

Why we need Control Theory ?

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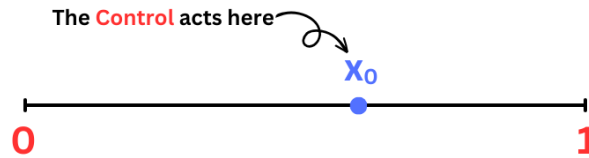
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Abstract

The main objective of this talk is to discuss some motivations for the control theory of partial differential equations. As an application, we will treat the case of the following one-dimensional degenerate/singular heat equation

$$\begin{cases} y_t - (x^\alpha y_x)_x - \frac{\mu}{x^{2-\alpha}} y = \delta_{x_0} v(t), & (t, x) \in Q = (0, T) \times (0, 1), \\ y(t, 0) = y(t, 1) = 0, & t \in (0, T), \\ y(0, x) = y_0(x), & x \in (0, 1), \end{cases} \quad (\text{P})$$

- $v(t)$: Control function,
- $x_0 \in (0, 1)$: control region,
- δ_{x_0} : the Dirac delta function,
- $0 \leq \alpha < 1$, $\mu \leq \mu(\alpha) = \frac{(1-\alpha)^2}{4}$,
- $T > 0$: Target time fixed,
- $y_0 \in L^2(0, 1)$.



keywords: Controllability, degenerate equations, singular potential, moment method.

References

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