{L}}: H \rightarrow \mathrm{~S}^{2}, \quad N_{\mathcal{L}}=\frac{\left(X_{1}, X_{2},-1\right)}{\sqrt{X_{1}^{2}+X_{2}^{2}+1}}
$$

hence $\left(X_{1}, X_{2}\right): H \rightarrow \mathbb{R}^{2}$ is bounded

## Convexity and the equilibrium condition.

- The Legendre transform of $H$,

$$
\mathcal{L}=\left(\frac{N_{1}}{N_{3}}, \frac{N_{2}}{N_{3}}, \frac{N_{1}}{N_{3}} X_{1}+\frac{N_{2}}{N_{3}} X_{2}+X_{3}\right): H \rightarrow \mathbb{R}^{3}
$$

defines a strongly positively curved surface $\mathcal{L}(H)$ with boundary in $\mathbb{R}^{3}$, that is a local graph in the $x_{3}$-direction at any point.

- The map $\mathbb{S}^{2} \cap\left\{x_{3} \in[1-\epsilon, 1)\right\} \rightarrow \Omega-\{(0,0)\}$,
$\left(x_{1}, x_{2}, x_{3}\right) \mapsto\left(x_{1} / x_{3}, x_{2} / x_{3}\right)$, is a diffeomorphism.
- $\mathcal{L}(H)$ is the graph of a function $\varphi: \Omega-\{(0,0)\} \rightarrow \mathbb{R}$.
- Nelli-Rosenberg $1997 \varphi$ extends continuously to $\Omega$ and its graph $\overline{\mathcal{L}(H)}$ is a convex $\mathcal{C}^{0}$ surface with boundary.
- The Gauss map of $\mathcal{L}$ is given by

$$
N_{\mathcal{L}}: H \rightarrow \mathrm{~S}^{2}, \quad N_{\mathcal{L}}=\frac{\left(X_{1}, X_{2},-1\right)}{\sqrt{X_{1}^{2}+X_{2}^{2}+1}}
$$

hence $\left(X_{1}, X_{2}\right): H \rightarrow \mathbb{R}^{2}$ is bounded and so $X_{3}: H \rightarrow \mathbb{R}$ has a limit $(=\varphi(0,0))$.

## Convexity and the equilibrium condition

- So the component $\gamma_{j}$ of $\bar{S}-S$ corresponding to $p_{j}$ via $N_{S}$ lies in an affine plane $\Pi_{j} \perp p_{j}$


## Convexity and the equilibrium condition

- So the component $\gamma_{j}$ of $\bar{S}-S$ corresponding to $p_{j}$ via $N_{S}$ lies in an affine plane $\Pi_{j} \perp p_{j}$
- $\gamma_{j}$ bounds a convex disc $D_{j}$ in $\Pi_{j}$.


## Convexity and the equilibrium condition

- So the component $\gamma_{j}$ of $\bar{S}-S$ corresponding to $p_{j}$ via $N_{S}$ lies in an affine plane $\Pi_{j} \perp p_{j}$
- $\gamma_{j}$ bounds a convex disc $D_{j}$ in $\Pi_{j}$.
- $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is a closed locally convex $\mathcal{C}^{0}$-surface.
- $N_{S}$ extends to $\mathscr{S}$ setting $\left.\left(N_{S}\right)\right|_{\bar{D}_{j}}=p_{j}$.


## Convexity and the equilibrium condition

- So the component $\gamma_{j}$ of $\bar{S}-S$ corresponding to $p_{j}$ via $N_{S}$ lies in an affine plane $\Pi_{j} \perp p_{j}$
- $\gamma_{j}$ bounds a convex disc $D_{j}$ in $\Pi_{j}$.
- $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is a closed locally convex $\mathcal{C}^{0}$-surface.
- $N_{S}$ extends to $\mathscr{S}$ setting $\left.\left(N_{S}\right)\right|_{\bar{D}_{j}}=p_{j}$.
- $N_{S}: S \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ is one to one $\Rightarrow \mathscr{S}$ is (globally) convex.


## Convexity and the equilibrium condition

- So the component $\gamma_{j}$ of $\bar{S}-S$ corresponding to $p_{j}$ via $N_{S}$ lies in an affine plane $\Pi_{j} \perp p_{j}$
- $\gamma_{j}$ bounds a convex disc $D_{j}$ in $\Pi_{j}$.
- $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is a closed locally convex $\mathcal{C}^{0}$-surface.
- $N_{S}$ extends to $\mathscr{S}$ setting $\left.\left(N_{S}\right)\right|_{\bar{D}_{j}}=p_{j}$.
- $N_{S}: S \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ is one to one $\Rightarrow \mathscr{S}$ is (globally) convex.
- $\mathscr{S}$ has a unique supporting plane at every point $\Rightarrow \mathscr{S}$ bounds a smooth convex body $\Rightarrow \mathscr{S}$ is $\mathcal{C}^{1}$ and embedded.


## Convexity and the equilibrium condition

- Equilibrium condition:
- $\int_{S} N_{S}(p) d p=\int_{S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}} p d p=\int_{S^{2}} p d p=0$.


## Convexity and the equilibrium condition

- Equilibrium condition:
- $\int_{S} N_{S}(p) d p=\int_{S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}} p d p=\int_{S^{2}} p d p=0$.
- $\int_{\mathscr{S}} N_{S}(p) d p=0$.


## Convexity and the equilibrium condition

- Equilibrium condition:
- $\int_{S} N_{S}(p) d p=\int_{\mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}} p d p=\int_{\mathrm{S}^{2}} p d p=0$.
- $\int_{\mathscr{S}} N_{S}(p) d p=0$.
- $0=\int_{\mathscr{S}-S} N_{S}(p)=\int_{\cup_{j=1}^{m} D_{j}} N_{S}(p)=\sum_{j=1}^{m} \operatorname{Area}\left(D_{j}\right) p_{j}$.
- $\mathcal{R}$ is a circular domain $\Rightarrow \operatorname{Area}\left(D_{j}\right)>0 \forall j$.


## Classification Result

- Let $\left\{p_{1}, \ldots, p_{m}\right\}$ be a subset of $S^{2}$.

Theorem (Alarcón-S., 2012)
The following statements are equivalent:
(i) There exists a $K$-surface $S \subset \mathbb{R}^{3}$ whose extrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and its Gauss map is a harmonic diffeomorphism

$$
\mathcal{R} \rightarrow \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

(ii) There exist positive real constants $a_{1}, \ldots, a_{m}$ such that

$$
\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}
$$

## Classification Result

## Theorem (Alarcón-S., 2012)

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{S}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.
In addition, given $\left(a_{1}, \ldots, a_{m}\right)$ satisfying (ii), there exists a unique, up to translations, $K$-surface $S$ satisfying (i) such that $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$.

## Existence. The Minkowski problem

- Let $X: \mathbb{S}^{2} \rightarrow \mathbb{R}^{3}$ be an immersion such that $X\left(\mathbb{S}^{2}\right)$ is a closed strictly convex surface in $\mathbb{R}^{3}$.
- Then the Gauss map $N_{X}: S^{2} \rightarrow S^{2}$ of $X$ is a homeomorphism.


## Existence. The Minkowski problem

- Let $X: S^{2} \rightarrow \mathbb{R}^{3}$ be an immersion such that $X\left(S^{2}\right)$ is a closed strictly convex surface in $\mathbb{R}^{3}$.
- Then the Gauss map $N_{X}: S^{2} \rightarrow S^{2}$ of $X$ is a homeomorphism.
- Define $\kappa: S^{2} \rightarrow \mathbb{R}, \kappa=K \circ N_{X}^{-1}$, where $K: S^{2} \rightarrow \mathbb{R}$ denotes the Gauss curvature function of $X$.


## Existence. The Minkowski problem

- Let $X: \mathbb{S}^{2} \rightarrow \mathbb{R}^{3}$ be an immersion such that $X\left(\mathbb{S}^{2}\right)$ is a closed strictly convex surface in $\mathbb{R}^{3}$.
- Then the Gauss map $N_{X}: S^{2} \rightarrow S^{2}$ of $X$ is a homeomorphism.
- Define $\kappa: S^{2} \rightarrow \mathbb{R}, \kappa=K \circ N_{X}^{-1}$, where $K: S^{2} \rightarrow \mathbb{R}$ denotes the Gauss curvature function of $X$.
- Minkowski observed that $\kappa$ must satisfy

$$
\int_{\mathrm{S}^{2}} \frac{p}{\kappa(p)} d p=0 .
$$

## Existence. The Minkowski problem

- Let $X: \mathbb{S}^{2} \rightarrow \mathbb{R}^{3}$ be an immersion such that $X\left(S^{2}\right)$ is a closed strictly convex surface in $\mathbb{R}^{3}$.
- Then the Gauss map $N_{X}: S^{2} \rightarrow S^{2}$ of $X$ is a homeomorphism.
- Define $\kappa: S^{2} \rightarrow \mathbb{R}, \kappa=K \circ N_{X}^{-1}$, where $K: S^{2} \rightarrow \mathbb{R}$ denotes the Gauss curvature function of $X$.
- Minkowski observed that $\kappa$ must satisfy

$$
\int_{\mathrm{S}^{2}} \frac{p}{\kappa(p)} d p=0
$$

- Minkowski asked for the converse.


## Existence. The generalized Minkowski problem

- Let $S$ be a compact convex surface in $\mathbb{R}^{3}$, not necessarily smooth; i.e., $S$ is the boundary of a general convex body in $\mathbb{R}^{3}$.


## Existence. The generalized Minkowski problem

- Let $S$ be a compact convex surface in $\mathbb{R}^{3}$, not necessarily smooth; i.e., $S$ is the boundary of a general convex body in $\mathbb{R}^{3}$.
- The generalized Gauss map $G: S \rightarrow S^{2}$ of $S$ is a set-valued map. It maps $p \in S$ to the set of all outer normals of the supporting planes of $S$ passing through $p$.


## Existence. The generalized Minkowski problem

- Let $S$ be a compact convex surface in $\mathbb{R}^{3}$, not necessarily smooth; i.e., $S$ is the boundary of a general convex body in $\mathbb{R}^{3}$.
- The generalized Gauss map $G: S \rightarrow S^{2}$ of $S$ is a set-valued map. It maps $p \in S$ to the set of all outer normals of the supporting planes of $S$ passing through $p$.
- Define a measure $\mu(S)$ on $S^{2}$ called the area function of $S$ by setting

$$
\mu(S)(E)=\operatorname{Area}(\{p \in S \mid G(p) \cap E \neq \varnothing\})
$$

for any Borel subset $E \subset S^{2}$.

## Existence. The generalized Minkowski problem

- Let $S$ be a compact convex surface in $\mathbb{R}^{3}$, not necessarily smooth; i.e., $S$ is the boundary of a general convex body in $\mathbb{R}^{3}$.
- The generalized Gauss map $G: S \rightarrow \mathrm{~S}^{2}$ of $S$ is a set-valued map. It maps $p \in S$ to the set of all outer normals of the supporting planes of $S$ passing through $p$.
- Define a measure $\mu(S)$ on $S^{2}$ called the area function of $S$ by setting

$$
\mu(S)(E)=\operatorname{Area}(\{p \in S \mid G(p) \cap E \neq \varnothing\})
$$

for any Borel subset $E \subset S^{2}$.

- If $S$ is $\mathcal{C}^{2}$ and strictly convex, then:

$$
\mu(S)=\frac{1}{\kappa} \mu_{\mathrm{S}^{2}}
$$

where $\mu_{\mathrm{S}^{2}}$ denotes the canonical Lebesgue measure on $\mathrm{S}^{2}$.

## Existence. The generalized Minkowski problem

- If $S$ is a polyhedron, then:

$$
\mu(S)=\sum_{j=1}^{n} c_{j} \delta_{v_{j}}
$$

where $\delta_{v_{j}}$ is the Dirac measure at $v_{j}$ and $c_{j}$ is the Euclidean area of the face of $S$ with outer normal $v_{j}$.

## Existence. The generalized Minkowski problem

- The convex surface $\mathscr{S}$ in (II) agrees with the solution to the generalized Minkowski problem for the Borel measure

$$
\mu(\mathscr{S})=\mu_{\mathrm{S}^{2}}+\sum_{j=1}^{m} a_{j} \delta_{p_{j}} \quad\left(a_{j}=\operatorname{Area}\left(D_{j}\right)\right)
$$

## Existence. The generalized Minkowski problem

- The convex surface $\mathscr{S}$ in (II) agrees with the solution to the generalized Minkowski problem for the Borel measure

$$
\mu(\mathscr{S})=\mu_{\mathrm{S}^{2}}+\sum_{j=1}^{m} a_{j} \delta_{p_{j}} \quad\left(a_{j}=\operatorname{Area}\left(D_{j}\right)\right)
$$

- Minkowski, Alexandrov, Fenchel, Jessen 1958 Let $\mu$ be a non-negative Borel measure on $\mathrm{S}^{2}$ such that

$$
\int_{\mathrm{S}^{2}} \mathrm{i}_{\mathrm{S}^{2}} \mu=0 \in \mathbb{R}^{3}
$$

and $\mu(H)>0$ for any hemisphere $H \subset S^{2}$.
Then there exists a unique, up to translations, convex body $\mathscr{K}$ in $\mathbb{R}^{3}$ such that $\mu$ is the area function of $\partial \mathscr{K}$.

## Existence. The generalized Minkowski problem

- The convex surface $\mathscr{S}$ in (II) agrees with the solution to the generalized Minkowski problem for the Borel measure

$$
\mu(\mathscr{S})=\mu_{\mathrm{S}^{2}}+\sum_{j=1}^{m} a_{j} \delta_{p_{j}} \quad\left(a_{j}=\operatorname{Area}\left(D_{j}\right)\right)
$$

- Minkowski, Alexandrov, Fenchel, Jessen 1958 Let $\mu$ be a non-negative Borel measure on $\mathrm{S}^{2}$ such that

$$
\int_{\mathrm{S}^{2}} \mathrm{i}_{\mathrm{S}^{2}} \mu=0 \in \mathbb{R}^{3}
$$

and $\mu(H)>0$ for any hemisphere $H \subset S^{2}$.
Then there exists a unique, up to translations, convex body $\mathscr{K}$ in $\mathbb{R}^{3}$ such that $\mu$ is the area function of $\partial \mathscr{K}$.

- This gives the uniqueness part of the theorem.


## Existence. The generalized Minkowski problem

- The convex surface $\mathscr{S}$ in (II) agrees with the solution to the generalized Minkowski problem for the Borel measure

$$
\mu(\mathscr{S})=\mu_{\mathrm{S}^{2}}+\sum_{j=1}^{m} a_{j} \delta_{p_{j}} \quad\left(a_{j}=\operatorname{Area}\left(D_{j}\right)\right)
$$

- Minkowski, Alexandrov, Fenchel, Jessen 1958 Let $\mu$ be a non-negative Borel measure on $\mathrm{S}^{2}$ such that

$$
\int_{\mathrm{S}^{2}} \mathrm{i}_{\mathrm{S}^{2}} \mu=0 \in \mathbb{R}^{3}
$$

and $\mu(H)>0$ for any hemisphere $H \subset S^{2}$.
Then there exists a unique, up to translations, convex body $\mathscr{K}$ in $\mathbb{R}^{3}$ such that $\mu$ is the area function of $\partial \mathscr{K}$.

- This gives the uniqueness part of the theorem.
- The theorem gives no information about the regularity of $\partial \mathscr{K}$.


## Existence. The Minkowski problem

- Pogorelov 1952, Nirenberg 1953, Cheng-Yau 1976 (for higher dimensions)Let $\kappa: S^{2} \rightarrow \mathbb{R}$ be a smooth positive function satisfying

$$
\int_{\mathrm{S}^{2}} \frac{p}{\kappa(p)} d p=0
$$

Then there exists a unique, up to translations, smooth embedding $X: \mathrm{S}^{2} \rightarrow \mathbb{R}^{3}$ such that $X\left(\mathrm{~S}^{2}\right)$ is a closed strictly convex surface and the curvature function $K: S^{2} \rightarrow \mathbb{R}$ of $X$ is given by

$$
K=\kappa \circ N_{X}
$$

- $X \circ N_{X}^{-1}: S^{2} \rightarrow \mathbb{R}^{3}$ has curvature function $\kappa$ and Gauss map the identity map of $\mathbb{S}^{2}$.


## Existence. The Minkowski problem

- Pogorelov 1952, Nirenberg 1953, Cheng-Yau 1976 (for higher dimensions)Let $\kappa: S^{2} \rightarrow \mathbb{R}$ be a smooth positive function satisfying

$$
\int_{\mathrm{S}^{2}} \frac{p}{\kappa(p)} d p=0
$$

Then there exists a unique, up to translations, smooth embedding $X: \mathrm{S}^{2} \rightarrow \mathbb{R}^{3}$ such that $X\left(\mathrm{~S}^{2}\right)$ is a closed strictly convex surface and the curvature function $K: S^{2} \rightarrow \mathbb{R}$ of $X$ is given by

$$
K=\kappa \circ N_{X} .
$$

- $X \circ N_{X}^{-1}: S^{2} \rightarrow \mathbb{R}^{3}$ has curvature function $\kappa$ and Gauss map the identity map of $\mathrm{S}^{2}$.
- The curvature function $K_{\mathscr{S}}$ of $\mathscr{S}$ is $\left.\left(K_{\mathscr{S}}\right)\right|_{S}=1$ and $\left.\left(K_{\mathscr{S}}\right)\right|_{D_{j}}=0$, hence it is neither continuous nor positive.


## Existence. The Minkowski problem

- Pogorelov 1952, Nirenberg 1953, Cheng-Yau 1976 (for higher dimensions)Let $\kappa: S^{2} \rightarrow \mathbb{R}$ be a smooth positive function satisfying

$$
\int_{\mathrm{S}^{2}} \frac{p}{\kappa(p)} d p=0
$$

Then there exists a unique, up to translations, smooth embedding $X: \mathrm{S}^{2} \rightarrow \mathbb{R}^{3}$ such that $X\left(\mathrm{~S}^{2}\right)$ is a closed strictly convex surface and the curvature function $K: S^{2} \rightarrow \mathbb{R}$ of $X$ is given by

$$
K=\kappa \circ N_{X} .
$$

- $X \circ N_{X}^{-1}: S^{2} \rightarrow \mathbb{R}^{3}$ has curvature function $\kappa$ and Gauss map the identity map of $\mathbb{S}^{2}$.
- The curvature function $K_{\mathscr{S}}$ of $\mathscr{S}$ is $\left.\left(K_{\mathscr{S}}\right)\right|_{S}=1$ and $\left.\left(K_{\mathscr{S}}\right)\right|_{D_{j}}=0$, hence it is neither continuous nor positive.
- Idea: Construct approximate solutions and take limits.


## Existence

- Let $\left\{p_{1}, \ldots, p_{m}\right\} \subset S^{2}$.
- Assume there exists positive constants $\left(a_{1}, \ldots, a_{m}\right)$ such that

$$
\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}
$$

and let us show a $K$-surface $S$ satisfying (i) (hence (I) and (II)) with $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$.

## Existence

- Denote by $B(p, r)$ the metric ball in $\mathrm{S}^{2}$ centered at $p \in \mathrm{~S}^{2}$ with radius $r>0$, and by $A(p, r)=B(p, 2 r)-\overline{B(p, r)}$.
- $\Sigma_{n}:=\mathrm{S}^{2}-\cup_{j=1}^{m} \overline{B\left(p_{j}, 2 / n\right)}$.


## Existence

- Denote by $B(p, r)$ the metric ball in $\mathrm{S}^{2}$ centered at $p \in \mathrm{~S}^{2}$ with radius $r>0$, and by $A(p, r)=B(p, 2 r)-\overline{B(p, r)}$.
- $\Sigma_{n}:=\mathrm{S}^{2}-\cup_{j=1}^{m} \overline{B\left(p_{j}, 2 / n\right)}$.
- Let $\kappa_{n}: S^{2} \rightarrow \mathbb{R}$ be a smooth function such that

$$
\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{\Sigma_{n}}=1,\left.\quad\left(\frac{1}{\kappa_{n}}\right)\right|_{B\left(p_{j}, 1 / n\right)}=\frac{n^{2}}{\pi} a_{j}, \quad 1 \leq\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{A\left(p_{j}, 1 / n\right)} \leq \frac{n^{2}}{\pi} a_{j}
$$

## Existence

- Denote by $B(p, r)$ the metric ball in $\mathrm{S}^{2}$ centered at $p \in \mathrm{~S}^{2}$ with radius $r>0$, and by $A(p, r)=B(p, 2 r)-\overline{B(p, r)}$.
- $\Sigma_{n}:=\mathrm{S}^{2}-\cup_{j=1}^{m} \overline{B\left(p_{j}, 2 / n\right)}$.
- Let $\kappa_{n}: S^{2} \rightarrow \mathbb{R}$ be a smooth function such that

$$
\begin{gathered}
\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{\Sigma_{n}}=1,\left.\quad\left(\frac{1}{\kappa_{n}}\right)\right|_{B\left(p_{j}, 1 / n\right)}=\frac{n^{2}}{\pi} a_{j}, \quad 1 \leq\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{A\left(p_{j}, 1 / n\right)} \leq \frac{n^{2}}{\pi} a_{j} \\
\int_{A\left(p_{j}, 1 / n\right)} \frac{p}{\kappa_{n}(p)} d p=\frac{4 \pi}{n^{2}} p_{j} \quad\left(=\int_{B\left(p_{j}, 2 / n\right)} p d p\right)
\end{gathered}
$$

## Existence

- Denote by $B(p, r)$ the metric ball in $\mathrm{S}^{2}$ centered at $p \in \mathrm{~S}^{2}$ with radius $r>0$, and by $A(p, r)=B(p, 2 r)-\overline{B(p, r)}$.
- $\Sigma_{n}:=\mathrm{S}^{2}-\cup_{j=1}^{m} \overline{B\left(p_{j}, 2 / n\right)}$.
- Let $\kappa_{n}: S^{2} \rightarrow \mathbb{R}$ be a smooth function such that

$$
\begin{gathered}
\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{\Sigma_{n}}=1,\left.\quad\left(\frac{1}{\kappa_{n}}\right)\right|_{B\left(p_{j}, 1 / n\right)}=\frac{n^{2}}{\pi} a_{j}, \quad 1 \leq\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{A\left(p_{j}, 1 / n\right)} \leq \frac{n^{2}}{\pi} a_{j} \\
\int_{A\left(p_{j}, 1 / n\right)} \frac{p}{\kappa_{n}(p)} d p=\frac{4 \pi}{n^{2}} p_{j} \quad\left(=\int_{B\left(p_{j}, 2 / n\right)} p d p\right)
\end{gathered}
$$

- Then $\int_{\mathrm{S}^{2}} \frac{p}{\kappa_{n}(p)} d p=0$


## Existence

- Denote by $B(p, r)$ the metric ball in $\mathrm{S}^{2}$ centered at $p \in \mathrm{~S}^{2}$ with radius $r>0$, and by $A(p, r)=B(p, 2 r)-\overline{B(p, r)}$.
- $\Sigma_{n}:=\mathrm{S}^{2}-\cup_{j=1}^{m} \overline{B\left(p_{j}, 2 / n\right)}$.
- Let $\kappa_{n}: S^{2} \rightarrow \mathbb{R}$ be a smooth function such that

$$
\begin{gathered}
\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{\Sigma_{n}}=1,\left.\quad\left(\frac{1}{\kappa_{n}}\right)\right|_{B\left(p_{j}, 1 / n\right)}=\frac{n^{2}}{\pi} a_{j}, \quad 1 \leq\left.\left(\frac{1}{\kappa_{n}}\right)\right|_{A\left(p_{j}, 1 / n\right)} \leq \frac{n^{2}}{\pi} a_{j} \\
\int_{A\left(p_{j}, 1 / n\right)} \frac{p}{\kappa_{n}(p)} d p=\frac{4 \pi}{n^{2}} p_{j} \quad\left(=\int_{B\left(p_{j}, 2 / n\right)} p d p\right)
\end{gathered}
$$

- Then $\int_{\mathrm{S}^{2}} \frac{p}{\kappa_{n}(p)} d p=0$ and the Minkowski problem can be solved for $\kappa_{n}: \mathbb{S}^{2} \rightarrow \mathbb{R}$.
- There exists a smooth embedding $X_{n}: S^{2} \rightarrow \mathbb{R}^{3}$ such that
(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $S^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(9) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$.


## Existence

- Denote by $\mathscr{K}_{n} \subset \mathbb{R}^{3}$ the strictly convex body bordered by $\mathscr{S}_{n}$.


## Existence

- Denote by $\mathscr{K}_{n} \subset \mathbb{R}^{3}$ the strictly convex body bordered by $\mathscr{S}_{n}$.

Claim
There exists $\xi>0$ (not depending on $n$ ) such that $\mathbb{B}(\xi) \subset \mathscr{K}_{n} \subset \mathbb{B}(1 / \xi) \forall n$. (adapting arguments in Cheng-Yau 1976.)
(5) Blaschke selection theorem $\Rightarrow\left\{\mathscr{K}_{n}\right\}_{n \in \mathbb{N}}$ converges in the Hausforff distance to a convex body $\mathscr{K}$.

## Existence

(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $S^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(1) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$, and
(0) $\left\{\mathscr{S}_{n}\right\}_{n \in \mathbb{N}} \rightarrow \mathscr{S}:=\partial \mathscr{K}$.

## Existence

(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $\mathrm{S}^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(9) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$, and
(6) $\left\{\mathscr{S}_{n}\right\}_{n \in \mathbb{N}} \rightarrow \mathscr{S}:=\partial \mathscr{K}$.

- $\left\{\left.\left(X_{n}\right)\right|_{\Sigma_{n}}\right\}_{n \in \mathbb{N}}$ converges to a $K$-immersion $\mathbb{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}^{3}$ with Gauss map the identity map of $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$; denote by $S$ the image $K$-surface.


## Existence

(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $S^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(9) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$, and
(3) $\left\{\mathscr{S}_{n}\right\}_{n \in \mathbb{N}} \rightarrow \mathscr{S}:=\partial \mathscr{K}$.

- $\left\{\left.\left(X_{n}\right)\right|_{\Sigma_{n}}\right\}_{n \in \mathbb{N}}$ converges to a $K$-immersion $\mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}^{3}$ with Gauss map the identity map of $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$; denote by $S$ the image $K$-surface.
- $\left\{X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right\}_{n \in \mathbb{N}}$ converges to an open disc $D_{j}$ contained in a plane $\Pi_{j}$ orthogonal to $p_{j}$, with $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$,


## Existence

(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $S^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(9) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$, and
(5) $\left\{\mathscr{S}_{n}\right\}_{n \in \mathbb{N}} \rightarrow \mathscr{S}:=\partial \mathscr{K}$.

- $\left\{\left.\left(X_{n}\right)\right|_{\Sigma_{n}}\right\}_{n \in \mathbb{N}}$ converges to a $K$-immersion
$\mathbb{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}^{3}$ with Gauss map the identity map of $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$; denote by $S$ the image $K$-surface.
- $\left\{X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right\}_{n \in \mathbb{N}}$ converges to an open disc $D_{j}$ contained in a plane $\Pi_{j}$ orthogonal to $p_{j}$, with $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$,
- $\left\{\operatorname{Area}\left(X_{n}\left(A\left(p_{j}, 1 / n\right)\right)\right)\right\}_{n \in \mathbb{N}} \rightarrow 0 \Rightarrow \mathscr{S}=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$, and


## Existence

(1) $\mathscr{S}_{n}:=X_{n}\left(\mathrm{~S}^{2}\right)$ is a closed smooth strictly convex surface,
(2) the Gauss map of $X_{n}$ is the identity map of $S^{2}$,
(3) the curvature function of $X_{n}$ agrees $\kappa_{n}$; in particular $S_{n}:=X_{n}\left(\Sigma_{n}\right)$ is a $K$-surface,
(9) $\operatorname{Area}\left(X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right)=a_{j}$ for all $j$, and
(5) $\left\{\mathscr{S}_{n}\right\}_{n \in \mathbb{N}} \rightarrow \mathscr{S}:=\partial \mathscr{K}$.

- $\left\{\left.\left(X_{n}\right)\right|_{\Sigma_{n}}\right\}_{n \in \mathbb{N}}$ converges to a $K$-immersion
$\mathbb{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}^{3}$ with Gauss map the identity map of $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$; denote by $S$ the image $K$-surface.
- $\left\{X_{n}\left(B\left(p_{j}, 1 / n\right)\right)\right\}_{n \in \mathbb{N}}$ converges to an open disc $D_{j}$ contained in a plane $\Pi_{j}$ orthogonal to $p_{j}$, with $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$,
- $\left\{\operatorname{Area}\left(X_{n}\left(A\left(p_{j}, 1 / n\right)\right)\right)\right\}_{n \in \mathbb{N}} \rightarrow 0 \Rightarrow \mathscr{S}=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$, and
- the extrinsic conformal structure of $S$ is a circular domain in $\overline{\mathbb{C}}$.


## Application: Harmonic diffeomorphims

- Liouville There is no non-constant harmonic map $\mathbb{C} \rightarrow \mathbb{D}$, with the Euclidean metric.
- Heinz 1952 There is no harmonic diffeomorphism $\mathbb{D} \rightarrow \mathbb{C}$ with the Euclidean metric.


## Question (Schoen-Yau 1985)

Are Riemannian surfaces which are related by a harmonic diffeomorphism quasiconformally related?
In particular, are there harmonic diffeomorphisms from $\mathbb{C}$ onto the hyperbolic plane $\mathbb{H}^{2}$ ?

- Collin-Rosenberg 2010 There exists an entire minimal graph $\Sigma$ over $\mathbb{H}^{2}$ in the Riemannian product $\mathbb{H}^{2} \times \mathbb{R}$ with the conformal type of $\mathbb{C}$.
In particular, the vertical projection $\Sigma \rightarrow \mathbb{H}^{2}$ is a harmonic diffeomorphism from $\mathbb{C}$ into $\mathbb{H}^{2}$.


## Application: Harmonic diffeomorphims

## Theorem (Alarcón-S.; CMH, in press)

- For any $m \in \mathbb{N}, m \geq 2$, and any subet $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$ there exist a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.


## Application: Harmonic diffeomorphims

## Theorem (Alarcón-S.; CMH, in press)

- For any $m \in \mathbb{N}, m \geq 2$, and any subet $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$ there exist a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.
- There exists no harmonic diffeomorphism $\mathbb{D} \rightarrow S^{2}-\{p\}$, $p \in S^{2}$.


## Application: Harmonic diffeomorphims

## Theorem (Alarcón-S.; CMH, in press)

- For any $m \in \mathbb{N}, m \geq 2$, and any subet $\left\{p_{1}, \ldots, p_{m}\right\} \subset S^{2}$ there exist a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.
- There exists no harmonic diffeomorphism $\mathbb{D} \rightarrow S^{2}-\{p\}$, $p \in \mathrm{~S}^{2}$.
- The harmonic diffeomorphism $\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ appears as the vertical projection $\Sigma \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$, where $\Sigma$ is a maximal graph over $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ in the Lorentzian manifold $\mathrm{S}^{2} \times \mathbb{R}_{1}$, with $\Sigma \cong \mathcal{R}$.
- Such a maximal graph $\Sigma$ is constructed by solving Dirichlet problems.


## Application: Harmonic diffeomorphims

## Theorem (Alarcón-S.; CMH, in press)

- For any $m \in \mathbb{N}, m \geq 2$, and any subet $\left\{p_{1}, \ldots, p_{m}\right\} \subset S^{2}$ there exist a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.
- There exists no harmonic diffeomorphism $\mathbb{D} \rightarrow S^{2}-\{p\}$, $p \in S^{2}$.
- The harmonic diffeomorphism $\mathcal{R} \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ appears as the vertical projection $\Sigma \rightarrow S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$, where $\Sigma$ is a maximal graph over $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ in the Lorentzian manifold $S^{2} \times \mathbb{R}_{1}$, with $\Sigma \cong \mathcal{R}$.
- Such a maximal graph $\Sigma$ is constructed by solving Dirichlet problems.
- The non-existence of harmonic diffeomorphisms $\mathbb{D} \rightarrow S^{2}-\{p\}$ follows from K-surface theory.


## Application: Harmonic diffeomorphims

Corollary
Let $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$ with $\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}$ for some positive numbers $a_{1}, \ldots, a_{m}$.
Then there exists a circular domain $\mathcal{R}$ in $\overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.

- The Gauss map of the $K$-surface $S$ in (i) is such a harmonic diffeomorphism.


## Application: Harmonic diffeomorphims

Corollary
Let $\left\{p_{1}, \ldots, p_{m}\right\} \subset \mathbb{S}^{2}$ with $\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}$ for some positive numbers $a_{1}, \ldots, a_{m}$.
Then there exists a circular domain $\mathcal{R}$ in $\overline{\mathbb{C}}$ and a harmonic diffeomorphism $\mathcal{R} \rightarrow \mathbb{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$.

- The Gauss map of the $K$-surface $S$ in (i) is such a harmonic diffeomorphism.
- We do not know if those harmonic diffeomorphisms given as Gauss maps of $K$-surfaces in $\mathbb{R}^{3}$ and those given as vertical projections of maximal graphs in $S^{2} \times \mathbb{R}_{1}$ are the same or not.


## The support function

- The support function of $S$,

$$
h: S^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}, \quad h(p)=\left\langle p, N_{S}^{-1}(p)\right\rangle
$$

satisfies $\quad\left(\operatorname{det}\left(\nabla^{2} h+h \mathrm{I}\right)\right) \circ N_{S}=1(=1 / K) \quad$ on $S$.

## The support function

- The support function of $S$,

$$
h: S^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}, \quad h(p)=\left\langle p, N_{S}^{-1}(p)\right\rangle
$$

satisfies $\quad\left(\operatorname{det}\left(\nabla^{2} h+h \mathrm{I}\right)\right) \circ N_{S}=1(=1 / K) \quad$ on $S$.

- A parameterization $X: \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}^{3}$ of $S$ is given by

$$
X(p)=\nabla h(p)+h(p) p
$$

## Application: A Hessian equation

- Fully nonlinear, elliptic second order partial differential equations of the form

$$
\mathscr{F}[h]:=F\left(\nabla^{2} h+A(\cdot, h, \nabla h)\right)=B(\cdot, h, \nabla h) \quad \text { on } \Omega \subset \mathcal{M}
$$

have been objective of considerable interest in recent years.

## Application: A Hessian equation

- Fully nonlinear, elliptic second order partial differential equations of the form

$$
\mathscr{F}[h]:=F\left(\nabla^{2} h+A(\cdot, h, \nabla h)\right)=B(\cdot, h, \nabla h) \quad \text { on } \Omega \subset \mathcal{M}
$$

have been objective of considerable interest in recent years.

- The space of solutions to the Hessian one equation

$$
\operatorname{det} \nabla^{2} h=1 \quad \text { on } \mathbb{R}^{2}-\left\{q_{1}, \ldots, q_{k}\right\}
$$

was described by Gálvez-Martínez-Mira 2005 (Jorgens 1955 for $k=1$ ).

- Jorgens 1954 The only solutions for $k=0$ are quadratic polynomials.


## Application: A Hessian equation

- Two solution $u$ and $v$ of the Hessian equation

$$
\operatorname{det}\left(\nabla^{2} h+h \mathrm{I}\right)=1 \quad \text { on } \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

are equivalent, $u \sim v$, if $u-v$ is the restriction to $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ of a linear function of $\mathbb{R}^{3}$.

## Application: A Hessian equation

- Two solution $u$ and $v$ of the Hessian equation

$$
\operatorname{det}\left(\nabla^{2} h+h \mathrm{I}\right)=1 \quad \text { on } \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

are equivalent, $u \sim v$, if $u-v$ is the restriction to $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ of a linear function of $\mathbb{R}^{3}$.

## Corollary

The space of equivalence classes of solutions of the above equation, under $\sim$, with non-removable singularities at the points $\left\{p_{1}, \ldots, p_{m}\right\}$, is in bijection with the set $\left\{\left(a_{1}, \ldots, a_{m}\right) \in \mathbb{R}^{m} \mid a_{j}>0 \forall j, \sum_{j=1}^{m} a_{j} p_{j}=0\right\}$.

## Application: A Hessian equation

- Two solution $u$ and $v$ of the Hessian equation

$$
\operatorname{det}\left(\nabla^{2} h+h \mathrm{I}\right)=1 \quad \text { on } \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

are equivalent, $u \sim v$, if $u-v$ is the restriction to $S^{2}-\left\{p_{1}, \ldots, p_{m}\right\}$ of a linear function of $\mathbb{R}^{3}$.

## Corollary

The space of equivalence classes of solutions of the above equation, under $\sim$, with non-removable singularities at the points $\left\{p_{1}, \ldots, p_{m}\right\}$, is in bijection with the set $\left\{\left(a_{1}, \ldots, a_{m}\right) \in \mathbb{R}^{m} \mid a_{j}>0 \forall j, \sum_{j=1}^{m} a_{j} p_{j}=0\right\}$.

- $h: S^{2}-\left\{p_{1}, \ldots, p_{m}\right\} \rightarrow \mathbb{R}$ is solution to the equation iff it is the support function of a surface $S$ as those in the theorem.
- The only solution for $m=0$ is the round sphere and there is no solution for $m=1$.


## Application: Capillary surfaces

- A capillary surface in a region $\mathcal{B}$ in $\mathbb{R}^{3}$ is a compact CMC surface meeting $\partial \mathcal{B}$ at a constant angle $\gamma \in[0, \pi]$ along its boundary. They model liquid drops inside a container in the absence of gravity.
- Capillary surfaces is a topic with large literature. Wente 1995, McCuan 1997, and Park 2005 studied capillary surfaces in polyhedral regions of $\mathbb{R}^{3}$.


## Application: Capillary surfaces

- A capillary surface in a region $\mathcal{B}$ in $\mathbb{R}^{3}$ is a compact CMC surface meeting $\partial \mathcal{B}$ at a constant angle $\gamma \in[0, \pi]$ along its boundary. They model liquid drops inside a container in the absence of gravity.
- Capillary surfaces is a topic with large literature. Wente 1995, McCuan 1997, and Park 2005 studied capillary surfaces in polyhedral regions of $\mathbb{R}^{3}$.
- The outer parallel surface at distance 1 to a $K$-surface is a CMC surface with $H=1 / 2$ (i.e., an $H$-surface).


## Application: Capillary surfaces

- Let $\left\{p_{1}, \ldots, p_{m}\right\}$ be a subset of $S^{2}$.


## Corollary

The following statements are equivalent:
(i) There exists a (positively curved) $H$-surface $S \subset \mathbb{R}^{3}$ whose intrinsic conformal structure is a circular domain $\mathcal{R} \subset \overline{\mathbb{C}}$ and its Gauss map is a harmonic diffeomorphism

$$
\mathcal{R} \rightarrow \mathrm{S}^{2}-\left\{p_{1}, \ldots, p_{m}\right\}
$$

(ii) There exist positive real constants $a_{1}, \ldots, a_{m}$ such that

$$
\sum_{j=1}^{m} a_{j} p_{j}=0 \in \mathbb{R}^{3}
$$

## Application: Capillary surfaces

## Corollary

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{S}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.
In addition, given $\left(a_{1}, \ldots, a_{m}\right)$ satisfying (ii), there exists a unique, up to translations, $H$-surface $S$ satisfying (i) such that $\operatorname{Area}\left(D_{j}\right)=a_{j}$ for all $j$.

## Application: Capillary surfaces

## Corollary

Furthermore, if $S$ is as above and $\gamma_{j}$ denotes the component of $\bar{s}-S$ corresponding to $p_{j}$ via the Gauss map, then
(I) $\gamma_{j}$ is a Jordan curve contained in an affine plane $\Pi_{j} \subset \mathbb{R}^{3}$ orthogonal to $p_{j}$, and
(II) $\mathscr{S}:=S \cup\left(\cup_{j=1}^{m} \bar{D}_{j}\right)$ is the boundary surface of a smooth convex body in $\mathbb{R}^{3}$, where $D_{j}$ denotes the bounded component of $\Pi_{j}-\gamma_{j}$.
In addition, given $\left(a_{1}, \ldots, a_{m}\right)$ satisfying (ii), there exists a unique, up to translations, $H$-surface $S$ satisfying (i) such that Area $\left(D_{j}\right)=a_{j}$ for all $j$.

- In particular, $S$ is an embedded $H$-surface of genus zero which meets tangentially all the faces of the polyhedral region determined by the affine planes $\Pi_{j}, j=1, \ldots, m$.

