

International Doctoral Summer School in
Conformal Geometry and Non-local operators

June 19-30, 2023. IMAG - Granada

Xavier Cabré (ICREA & UPC)

On the nonlocal mean curvature

Or:

Michael-Simon type
Sobolev inequalities and
applications to local and
nonlocal mean curvature
problems.

• PLAN (detailed :)

1. The Euclidean isoperimetric inequality

2. The Michael-Simon (MS) and Allard Sobolev Ineq.

3. The fractional Sobolev inequality (and a geometric
version)

4. Fractional perimeter and nonlocal mean curvature (MLC)

5. Density estimate and application: fract. MS ineq.

6. Appl'n. gradient estimate for nonl. minimal surf.

7. Appl'n of MS Sobolev ineq's): extinction time for
(nonlocal) mean curvature flow (7 not taught)

8. Foliations by nonlocal minimal surfaces: minimality
and viscosity property. Calibration for the fract. perimeter

9. Calibration for the fract. Laplacian.) 8&9 not
covered

• General plan: A-local & nonlocal Michael-Simon Sob. ineq.

B-Appl'n: gradient estimate for nonl. min. graphs

C-Appl'n: extinction time for (nonl.) MCF flow.

D-Foliations and nonlocal calibrations.

1. The Euclidean Isop. Ineq.

Thm 1 $E \subset \mathbb{R}^n$ smooth & ^{open} bounded \Rightarrow

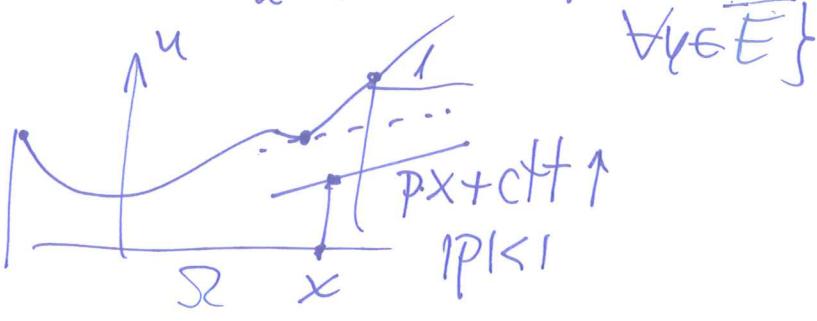
$$(1) \quad \frac{|\partial E|}{|E|^{\frac{n-1}{n}}} \geq \frac{|B_1|}{|B_1|^{\frac{n-1}{n}}} (= n |B_1|^{\frac{1}{n}}) \quad \& \text{eq. iff } E \text{ is a ball}$$

• Proof (Cabré 1996. See [Cabré, Isoperimetric... survey, Chin. Ann. Math. 2017])

$$\left\{ \begin{array}{l} \Delta u = \frac{|\partial E|}{|E|} \\ u_\nu = 1 \end{array} \right.$$

Claim $B_1(0) \subset \nabla u(\Gamma_u)$ (Exercise 1)

where $\Gamma_u = \{x \in E : u(y) \geq u(x) + \nabla u(x) \cdot (y-x) \quad \forall y \in E\}$



$$|B_1| \leq |\nabla u(\Gamma_u)| \leq \int_{\Gamma_u} |\operatorname{Jac} \nabla u| dx = \int_{\Gamma_u} \underbrace{\det D^2 u}_{\geq 0} dx$$

$$\int_{\Gamma_u} dP \stackrel{\text{area formula: }}{=} \int_{\Gamma_u} \left(\frac{\Delta u}{n} \right)^n dx \leq \left(\frac{|\partial E|}{n |E|} \right)^n |E| . \square$$

$$\text{Note: } E = B_1 \rightarrow u(x) = \frac{|x|^2}{2} + \text{ctf}$$

Analyze \Leftarrow in proof \Rightarrow iff. \square

2. The Michael-Simon (MS) & Allard Sob. ineq.

Classical perimeter functional
 \downarrow 1st variation
 Mean curvature = H .

Minimal surfaces : $H=0$

• 1967, M. Miranda proved

$M = M_n \cap \mathbb{R}^{n+1}$ is a min. surface &
 $E \subset M$ smooth } open bold $\Rightarrow |DE| \geq c(n) \cdot |E|^{\frac{n-1}{n}}$
 for some dimnl. cst. $c(n)$.

• Extension: Michael-Simon & Allard, independ.
 $\xrightarrow{1972}$

Theorem 2 (MS & Allard, '72)

(2) $M \subset \mathbb{R}^{n+1}$ smooth hypersurface, $E \subset M$ smooth open
 bold set. \Rightarrow
 $|E|^{\frac{n-1}{n}} \leq c(n) \left\{ |DE| + \int_E |H| \right\}$.

Before proving it,

Corollary 3 (MS Sobolev ineq) $M \subset \mathbb{R}^{n+1}$ smooth hyper.
 $u \in C_c^1(M)$, $1 \leq p < n \Rightarrow (P^* = \frac{np}{n-p})$

(3) $\left(\int_M |u|^{p^*} \right)^{1/p^*} \leq c(n) \left(\int_M |\nabla u|^p + \int_M |H|^p |u|^p \right)^{1/p}$
 ↪ tangential gradient.

-4-

• Proof of Thm 2, following

① [Cabré-Miraglio], Universal Hardy-Sobolev... Comm. Cont. Math. 2022]

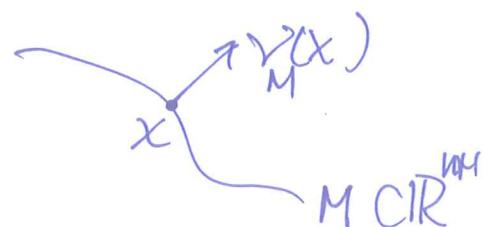
Exercise 2

Learn basics of Riemannian Geometry or, if not, tangential derivatives as in [Giga, Min. Surf...].
↑ same approach as ②

$x \in M, \lambda > 0 \rightarrow \lambda x \in M$
has volume = $\lambda^n \text{vol}(M)$

Exercise 3: $\boxed{\text{div}_T x = n}$

Also $H = \text{div}_T v_M$. So,



$$n = \text{div}_T x = \text{div}_T (x_T + (x \cdot v_M) v_M)$$

$$= \text{div}_T x_T + \nabla_T(x \cdot v_M) \cdot v_M + (x \cdot v_M) H$$

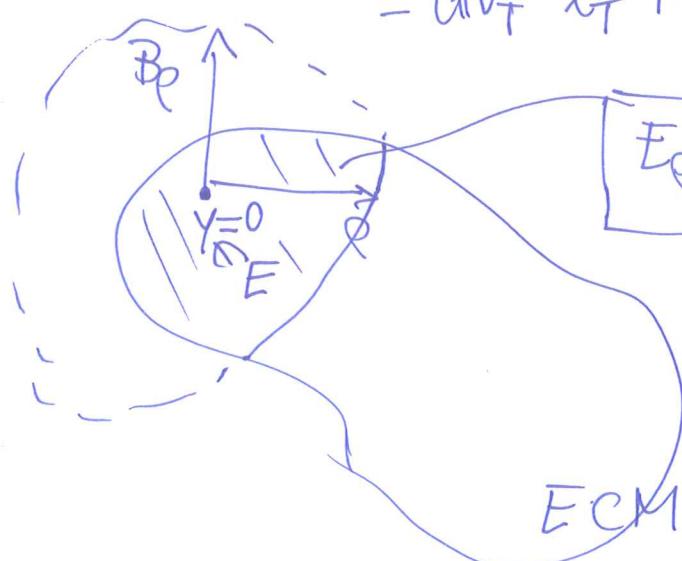
$$\boxed{E_\rho = E \cap B_\rho, B_\rho = B_\rho^{n+1}}$$

$$n |E_\rho| = \int_{E_\rho} \text{div}_T x \, dV =$$

$$= \int_{\partial E_\rho} x_T \cdot v_E \, dA + \int_{E_\rho} (x \cdot v_M) H \, dV$$

$$1.1 \leq \rho$$

$$\leq C |\partial E_\rho| + \epsilon \int_{E_\rho} |H| \, dV.$$



$$|\partial E_\rho| = |\partial B_\rho \cap E| + |\partial E \cap B_\rho|$$

$$\leq \frac{d}{d\rho} |E_\rho| + |\partial E \cap B_\rho| \Rightarrow$$

$$\frac{d}{d\rho} (-\rho^{-n} |E_\rho|) \leq \bar{\rho}^{-n} \left\{ |\partial E \cap B_\rho| + \int_{B_\rho} |H| dV \right\} \Leftrightarrow$$

$$\frac{d}{d\rho} \left(\bar{\rho}^{-n} |E_\rho| \exp \int_0^\rho \frac{|\partial E \cap B_\sigma| + \int_{B_\sigma} |H| dV}{|E_\sigma|} d\sigma \right) \geq 0$$

$$\bar{\rho}^{-n} |E_\rho| \exp \int_0^\rho \dots \geq \lim_{\rho \rightarrow 0} \frac{|E_\rho|}{\rho^n} = |B_1^n| = w_n$$

$$\text{choose } \rho_0 := (2|E|w_n^{-1})^{1/n} \rightarrow$$

$$\exp \int_0^{\rho_0} \frac{|\partial E \cap B_\sigma(y)| + \int_{B_\sigma} |H| dV}{|E_\sigma|} d\sigma \geq \rho_0^n w_n |E_{\rho_0}|^{-1} \geq \rho_0^n w_n |E|^{-1} = 2.$$

Hence:

$\forall y \in E \exists r(y) \in (0, \rho_0)$ st.

$$\rho_0 (|\partial E \cap B_{r(y)}(y)| + \int_{E_{r(y)}} |H| dV) \geq |E_{r(y)}| \log 2.$$

$$|E_{r(y)}| \leq \text{(c)} |E|^{\frac{n}{n}} \left\{ |\partial E \cap B_{r(y)}(y)| + \int_{E_{r(y)}} |H| dV \right\}$$

Finally, Besicovitch ^{sub}covering of $\cup B_{r(y)}(y) \supset E$ \rightsquigarrow countable collection $\{B_{r(y_i)}\}_{y \in E}$. st

$E \subset \bigcup_i B_{r(y_i)}$ & st. every pt of E belongs at most to $N(n)$ balls $B_{r(y_i)}$ \square

Theorem of [Simon Brendle, JAMS, 2021]

The Euclidean constant in the isop. ineq. is also OK (and thus it is the optimal constant) in the isop. ineq. on any minimal surface (and also in the MS Sobolev ineq. for $p=1$ on any hypersurf. $M_n \subset \mathbb{R}^{n+1}$)

The proof is a very clever extension of the one of Cabré in Thm 1 above. One starts solving

$$\begin{cases} \Delta u = \frac{|2E|}{|E|} & \text{in } E \subset M \\ u_\nu = 1 & \text{on } \partial E. \end{cases}$$

add artificial variable

One then takes $M \subset \mathbb{R}^{n+1} \subset \mathbb{R}^{n+2}$

Let $T_x^+ M$ be the normal bundle to $T_x M$ in \mathbb{R}^{n+2} . Thus $\dim(T_x^+ M) = 2$

One considers the map

$$(x, y) \in E \times T_x^+ M \rightarrow \mathbb{R}^{n+2}$$

$$\underbrace{\quad}_{\mathcal{T}} \rightarrow \phi(x, y) = \nabla u(x) + y$$

and the set $\{(x, y) : |\nabla u(x)|^2 + |y|^2 < 1\}$
 instead of $\{x : |\nabla u(x)| = |\rho| < 1\}$.

1st lecture
1/2 h

3. The fract. Sobolev ineq. (and a geometric version).

Prop 4 (Fractional Sob. ineq. on hypersurfaces "with density")

$n \geq 1, s \in (0,1), p \geq 1$ st $\boxed{sp < n}$.

(4) $M \subset \mathbb{R}^{n+1}$ hypersurface st $\exists c_* > 0$ (a diff) &

$$|M \cap B_\rho^n(x_0)| \geq c_* \rho^n \quad \forall \rho > 0 \quad \forall x_0 \in M.$$

Then, for all $u \in C_c^1(M)$, $(P_s^* = \frac{np}{n-sp})$

$$(5) \quad \left(\int_M |u|^{P_s^*} \right)^{\frac{1}{P_s^*}} \leq C \left(\iint_{M \times M} \frac{|u(x) - u(y)|^p}{|x-y|^{n+sp}} dV(x) dV(y) \right)^{\frac{1}{p}}$$

with $C = C(n, s, p, c_*)$.

In particular (4) and (5) hold if $\boxed{M = \mathbb{R}^n / (\mathbb{C} \mathbb{R}^{n+1})}$

(Note: c_* depends on the geom. of M \ddagger)

$$\& c_* = c_*(n).$$

• Proof by Brezis, unpub. 2001

↳ adapted to hypersurf. in

$B_r = B_r^{n+1}$
NOTATION

[Cabré & Cozzi, A gradient estimate... Duke M.J. 2019]

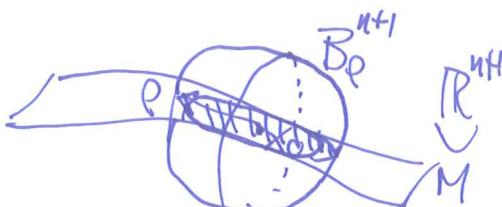
see also [Cabré - Cozzi - Csató, A fract. MS., AIMPS 2022.]

$$|u(x)| \leq |u(x) - u(y)| + |u(y)| \quad ; \quad \forall r > 0 \rightarrow$$

$$|u(x)| \leq \int_{M \cap B_r(x)} |u(x) - u(y)| dV(y) + \int_{M \cap B_r(x)} |u(y)| dV(y)$$

↓

$$\left\{ \begin{array}{l} \textcircled{1} \leq \left(\int_{M \cap B_r(x)} |u(x) - u(y)|^p dV(y) \right)^{\frac{1}{p}} \leq (r^{n-sp} \int_{M \cap B_r(x)} \frac{|u(x) - u(y)|^p}{|x-y|^{n+sp}} dV(y))^{\frac{1}{p}} \\ \textcircled{2} \text{ Jensen} \Rightarrow \end{array} \right.$$



NOTE: If $P=1$ & $E \subset \mathbb{R}^n$ bdd & $u = \chi_E$ (by density), then (5) says $|E|^{\frac{n-s}{n}} \leq C(n,s) \int_E \int_{\mathbb{R}^{n-s} \setminus E} \frac{1}{|x-y|^{n+s}} dxdy$

$$|u(x)| \leq c \left\{ r^s \left(\int_M \frac{|u(x)-u(y)|^P}{|x-y|^{n+sp}} dV(y) \right)^{1/p} + r^{-\frac{n}{ps}} \left(\int_M |u(y)|^{ps} dV(y) \right)^{1/ps} \right\}$$

fract. perimeter
ols in section 4

optimize in r

$$r(x) := \left(\int_M |u(y)|^{ps} dV(y) \right)^{\frac{ps}{nps}} \left(\int_M \frac{|u(x)-u(y)|^P}{|x-y|^{n+sp}} dV(y) \right)^{-\frac{1}{n}}$$

$$|u(x)| \leq c \left(\int_M \frac{|u(x)-u(y)|^P}{|x-y|^{n+sp}} dV(y) \right)^{\frac{ps}{nps}} \left(\int_M |u(y)|^{ps} dV(y) \right)^{\frac{sp}{nps}}$$

Now, $\int_M dV(x)$ \square .

DEF $[u]_{W^{s,p}(M)} \quad \begin{cases} 0 \leq s \leq 1 \\ p \geq 1 \end{cases}$

4. Fractional perimeter & NMC (non-local mean conv.)

As introduced in the seminal paper

- Caffarelli - Roquejoffre - Savin, Nonlocal min. surfaces, CPAM 2010]

Def 5 Fractional perimeter $E \subset \mathbb{R}^N$ (sometimes we will take $N=n+1$)
 L open set \quad others $N=n$)

$$P_{N,\alpha}(E) = C_{N,\alpha} \int_E \int_{E^c} \frac{1}{|x-y|^{N+\alpha}} dy dx ; \quad E^c = \mathbb{R}^N \setminus E$$

$$C_{N,\alpha} \approx C \cdot (1-\alpha) \text{ as } \alpha \uparrow 1 \Rightarrow P_{N,\alpha}(E) \xrightarrow{\alpha \uparrow 1} \frac{|2E|}{N} = \text{Per}(E)$$

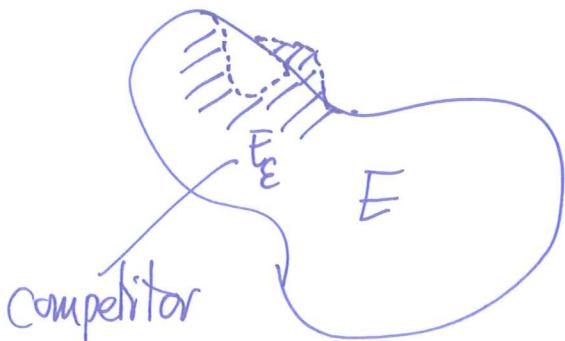
Finite if E open bdd smooth



- 9 -

$$A, B \subset \mathbb{R}^N \rightsquigarrow L(A, B) := \int_A dx \int_B dy \frac{1}{|x-y|^{N+\alpha}} = L(B, A)$$

Euler-Lagrange (or 1st vari) of fract. perimeter under volume constraint: fractional isop. pb



Compare fract. perimeters:



4 disjoint sets:

$$P(E) = L(E_1, E_3) + L(E_1, E_4)$$

$$\text{at } \partial E \rightarrow P(E) = L(E_1, E_3) + L(E_2, E_4)$$

$$P(E_E) = L(E_1, E_2) + L(E_1, E_4) \\ + L(E_3, E_2) + L(E_3, E_4)$$

$$0 \geq L(E_3, E_1) - L(E_3, E_4)$$

$$- (L(E_2, E_1) - L(E_2, E_4)) =$$

balls min. fract. per. under given volume: Gauss-Rademich 1974 [rearrangement]

Frank-Seininger '08 $(X_E - X_{E^c})(y)$

$$\int_{E_3} dx \int_{\mathbb{R}^N} dy \frac{X_{E_1}(y) - X_{E_4}(y)}{|x-y|^{N+\alpha}}$$

$$|E_2| = |E_3|$$

$$E_2 \& E_3 \downarrow x \in \partial E$$

$$- \int_{E_2} dx \int_{\mathbb{R}^N} dy \frac{X_{E_1}(y) - X_{E_4}(y)}{|x-y|^{N+\alpha}}$$

$$\forall x \in \partial E$$

$$\text{Def 6} \quad H_{\alpha, E}(x) := C_{N, \alpha} \text{PV} \int_{\mathbb{R}^N} \frac{X_{E^c}(y) - X_E(y)}{|x-y|^{N+\alpha}} dy = NMC \text{ at } x$$

CNMC surfaces [= eff] for minimizers with vol. constraint

sometimes we do
not write off

-10-

$$H_{d,E}(x) = \int_{\mathbb{R}^N} \frac{\chi_{E^c}(y) - \chi_E(y)}{|x-y|^{N+\alpha}} dy$$

Exercise 4: div thm

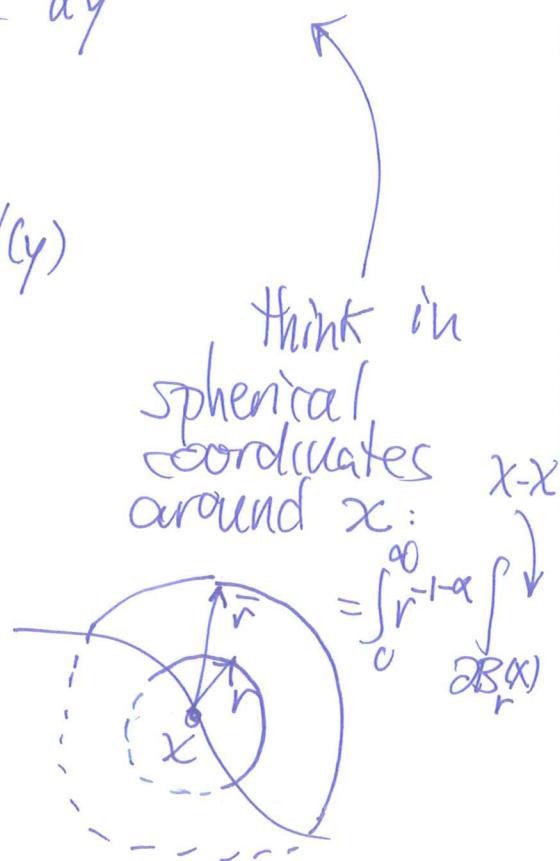
Prove

$$\oint_E -\frac{2}{\alpha} \int_{\partial E} \frac{(x-y) \cdot \nu_E(y)}{|x-y|^{N+\alpha}} d\mathcal{H}(y)$$

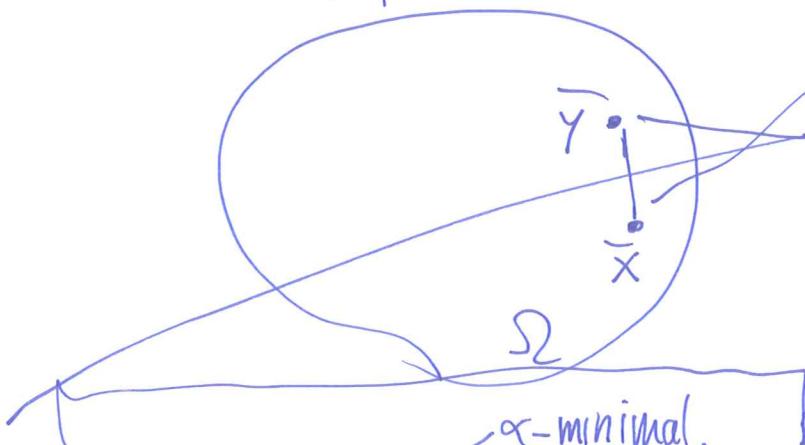
[balls have off NMC]
cylinders " " "

$$= (-\Delta)^{\alpha/2} (\chi_E - \chi_{E^c})(x)$$

fract. Lapl. of order α
 $\alpha/2 \in (0, 1/2)$!!



- NMC appeared in Caff-Savardis as limit ESO of fractional (Allen-Cahn heat eq'n).
volume mean corr. flow.
- Minimizers with no constraint. The Dirichlet (or Plateau) pb in $S \subset \mathbb{R}^N$.



forbidden. But:
equilibrium everybody
Minimize fract. perimeter among sets that agree with E outside S^1 :

Note: In these notes, non-minimal α -minimal surface \equiv minimizing α -min. surface.

$\sim 11.-$

$FOR^N \text{ st } FIS = EIS \text{ (given } ECR^N \text{ "fixed")}$

↙ Plateau or Dir.
extender pb.

Def 7 Relative fract. perimeter
(relative to S^c) :

$$\boxed{P_\alpha(E; S^c) = L(S^c \cap E, S^c \setminus E) + L(S^c \cap E^c, S^c \setminus E^c) + L(S^c \cap E^c, S^c \setminus E)}$$

they solve
 $NMC = H(E) = 0$
 $\forall x \in \partial E$
weak visc.
sense:
nonlocal
min. surf.

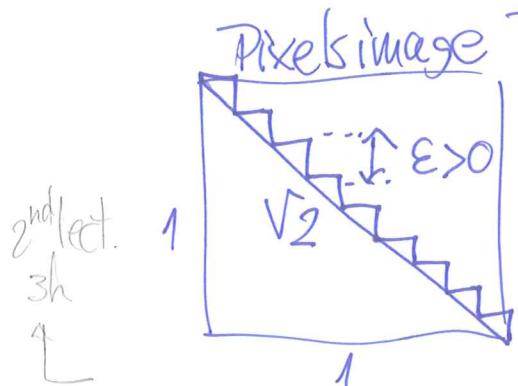
[CRS, 2010] prove:

- \exists of minimizer (l.s.c.)
- Density estimate (see section 5)
- EL eqn in visc. sense
- Improvement of flatness
- Ext. pb & monotonicity formula
- Dimension reduction

Main later contrib by
Valdinoci, Savin, Figalli,
Serra, Cinti, Cabré, ...

Thm [CRS]
NMS minimizers are $C^{1,\alpha}$ except
for a set of H^{N-2} dimension.

- Nonlocal or fract. perimeter methods are also very relevant in Image Processing



$$Per^{(\epsilon)}(\text{diagonal}) = 2\sqrt{2} \quad \forall \epsilon > 0$$

$$Per_\alpha^{(\epsilon)}(\text{diagonal}) \xrightarrow{\epsilon \downarrow 0} Per_\alpha(\text{diagonal}) \quad \forall \alpha \in (0,1)$$

$\downarrow \alpha \uparrow 1$

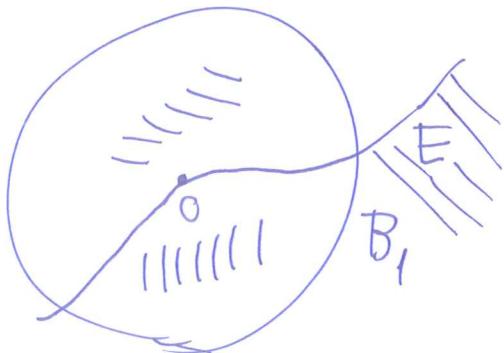
$\sqrt{2}$

5. Density estimate and an application:
fract. MS iueq. on nonl. min. surfaces.

Thm 8 (density estimate, both for min. surf & nonl. min. surf. \leftarrow [EGRS '10])

If the minimizing surface ∂E in B_1 passes through $O \in \mathbb{R}^N$, i.e., $O \in \partial E$, then

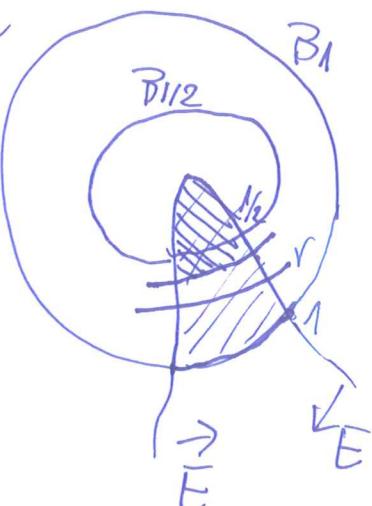
$$|E \cap B_1| \geq c(N, \alpha) > 0 \quad \& \quad |E^c \cap B_1| \geq c(N, \alpha) > 0.$$

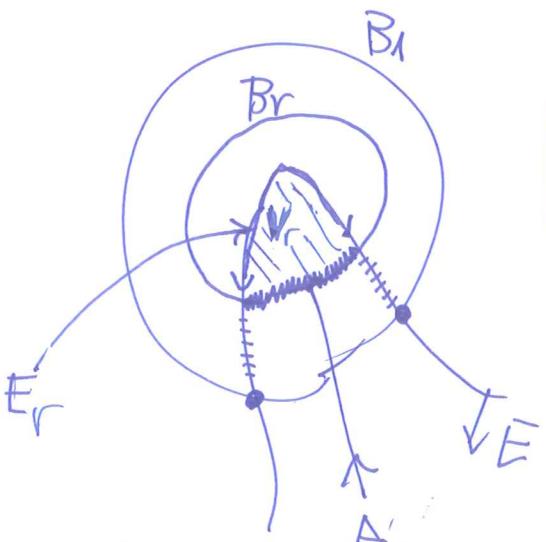


detailed

Proof (see [EGRS '10] for clear proof in nonl. case)

By contradiction assume
 $|E \cap B_1|$ small. Then
we prove E does
not arrive to 0.





-13- Tsop. ineq. \oplus Minimality of E

$$\left| \frac{1}{C} V_r^{\frac{N}{N-1}} \right| \leq |\partial V_r| = |E_r| + |A_r| \leq 2 |A_r| \quad \left[\frac{d}{dr} V_r \right]$$

$$C \leq V_r^{\frac{N}{N-1}} = N (V_r^{\frac{1}{N}})^N$$

$$\frac{C}{N} \frac{1}{2} = \frac{C}{N} \int_{V_1}^{V_r} dr \leq \int_{V_1}^{V_r} (V_r^{\frac{1}{N}})^N dr$$

$$= V_1^{\frac{N}{N}} - V_{\frac{1}{2}}^{\frac{N}{N}}$$

Nonlinear ODE that gives

$$|E \cap B_1| = V_1 \text{ small} \Rightarrow V_{\frac{1}{2}} = 0$$

$\epsilon^{(n)}$

$$E \cap B_{1/2} = \emptyset \quad \square$$

Now, from Thm 8 (density est) and the relative Tsop ineq.

$$|\partial E \cap B_1|^{\frac{N}{N-1}} \geq c(N) \min(|E \cap B_1|, |E^c \cap B_1|)$$

$$\geq c(N) \text{ (or } c(N, \alpha))$$



and thus the density estimate (4) for the fract. Sob. ineq. holds (after rescaling). Hence:

Corol 9: The fract. Sobolev ineq. (5) holds on every minimizing nonlocal α -minimal surface

$$\forall \delta \in (0, 1) \quad \forall s \in (0, 1) \quad (\text{take } M = \partial E \cap \overset{\wedge}{\mathbb{R}^{n+1}} \cap \overset{\wedge}{\mathbb{R}^N}; N = n+1)$$

6. Appl'n 1 (of fract MS ineq): a gradient estimate for nonl. min. graphs.

Theorem 10 [C-Cozzi DMJ 2019] $u: \mathbb{R}^n \rightarrow \mathbb{R}$

$$E = \{(x^1, x_{n+1}) \in \mathbb{R}^n \times \mathbb{R} : x_{n+1} < u(x^1)\} \subset \mathbb{R}^{n+1}, n \geq 1, \alpha \in (0, 1).$$

∂E nonl. α -min. surface in $B_{2r}^1 \times \mathbb{R}$. \Rightarrow

$\Rightarrow \text{vec}^\infty(B_r^1)$ &

$$\|\nabla_{x^1} u\|_{L^\infty(B_r^1)} \leq C(n, \alpha) \left(1 + \frac{\text{osc}_{B_r^1} u}{r}\right)^{n+1+\alpha}.$$

smoothness was only known for $n=1, 2$ (Savin, Figalli, Vald.)

- In the local case, the r.h.s. is $\exp(\text{osc})$ instead of power: $n=2$ [Finn, 1963]
- $n \geq 3$ [Bombieri - De Giorgi - Miranda, 1969].

Main ideas of the proof

\otimes LOCAL CASE: $H=0$ (1st var. of perim) $M = \partial E$
min. surf.

Jacobi opr: $Jv = (\Delta_{LB} + |A|^2)v$ (2nd var. of perim)

\nearrow Linearity. \downarrow

$\sqrt{M} \xrightarrow{e_k} \sqrt{M+e_k}$ \uparrow Second. fund. form of the
min. surf $M = k_1^2 + \dots + k_n^2$.

$H=0$ is invariant by translations & $e_k \cdot v_E^K = v_E^K \Rightarrow$
Every component v_E^K of the normal to M solves
the Jacobi eqn: $\int J v_E^K = 0$ in $M \quad \forall K \in \{1, \dots, n+1\}$

-15-

⊕ NONLOCAL CASE ($M = \partial E$)

$$\text{Jacobi operator : } J_\alpha v = \left(\mathcal{L}_{\frac{1+\alpha}{2}} + C_{\frac{1+\alpha}{2}}^2 \right) v = \left(\mathcal{L}_S + C_S^2 \right) v$$

where $S = \frac{1+\alpha}{2} \in (\frac{1}{2}, 1)$

$$\left\{ \begin{array}{l} \mathcal{L}_{\frac{1+\alpha}{2}} v(x) := \int_M \frac{v(y) - v(x)}{|x-y|^{n+1+\alpha}} dV(y) \\ C_{\frac{1+\alpha}{2}}^2(x) := \int_M \frac{\langle v_E(x) - v_E(y), v_E(x) \rangle}{|x-y|^{n+1+\alpha}} dV(y). \end{array} \right.$$

Translation invariance of $H_\alpha = 0 \Rightarrow$

Lemma 11 (see Thm 1.3(i), and the key computation in Prop 4.1, both of [C-Cozzi, 2019])

$$J_\alpha v_E^k = 0 \text{ in } M = \partial E \quad \forall k \in \{1, \dots, n+1\}.$$

$$\text{Now } 0 = J_\alpha v_E^{n+1} = \mathcal{L}_S v_E^{n+1} + C_S(x) v_E^{n+1} \geq \left(\mathcal{L}_S \right) v_E^{n+1}$$

$$\left. \begin{array}{l} M \text{ is a graph } x_{n+1} = u(x') \\ \Rightarrow v_E^{n+1} = \frac{1}{\sqrt{1 + |\nabla_{x'} u|^2}} > 0 \text{ in } \mathbb{T}^n \end{array} \right\} \begin{array}{l} \text{"kind" of} \\ \text{-fract. Lapl} \\ (-\Delta_M)^s \end{array}$$

Hence, $0 < v_E^{n+1}$ is a positive supersolution of the fract. eqn $\mathcal{L}_S v_E^{n+1} = 0$ in M .
(\leq)

Now, since we have a fractional Sobolev inequality on the graph $M = \partial E$, a fractional version of the Moser iteration technique (first done in \mathbb{R}^n by M. Kassmann,) to get a weak Harnack inequality (see [GT] for local case) & show [Gilbarg-Trud.]

Prop 12 [C-Cozzi 2019]

$$\inf_{\partial E \cap B_1} V_E^{n+1} \geq C_{n+1} \left\{ \int_{\partial E \cap B_1} V_E^{n+1}(y) dV(y) + \int_{\partial E \setminus B_1} \frac{V_E^{n+1}(y)}{|y|^{n+1+\alpha}} dV(y) \right\}.$$

Since $\inf_{\partial E} V_E^{n+1} = \frac{1}{\sup_{\mathbb{R}^n} |1+|\nabla_x u|^2|}$ { gives immediately the grad. estimate. }
 ... easy lower bdd.

3d/last
lect
4 1/2 h
↑

7. Appl'n 2 (of fract MS inequalities) : extinction

times for (nonlocal) mean curvature flow.

The local case : see [Evans, Regularity... LNM 1660, (1999)]

Let $\{\Gamma_t\}_{0 \leq t \leq T^*}$ be a smooth flow of hypersurfaces

of \mathbb{R}^{n+1} flowing by MCF (mean curvature flow) :

"The surface flows with speed in the normal direction equal to $-H = -H(\Gamma_t)$ " (shrinkage)

This is a parabolic flow enjoying comparison principle. Thus,

if $\vec{T}_0 \subset B_R = B_R(0)$, then $\vec{T}_t \subset B_{R(t)}$

where

$$R(t) = (R^2 - 2nt)^{\frac{1}{2}}$$

since $R(t) = 0$ for $t = R^2/(2n)$

Extinction time $= T^* \leq C(n) \operatorname{diam}(\vec{T}_0)^2$

A better estimate, got using the MS ineq:

Propn 13 $\{\vec{T}_t\}_{0 \leq t \leq T^*}$ smooth MC flow in \mathbb{R}^{n+1}

Then, $T^* \leq C(n) |\vec{T}_0|^{\frac{2}{n}}$.

Proof: $\frac{d}{dt} |\vec{T}_t| = - \int_{\vec{T}_t} \langle \vec{v}, \vec{H} \rangle dV_t$ ←
 \vec{v} MC vector $= H \cdot \vec{v}_{T_t}$
velocity of flow ($= H v_H$)

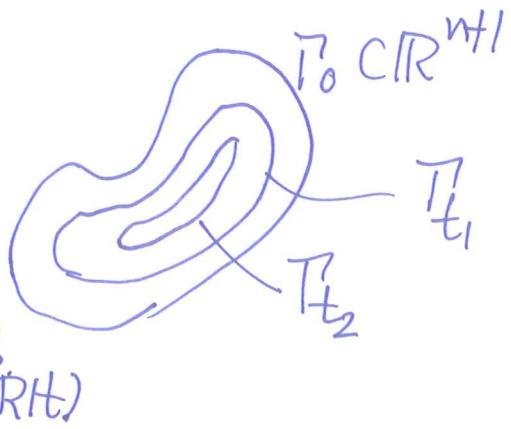
$$= - \int_{\vec{T}_t} |H|^2 dV_t \leq$$

$$\leq -C(n) |\vec{T}_t|^{\frac{n-2}{n}}.$$

General result
 (see [Ecker], [Guan-Li]
 in refs of [Cabré-Ozzi-Qafsa])

$$\Rightarrow \frac{d}{dt} |\vec{T}_t|^{\frac{2}{n}} \leq -\tilde{C}(n) = C \rightarrow$$

↑ Use MS in $M = \vec{T}_t$ compact hypers. with $u=1$ & $p=2$



$$|\Gamma_t|^{2n} - |\Gamma_0|^{2n} \leq -ct \quad \left. \begin{array}{l} \text{thus, } T^* \leq c|\Gamma_0|^{2n}. \quad \square \\ \text{as } t \uparrow T^* = \text{extinct. time.} \end{array} \right\}$$

[Cabré-Cozzi-Csato, A fract. MS..., AFHP 2022]
 shows the analogue estimate:

Propn 14 $T^* \leq c(n, \alpha) |\Gamma_0|^{\frac{1+\alpha}{n}}$ for fractional MCF ($\alpha \in (0, 1)$)

| if Ω_0 is a C^2 bold open convex set & $T_0 = 2\Omega_0$.

↑ It was known that convexity
 is preserved under the
 fract. MCF.

The proof, as before,
 relies in a non fractional MS Sobolev ineq. in
convex sets of \mathbb{R}^{n+1} . The only other fract. MS ineq.
 known is the one on non-l. min. surf of [C-Cozzi].

Open pb : Frac MS in general hypersurfaces.

Thm 15 [Cozzi-Csato] $n \geq 1, \alpha \in (0, 1), s \in (0, 1), p \geq 1$ st $[sp < n]$.

$\Sigma \subset \mathbb{R}^{n+1}$ open convex set (perhaps unbold). Then, $M = 2\Sigma$

$$\|u\|_{L_s^p(M)} \leq c(n, \alpha, s, p) \left\{ \int_M dV(x) \int_M dV(y) \frac{|u(x) - u(y)|^p}{|x-y|^{n+sp}} + \right.$$

$$\left. \lambda \in W_s^p(M), (p_s^* = np/(n-sp)) \right\} + \int_M H_\alpha(x)^{sp/\alpha} |u(x)|^p dV(x) \quad \left. \begin{array}{l} \frac{1}{p} \\ \dots \\ \dots \\ \text{end} \end{array} \right\}$$